

IBM Storwize V7000 Unified

Problem Determination Guide



Note

Before using this information and the product it supports, read the general information in “Notices” on page 297, the information in the “Safety and environmental notices” on page iii, as well as the information in the *IBM Environmental Notices and User Guide* , which is provided on a DVD.

This edition applies to IBM Storwize V7000 Unified and to all subsequent releases and modifications until otherwise indicated in new editions.

This edition replaces GA32-1057-09.

© **Copyright IBM Corporation 2011, 2013.**

US Government Users Restricted Rights – Use, duplication or disclosure restricted by GSA ADP Schedule Contract with IBM Corp.

Safety and environmental notices

Review the safety notices, environmental notices, and electronic emission notices for IBM® Storwize® V7000 Unified before you install and use the product.

Suitability for telecommunication environment: This product is not intended to connect directly or indirectly by any means whatsoever to interfaces of public telecommunications networks. See Homologation statement for more information.

Here are examples of a caution and a danger notice:

CAUTION:

A caution notice indicates the presence of a hazard that has the potential of causing moderate or minor personal injury. (C001)

DANGER

| |
|---|
| <p>A danger notice indicates the presence of a hazard that has the potential of causing death or serious personal injury. (D002)</p> |
|---|

To find the translated text for a caution or danger notice:

1. Look for the identification number at the end of each caution notice or each danger notice. In the preceding examples, the numbers (C001) and (D002) are the identification numbers.
2. Locate *IBM Systems Safety Notices* with the user publications that were provided with the Storwize V7000 Unified hardware.
3. Find the matching identification number in the *IBM Systems Safety Notices*. Then review the topics concerning the safety notices to ensure that you are in compliance.
4. Optionally, read the multilingual safety instructions on the Storwize V7000 Unified website. Go to www.ibm.com/storage/support/storwize/v7000/unified and click the documentation link.

Safety notices and labels

Review the safety notices and safety information labels before using this product.

To view a PDF file, you need Adobe Acrobat Reader. You can download it at no charge from the Adobe website:

www.adobe.com/support/downloads/main.html

IBM Systems Safety Notices

This publication contains the safety notices for the IBM Systems products in English and other languages. Anyone who plans, installs, operates, or services the system must be familiar with and understand the safety notices. Read the related safety notices before you begin work.

Note: The IBM Systems Safety Notices document is organized into two sections. The danger and caution notices without labels are organized alphabetically by

language in the “Danger and caution notices by language” section. The danger and caution notices that are accompanied with a label are organized by label reference number in the “Labels” section.

The following notices and statements are used in IBM documents. They are listed in order of decreasing severity of potential hazards.

Danger notice definition

A special note that emphasize a situation that is potentially lethal or extremely hazardous to people.

Caution notice definition

A special note that emphasize a situation that is potentially hazardous to people because of some existing condition, or to a potentially dangerous situation that might develop because of some unsafe practice.

Note: In addition to these notices, labels might be attached to the product to warn of potential hazards.

Finding translated notices

Each safety notice contains an identification number. You can use this identification number to check the safety notice in each language.

To find the translated text for a caution or danger notice:

1. In the product documentation, look for the identification number at the end of each caution notice or each danger notice. In the following examples, the numbers (D002) and (C001) are the identification numbers.

DANGER

A danger notice indicates the presence of a hazard that has the potential of causing death or serious personal injury. (D002)

CAUTION:

A caution notice indicates the presence of a hazard that has the potential of causing moderate or minor personal injury. (C001)

2. Open the IBM Systems Safety Notices.
3. Under the language, find the matching identification number. Review the topics about the safety notices to ensure that you are in compliance.

Note: This product was designed, tested, and manufactured to comply with IEC 60950-1, and where required, to relevant national standards that are based on IEC 60950-1.

Caution notices for the Storwize V7000 Unified

Ensure that you understand the caution notices for Storwize V7000 Unified.

Use the reference numbers in parentheses at the end of each notice, such as (C003) for example, to find the matching translated notice in *IBM Systems Safety Notices*.

CAUTION:

The battery contains lithium. To avoid possible explosion, do not burn or charge the battery.

Do not: Throw or immerse into water, heat to more than 100°C (212°F), repair or disassemble. (C003)

CAUTION:

Electrical current from power, telephone, and communication cables can be hazardous. To avoid personal injury or equipment damage, disconnect the attached power cords, telecommunication systems, networks, and modems before you open the machine covers, unless instructed otherwise in the installation and configuration procedures. (26)

CAUTION:

Use safe practices when lifting.

| | | |
|---|---|--|
|  |  |  |
| 18-32 kg (39.7-70.5 lbs) | 32-55 kg (70.5-121.2 lbs) | ≥ 55 kg (≥121.2 lbs) |

svc00146

(27)

CAUTION:

- Do not install a unit in a rack where the internal rack ambient temperatures will exceed the manufacturer's recommended ambient temperature for all your rack-mounted devices.
- Do not install a unit in a rack where the air flow is compromised. Ensure that air flow is not blocked or reduced on any side, front, or back of a unit used for air flow through the unit.
- Consideration should be given to the connection of the equipment to the supply circuit so that overloading of the circuits does not compromise the supply wiring or overcurrent protection. To provide the correct power connection to a rack, refer to the rating labels located on the equipment in the rack to determine the total power requirement of the supply circuit.
- (For sliding drawers) Do not pull out or install any drawer or feature if the rack stabilizer brackets are not attached to the rack. Do not pull out more than one drawer at a time. The rack might become unstable if you pull out more than one drawer at a time.
- (For fixed drawers) This drawer is a fixed drawer and must not be moved for servicing unless specified by the manufacturer. Attempting to move the drawer partially or completely out of the rack might cause the rack to become unstable or cause the drawer to fall out of the rack.

(R001 part 2 of 2)

CAUTION:

Removing components from the upper positions in the rack cabinet improves rack stability during a relocation. Follow these general guidelines whenever you relocate a populated rack cabinet within a room or building.

- Reduce the weight of the rack cabinet by removing equipment starting at the top of the rack cabinet. When possible, restore the rack cabinet to the configuration of the rack cabinet as you received it. If this configuration is not known, you must observe the following precautions.
 - Remove all devices in the 32U position and above.
 - Ensure that the heaviest devices are installed in the bottom of the rack cabinet.
 - Ensure that there are no empty U-levels between devices installed in the rack cabinet below the 32U level.
- If the rack cabinet you are relocating is part of a suite of rack cabinets, detach the rack cabinet from the suite.
- If the rack cabinet you are relocating was supplied with removable outriggers they must be reinstalled before the cabinet is relocated.
- Inspect the route that you plan to take to eliminate potential hazards.
- Verify that the route that you choose can support the weight of the loaded rack cabinet. Refer to the documentation that comes with your rack cabinet for the weight of a loaded rack cabinet.
- Verify that all door openings are at least 760 x 230 mm (30 x 80 in.).
- Ensure that all devices, shelves, drawers, doors, and cables are secure.
- Ensure that the four leveling pads are raised to their highest position.
- Ensure that there is no stabilizer bracket installed on the rack cabinet during movement.
- Do not use a ramp inclined at more than 10 degrees.
- When the rack cabinet is in the new location, complete the following steps:
 - Lower the four leveling pads.
 - Install stabilizer brackets on the rack cabinet.
 - If you removed any devices from the rack cabinet, repopulate the rack cabinet from the lowest position to the highest position.
- If a long-distance relocation is required, restore the rack cabinet to the configuration of the rack cabinet as you received it. Pack the rack cabinet in the original packaging material, or equivalent. Also lower the leveling pads to raise the casters off the pallet and bolt the rack cabinet to the pallet.

(R002)

CAUTION:

- Rack is not intended to serve as an enclosure and does not provide any degrees of protection required of enclosures.
- It is intended that equipment installed within this rack will have its own enclosure. (R005).

CAUTION:

Tighten the stabilizer brackets until they are flush against the rack. (R006)

CAUTION:

Use safe practices when lifting. (R007)

CAUTION:

Do not place any object on top of a rack-mounted device unless that rack-mounted device is intended for use as a shelf. (R008)

CAUTION:

If the rack is designed to be coupled to another rack only the same model rack should be coupled together with another same model rack. (R009)

Danger notices for Storwize V7000 Unified

Ensure that you are familiar with the danger notices for Storwize V7000 Unified.

Use the reference numbers in parentheses at the end of each notice, such as (C003) for example, to find the matching translated notice in *IBM Systems Safety Notices*.

DANGER

When working on or around the system, observe the following precautions:

Electrical voltage and current from power, telephone, and communication cables are hazardous. To avoid a shock hazard:

- If IBM supplied a power cord(s), connect power to this unit only with the IBM provided power cord. Do not use the IBM provided power cord for any other product.
- Do not open or service any power supply assembly.
- Do not connect or disconnect any cables or perform installation, maintenance, or reconfiguration of this product during an electrical storm.
- The product might be equipped with multiple power cords. To remove all hazardous voltages, disconnect all power cords.
- Connect all power cords to a properly wired and grounded electrical outlet. Ensure that the outlet supplies proper voltage and phase rotation according to the system rating plate.
- Connect any equipment that will be attached to this product to properly wired outlets.
- When possible, use one hand only to connect or disconnect signal cables.
- Never turn on any equipment when there is evidence of fire, water, or structural damage.
- Disconnect the attached power cords, telecommunications systems, networks, and modems before you open the device covers, unless instructed otherwise in the installation and configuration procedures.
- Connect and disconnect cables as described in the following procedures when installing, moving, or opening covers on this product or attached devices.

To disconnect:

1. Turn off everything (unless instructed otherwise).
2. Remove the power cords from the outlets.
3. Remove the signal cables from the connectors.
4. Remove all cables from the devices.

To connect:

1. Turn off everything (unless instructed otherwise).
 2. Attach all cables to the devices.
 3. Attach the signal cables to the connectors.
 4. Attach the power cords to the outlets.
 5. Turn on the devices.
- Sharp edges, corners and joints may be present in and around the system. Use care when handling equipment to avoid cuts, scrapes and pinching. (D005)

DANGER

Heavy equipment—personal injury or equipment damage might result if mishandled. (D006)

DANGER

Observe the following precautions when working on or around your IT rack system:

- Heavy equipment—personal injury or equipment damage might result if mishandled.
- Always lower the leveling pads on the rack cabinet.
- Always install stabilizer brackets on the rack cabinet.
- To avoid hazardous conditions due to uneven mechanical loading, always install the heaviest devices in the bottom of the rack cabinet. Always install servers and optional devices starting from the bottom of the rack cabinet.
- Rack-mounted devices are not to be used as shelves or work spaces. Do not place objects on top of rack-mounted devices.



- Each rack cabinet might have more than one power cord. Be sure to disconnect all power cords in the rack cabinet when directed to disconnect power during servicing.
- Connect all devices installed in a rack cabinet to power devices installed in the same rack cabinet. Do not plug a power cord from a device installed in one rack cabinet into a power device installed in a different rack cabinet.
- An electrical outlet that is not correctly wired could place hazardous voltage on the metal parts of the system or the devices that attach to the system. It is the responsibility of the customer to ensure that the outlet is correctly wired and grounded to prevent an electrical shock.

(R001 part 1 of 2)

DANGER

Racks with a total weight of > 227 kg (500 lb.), Use Only Professional Movers!
(R003)

DANGER

Do not transport the rack via fork truck unless it is properly packaged,
secured on top of the supplied pallet. (R004)

DANGER



Main Protective Earth (Ground):

This symbol is marked on the frame of the rack.

The PROTECTIVE EARTHING CONDUCTORS should be terminated at that point. A recognized or certified closed loop connector (ring terminal) should be used and secured to the frame with a lock washer using a bolt or stud. The connector should be properly sized to be suitable for the bolt or stud, the locking washer, the rating for the conducting wire used, and the considered rating of the breaker. The intent is to ensure the frame is electrically bonded to the PROTECTIVE EARTHING CONDUCTORS. The hole that the bolt or stud goes into where the terminal conductor and the lock washer contact should be free of any non-conductive material to allow for metal to metal contact. All PROTECTIVE EARTHING CONDUCTORS should terminate at this main protective earthing terminal or at points marked with \perp . (R010)

Special caution and safety notices

This information describes special safety notices that apply to the Storwize V7000 Unified. These notices are in addition to the standard safety notices supplied and address specific issues relevant to the equipment provided.

General safety

When you service the Storwize V7000 Unified, follow general safety guidelines.

Use the following general rules to ensure safety to yourself and others:

- Observe good housekeeping in the area where the devices are kept during and after maintenance.
- Follow the guidelines when lifting any heavy object:
 1. Ensure that you can stand safely without slipping.
 2. Distribute the weight of the object equally between your feet.
 3. Use a slow lifting force. Never move suddenly or twist when you attempt to lift.
 4. Lift by standing or by pushing up with your leg muscles; this action removes the strain from the muscles in your back. *Do not attempt to lift any objects that weigh more than 18 kg (40 lb) or objects that you think are too heavy for you.*
- Do not perform any action that causes a hazard or that makes the equipment unsafe.
- Before you start the device, ensure that other personnel are not in a hazardous position.
- Place removed covers and other parts in a safe place, away from all personnel, while you are servicing the unit.
- Keep your tool case away from walk areas so that other people will not trip over it.

- Do not wear loose clothing that can be trapped in the moving parts of a device. Ensure that your sleeves are fastened or rolled up above your elbows. If your hair is long, fasten it.
- Insert the ends of your necktie or scarf inside clothing or fasten it with a nonconducting clip, approximately 8 cm (3 in.) from the end.
- Do not wear jewelry, chains, metal-frame eyeglasses, or metal fasteners for your clothing.

Remember: Metal objects are good electrical conductors.

- Wear safety glasses when you are: hammering, drilling, soldering, cutting wire, attaching springs, using solvents, or working in any other conditions that might be hazardous to your eyes.
- After service, reinstall all safety shields, guards, labels, and ground wires. Replace any safety device that is worn or defective.
- Reinstall all covers correctly after you have finished servicing the unit.

Handling static-sensitive devices

Ensure that you understand how to handle devices that are sensitive to static electricity.

Attention: Static electricity can damage electronic devices and your system. To avoid damage, keep static-sensitive devices in their static-protective bags until you are ready to install them.

To reduce the possibility of electrostatic discharge, observe the following precautions:

- Limit your movement. Movement can cause static electricity to build up around you.
- Handle the device carefully, holding it by its edges or frame.
- Do not touch solder joints, pins, or exposed printed circuitry.
- Do not leave the device where others can handle and possibly damage the device.
- While the device is still in its antistatic bag, touch it to an unpainted metal part of the system unit for at least two seconds. (This action removes static electricity from the package and from your body.)
- Remove the device from its package and install it directly into your Storwize V7000 Unified, without putting it down. If it is necessary to put the device down, place it onto its static-protective bag. (If your device is an adapter, place it component-side up.) Do not place the device onto the cover of the Storwize V7000 Unified or onto a metal table.
- Take additional care when you handle devices during cold weather because heating reduces indoor humidity and increases static electricity.

Sound pressure

Attention: Depending on local conditions, the sound pressure can exceed 85 dB(A) during service operations. In such cases, wear appropriate hearing protection.

Environmental notices

This publication contains all the required environmental notices for IBM Systems products in English and other languages.

The IBM Systems Environmental Notices and User Guide (ftp://public.dhe.ibm.com/systems/support/warranty/envnotices/environmental_notices_and_user_guide.pdf), Z125-5823 document includes statements on limitations, product information, product recycling and disposal, battery information, flat panel display, refrigeration, and water-cooling systems, external power supplies, and safety data sheets.

To view a PDF file, you need Adobe Reader. You can download it at no charge from the Adobe web site (get.adobe.com/reader/).

About this guide

This publication provides information that helps you install and initialize IBM Storwize V7000 Unified.

Who should use this guide

This guide is intended for installers of Storwize V7000 Unified.

Before configuring your system, ensure that you follow the procedures as listed. Be sure to gather IP addresses that you will need before you begin the installation.

Storwize V7000 Unified library and related publications

Product manuals, other publications, and websites contain information that relates to Storwize V7000 Unified.

Storwize V7000 Unified Information Center

The IBM Storwize V7000 Unified Information Center contains all of the information that is required to install, configure, and manage the Storwize V7000 Unified. The information center is updated between Storwize V7000 Unified product releases to provide the most current documentation. The information center is available at the following website:

publib.boulder.ibm.com/infocenter/storwize/unified_ic/index.jsp

Storwize V7000 Unified library

Unless otherwise noted, the publications in the Storwize V7000 Unified library are available in Adobe portable document format (PDF) from the following website:

www.ibm.com/e-business/linkweb/publications/servlet/pbi.wss

The following table lists websites where you can find help, services, and more information:

Table 1. IBM websites for help, services, and information

| Website | Address |
|---|--|
| IBM home page | http://www.ibm.com |
| Directory of worldwide contacts | http://www.ibm.com/planetwide |
| Support for Storwize V7000 (2076) | www.ibm.com/storage/support/storwize/v7000 |
| Support for Storwize V7000 Unified (2073) | www.ibm.com/storage/support/storwize/v7000/unified |
| Support for IBM System Storage® and IBM TotalStorage products | www.ibm.com/storage/support/ |

Each of the PDF publications in the Table 2 is also available in the information center by clicking the number in the “Order number” column:

Table 2. Storwize V7000 Unified library

| Title | Description | Order number |
|--|--|---------------------|
| IBM Storwize V7000 Model 2073-720 Quick Start Guide | This guide provides general instructions for installing your system, and is intended for experienced developers. | GI13-2867 |
| <i>Storwize V7000 Unified Quick Installation Guide</i> | This guide provides instructions for unpacking your shipping order and installing your system. The first of three chapters describes verifying your order, becoming familiar with the hardware components, and meeting environmental requirements. The second chapter describes installing the hardware and attaching data cables and power cords. The last chapter describes accessing the management GUI to initially configure your system. | GA32-1056 |
| <i>IBM Storwize V7000 Expansion Enclosure Installation Guide, Machine type 2076</i> | This guide provides instructions for unpacking your shipping order and installing the 2076 expansion enclosure for the Storwize V7000 Unified system. | GC27-4234 |
| <i>Adding Storwize V7000 Unified File modules to an Existing Storwize V7000 System</i> | This guide is intended for users adding Storwize V7000 file modules to an existing Storwize V7000 system to create a Storwize V7000 Unified system. | SC27-4223 |
| <i>Storwize V7000 Unified Problem Determination Guide</i> | This guide describes how to service, maintain, and troubleshoot the Storwize V7000 Unified system. | GA32-1057 |
| <i>IBM Storwize V7000 Unified Safety Notices</i> | This guide contains translated caution and danger statements for the node canister documentation. Each caution and danger statement in the Storwize V7000 Unified documentation has a number that you can use to locate the corresponding statement in your language in the <i>IBM Storwize V7000 Unified Safety Notices</i> document. | SC27-5947 |

Table 2. Storwize V7000 Unified library (continued)

| Title | Description | Order number |
|--|---|---------------------------------|
| <i>Safety Information</i> | This guide contains translated caution and danger statements for the file module documentation. Each caution and danger statement in the Storwize V7000 Unified documentation has a number that you can use to locate the corresponding statement in your language in the <i>Safety Information</i> document. | Part number: 00D2303 |
| <i>Storwize V7000 Unified Read First Flyer</i> | This document introduces the major components of the Storwize V7000 Unified system and describes how to get started with the <i>Storwize V7000 Unified Quick Installation Guide</i> . | GA32-1055 |
| <i>Read First before adding file modules to an existing Storwize V7000 Unified</i> | This document introduces the major components of the Storwize V7000 Unified system and describes how to get started with <i>Adding Storwize V7000 Unified File modules to an Existing Storwize V7000 System</i> . | SC27-5415 |
| <i>IBM Statement of Limited Warranty (2145 and 2076)</i> | This multilingual document provides information about the IBM warranty for machine types 2145 and 2076. | Part number: 4377322 |
| <i>IBM Statement of Limited Warranty (2073)</i> | This multilingual document provides information about the IBM warranty for machine type 2073. | Part number: 00L4547 |
| <i>IBM License Agreement for Machine Code</i> | This multilingual guide contains the License Agreement for Machine Code for the Storwize V7000 Unified product. | SC28-6872 (contains Z125-5468) |
| <i>Getting Started with Real-time Compression on IBM Storwize(r) V7000 Unified 1.4.0.1</i> | This document provides technical information and guidelines on what should be considered when deploying compression in the Storwize V7000 Unified storage environment. | Version 1.03 (January 27, 2012) |

IBM documentation and related websites

Table 3 on page xvi lists websites that provide publications and other information about the Storwize V7000 Unified or related products or technologies.

Table 3. IBM documentation and related websites

| Website | Address |
|--|--|
| <i>IBM Storage Management Pack for Microsoft System Center Operations Manager (SCOM)</i> | The IBM Storage Host Software Solutions Information Center describes how to install, configure, and use the IBM Storage Management Pack for Microsoft System Center Operations Manager. |
| <i>IBM Storage Management Console for VMware vCenter</i> | The IBM Storage Host Software Solutions Information Center describes how to install, configure, and use the IBM Storage Management Console for VMware vCenter, which enables Storwize V7000 Unified and other IBM storage systems to be integrated in VMware vCenter environments. |
| IBM Publications Center | www.ibm.com/e-business/linkweb/publications/servlet/pbi.wss |
| IBM Redbooks® publications | www.redbooks.ibm.com/ |

Related accessibility information

To view a PDF file, you need Adobe Reader, which can be downloaded from the Adobe website:

www.adobe.com/support/downloads/main.html

How to order IBM publications

The IBM Publications Center is a worldwide central repository for IBM product publications and marketing material.

The IBM Publications Center offers customized search functions to help you find the publications that you need. Some publications are available for you to view or download at no charge. You can also order publications. The publications center displays prices in your local currency. You can access the IBM Publications Center through the following website:

www.ibm.com/e-business/linkweb/publications/servlet/pbi.wss

Related websites

The following websites provide information about Storwize V7000 Unified or related products or technologies:

| Type of information | Website |
|--|--|
| Storwize V7000 Unified support | www.ibm.com/storage/support/storwize/v7000/unified |
| Technical support for IBM storage products | www.ibm.com/storage/support/ |
| IBM Electronic Support registration | www.ibm.com/support/electronicssupport |

Sending your comments

Your feedback is important in helping to provide the most accurate and highest quality information.

To submit any comments about this book or any other Storwize V7000 Unified documentation:

- Go to the feedback form on the website for the Storwize V7000 Unified Information Center at publib.boulder.ibm.com/infocenter/storwize/unified_ic/index.jsp?topic=/com.ibm.storwize.v7000.unified.doc/feedback_ifs.htm. You can use the form to enter and submit comments. You can browse to the topic in question and use the feedback link at the very bottom of the page to automatically identify the topic for which you have a comment.
- Send your comments by email to starpubs@us.ibm.com. Include the following information in your email:
 - Publication title
 - Publication form number
 - Page, table, or illustration numbers that you are commenting on
 - A detailed description of any information that should be changed

How to get information, help, and technical assistance

If you need help, service, technical assistance, or just want more information about IBM products, you will find a wide variety of sources available from IBM to assist you.

Information

IBM maintains pages on the web where you can get information about IBM products and fee services, product implementation and usage assistance, break and fix service support, and the latest technical information. For more information, refer to Table 4.

Table 4. IBM websites for help, services, and information

| Website | Address |
|--|--|
| IBM home page | http://www.ibm.com |
| Directory of worldwide contacts | http://www.ibm.com/planetwide |
| Support for Storwize V7000 (2076) | www.ibm.com/storage/support/storwize/v7000 |
| Support for Storwize V7000 Unified (2073) | www.ibm.com/storage/support/storwize/v7000/unified |
| Support for IBM System Storage and IBM TotalStorage products | www.ibm.com/storage/support/ |

Note: Available services, telephone numbers, and web links are subject to change without notice.

Help and service

Before calling for support, be sure to have your IBM Customer Number available. If you are in the US or Canada, you can call 1 (800) IBM SERV for help and service. From other parts of the world, see <http://www.ibm.com/planetwide> for the number that you can call.

When calling from the US or Canada, choose the **storage** option. The agent decides where to route your call, to either storage software or storage hardware, depending on the nature of your problem.

If you call from somewhere other than the US or Canada, you must choose the **software** or **hardware** option when calling for assistance. Choose the **software** option if you are uncertain if the problem involves the Storwize V7000 Unified software or hardware. Choose the **hardware** option only if you are certain the problem solely involves the Storwize V7000 Unified hardware. When calling IBM for service regarding the product, follow these guidelines for the **software** and **hardware** options:

Software option

Identify the Storwize V7000 Unified product as your product and supply your customer number as proof of purchase. The customer number is a 7-digit number (0000000 to 9999999) assigned by IBM when the product is purchased. Your customer number should be located on the customer information worksheet or on the invoice from your storage purchase. If asked for an operating system, use **Storage**.

Hardware option

Provide the serial number and appropriate 4-digit machine type. For the Storwize V7000 Unified, the machine type is 2073.

In the US and Canada, hardware service and support can be extended to 24x7 on the same day. The base warranty is 9x5 on the next business day.

Getting help online

You can find information about products, solutions, partners, and support on the IBM website.

To find up-to-date information about products, services, and partners, visit the IBM website at www.ibm.com/storage/support/storwize/v7000/unified.

Before you call

Make sure that you have taken steps to try to solve the problem yourself before you call.

Some suggestions for resolving the problem before calling IBM Support include:

- Check all cables to make sure that they are connected.
- Check all power switches to make sure that the system and optional devices are turned on.
- Use the troubleshooting information in your system documentation. The troubleshooting section of the information center contains procedures to help you diagnose problems.
- Go to the IBM Support website at www.ibm.com/storage/support/storwize/v7000/unified to check for technical information, hints, tips, and new device drivers or to submit a request for information.

Using the documentation

Information about your IBM storage system is available in the documentation that comes with the product.

That documentation includes printed documents, online documents, readme files, and help files in addition to the information center. See the troubleshooting information for diagnostic instructions. The troubleshooting procedure might require you to download updated device drivers or software. IBM maintains pages on the web where you can get the latest technical information and download device drivers and updates. To access these pages, go to www.ibm.com/storage/support/storwize/v7000/unified and follow the instructions. Also, some documents are available through the IBM Publications Center.

Sign up for the Support Line Offering

If you have questions about how to use and configure the machine, sign up for the IBM Support Line offering to get a professional answer.

The maintenance supplied with the system provides support when there is a problem with a hardware component or a fault in the system machine code. At times, you might need expert advice about using a function provided by the system or about how to configure the system. Purchasing the IBM Support Line offering gives you access to this professional advice while deploying your system, and in the future.

Contact your local IBM sales representative or the IBM Support Center for availability and purchase information.

What's new

This book describes troubleshooting a Storwize V7000 Unified system. New information was included for troubleshooting a system with a new model of the Storwize V7000 Unified File Module, the 2073-720. Other information was included in this version of the book as a result of technical changes and feedback.

GA32-1057-10

The following table describes current technical changes and enhancements to this guide:

| | |
|---------------------|----------------------|
| Changed information | • Only minor changes |
|---------------------|----------------------|

Chapter 1. Storwize V7000 Unified hardware components

A Storwize V7000 Unified system consists of one or more machine type 2076 rack-mounted enclosures and two machine type 2073 rack-mounted file modules.

There are several model types for the 2076 machine type. The main differences among the model types are the following items:

- The number of drives that an enclosure can hold. Drives are located on the front of the enclosure. An enclosure can hold up to 12 3.5-inch drives or up to 24 2.5-inch drives.
- Whether the model is a control enclosure or an expansion enclosure.
Control enclosures contain the main processing units that control the whole system. They are where external systems, such as host application servers, other storage systems, and management workstations are connected through the Ethernet ports or Fibre Channel ports. Control enclosures can also be connected to expansion enclosures through the serial-attached SCSI (SAS) ports.
Expansion enclosures contain additional storage capacity. Expansion enclosures connect either to control enclosures or to other expansion enclosures through the SAS ports.
- If the control enclosure has either 1 Gbps Ethernet capability or 10 Gbps Ethernet capability.

The machine type and model for the file module is 2073-720.

Chapter 2. Best practices for troubleshooting

Taking advantage of certain configuration options, and ensuring vital system access information has been recorded, makes the process of troubleshooting easier.

Record the access information

It is important that anyone who has responsibility for managing the system know how to connect to and log on to the system. Give attention to those times when the normal system administrators are not available because of vacation or illness.

Record the following information and ensure that authorized people know how to access the information:

- The management IP addresses. This address connects to the system using the management GUI or starts a session that runs the command-line interface (CLI) commands. Record this address and any limitations regarding where it can be accessed from within your Ethernet network.
- The service IP addresses for the file module are used to access the root console on each of the file modules when needed to perform some investigation and recovery procedures.
- The root password for the file modules. The root password might be needed to perform some recovery procedures. For security reasons, the root password must be changed from its default value of `Passw0rd` using the `chrootpwd` CLI command. If you lose the root password, see “Recovering from losing the root password” on page 261.
- The control enclosure management IP address. This address is normally not needed. You might need it to access the control enclosure management GUI or the CLI during some recovery procedures. Use this address if the file modules lose their connection to the control enclosure CLI.
- The service IP addresses for the control enclosure canister. These addresses are normally not needed. You might need a service IP address to access the service assistant during some recovery procedures. Use this address if the control enclosure CLI is not working. These addresses are not set during the installation of a Storwize V7000 Unified system, but you can set these IP addresses later by using the management GUI or the `chserviceip` CLI command.

Table 5. Access information for your system

| Item | Value | Notes |
|---|-------|-------|
| The management IP address for the management GUI and CLI | | |
| The management user ID (the default is admin) | | |
| The management user ID password (the default is admin) | | |
| The additional management user IDs and passwords that you create on your system | | |
| The network gateway IP address | | |
| File module 1 service IP address | | |

Table 5. Access information for your system (continued)

| Item | Value | Notes |
|--|-------|-------|
| File module 2 service IP address | | |
| The root password for the file modules (the default is Passw0rd) | | |
| The control enclosure superuser IP address | | |
| The control enclosure superuser password (the default is passw0rd) | | |
| Control enclosure 1 canister 1 service IP address | | |
| Control enclosure 1 canister 2 service IP address | | |
| Control enclosure 2 canister 1 service IP address | | |
| Control enclosure 2 canister 2 service IP address | | |
| Control enclosure 3 canister 1 service IP address | | |
| Control enclosure 3 canister 2 service IP address | | |
| Control enclosure 4 canister 1 service IP address | | |
| Control enclosure 4 canister 2 service IP address | | |

Follow power management procedures

Access to your volume data can be lost if you incorrectly power off all or part of a system.

Use the management GUI or the CLI commands to power off a system. Using either of these methods ensures that the system fails properly in the case of powering down individual file modules and that data that is cached in the node canister memory is correctly flushed to the RAID arrays for the disk system.

The Storwize V7000 Unified system uses a pair of file modules for redundancy. Follow the appropriate power down procedures to minimize impacts to the system operations. See “Turning off the system” in the Storwize V7000 Unified information center.

Do not power off an enclosure unless instructed to do so. If you power off an expansion enclosure, you cannot read or write to the drives in that enclosure or to any other expansion enclosure that is attached to it from the SAS ports. Powering off an expansion enclosure can prevent the control enclosure from flushing all the data that it has cached to the RAID arrays.

Set up event notifications

Configure your system to send notifications when a new event is reported.

Correct any issues reported by your system as soon as possible. To avoid monitoring for new events by constantly monitoring the management GUI, configure your system to send notifications when a new event is reported. Select the type of event that you want to be notified about. For example, restrict notifications to just events that require immediate action. Several event notification mechanisms exist:

- Email. An event notification can be sent to one or more email addresses. This mechanism notifies individuals of problems. Individuals can receive notifications wherever they have email access which includes mobile devices.
- Simple Network Management Protocol (SNMP). An SNMP trap report can be sent to a data-center management system, such as IBM Systems Director, that consolidates SNMP reports from multiple systems. Using this mechanism, you can monitor your data center from a single workstation.
- Syslog. A syslog report can be sent to a data-center management system that consolidates syslog reports from multiple systems. Using this mechanism, you can monitor your data center from a single workstation.

If your system is within warranty, or you have a hardware maintenance agreement, configure your system to send email events to IBM if an issue that requires hardware replacement is detected. This mechanism is called Call Home. When this event is received, IBM automatically opens a problem report, and if appropriate, contacts you to verify if replacement parts are required.

If you set up Call Home to IBM, ensure that the contact details that you configure are correct and kept up to date as personnel change.

Back up your data

Back up your system configuration data, volume data, and file systems.

The file modules back up their configuration after each configuration change. Download the backup files regularly to your management workstation to protect the data.

The storage system backs up your control enclosure configuration data to a file every day. This data is replicated on each control node canister in the system. Download this file regularly to your management workstation to protect the data. This file must be used if there is a serious failure that requires you to restore your system configuration. It is important to back up this file after modifying your system configuration.

Your volume data or files in the file systems are susceptible to failures in your host application or your Storwize V7000 Unified system. Follow a backup and archive policy that is appropriate to the data that you have for storing the volume data on a different system or the files on a different system.

Manage your spare and failed drives

Your RAID arrays that are created from drives consist of drives that are active members and drives that are spares.

The spare drives are used automatically if a member drive fails. If you have sufficient spare drives, you do not have to replace them immediately when they fail. However, monitoring the number, size, and technology of your spare drives,

ensures that you have sufficient drives for your requirements. Ensure that there are sufficient spare drives available so that your RAID arrays are always online.

Resolve alerts in a timely manner

Your system reports an alert when there is an issue or a potential issue that requires user attention.

The management GUI provides the capability to review these issues from the Events panel.

For file module issues, use the Storwize V7000 Unified information center to look up the events and perform the actions listed for the events.

For Storwize V7000 issues, resolve these problems through the **Recommended actions only** option from the Events panel.

Perform the recommended actions as quickly as possible after the problem is reported. Your system is designed to be resilient to most single hardware failures. However, if you operate for any period of time with a hardware failure, the possibility increases that a second hardware failure can result in some volume data that is unavailable.

If there are a number of unfixed alerts, fixing any one alert might become more difficult because of the effects of the other alerts.

Keep your software up to date

Check for new code releases and update your code on a regular basis.

This can be done using the management GUI or check the IBM support website to see if new code releases are available:

www.ibm.com/storage/support/storwize/v7000/unified

www.ibm.com/storage/support/

The release notes provide information about new function in a release plus any issues that have been resolved. Update your code regularly if the release notes indicate an issue that you might be exposed to.

Keep your records up to date

Record the location information for your enclosures and file modules.

If you have only one system, it is relatively easy to identify the enclosures that make up the system. Identification becomes more difficult when you have multiple systems in your data center and multiple systems in the same rack.

For each system, record the location of the file modules, control enclosure, and any expansion enclosures. It is useful to label the enclosures themselves with the system name and the management IP addresses.

Subscribe to support notifications

Subscribe to support notifications so that you are aware of best practices and issues that might affect your system.

Subscribe to support notifications by visiting the IBM support page on the IBM website:

www.ibm.com/storage/support/storwize/v7000/unified

www.ibm.com/storage/support/

By subscribing, you are informed of new and updated support site information, such as publications, hints and tips, technical notes, product flashes (alerts), and downloads.

Know your IBM warranty and maintenance agreement details

If you have a warranty or maintenance agreement with IBM, know the details that must be supplied when you call for support.

Have the phone number of the support center available. When you call support, provide the machine type and the serial number of the enclosure or file module that has the problem. The machine type is always 2076 for a control enclosure or 2073 for a file module. If the problem does not relate to a specific enclosure, provide the control enclosure serial number. The serial numbers are on the labels on the enclosures.

Support personnel also ask for your customer number, machine location, contact details, and the details of the problem.

Chapter 3. Getting started troubleshooting

This topic is an entry point to troubleshooting your system. The content provides help in correctly identifying which of the recovery procedures must be run to recover a Storwize V7000 Unified system from a problem.

About this task

Important: After you successfully fix a problem by using the instructions that follow, use the Health status and recovery procedure to set the health status back to green.

If you are here because you installed a new system and cannot initialize it by using the USB flash drive, go to “Installation troubleshooting” on page 10.

If one of the file modules does not boot up and join the GPFS™ cluster, look for a hardware problem by using the light-path diagnostics LEDs. See “File node hardware indicators for 2073-720” on page 38. If you suspect that the boot software is corrupted, call IBM support.

If any orange fault LEDs are illuminated on the control enclosure, front or rear, see “Resolving a problem” on page 186.

If you are having problems accessing the management GUI or the CLI, see “GUI access issues” on page 22. For information about accessing the management GUI, see “Accessing the Storwize V7000 Unified management GUI” on page 55.

If the health status indicator in the lower right corner of management GUI is not green, hover over the icon on the left side of the indicator to see the type of error that is causing the poor health status. Select an error type, and you are shown the critical errors in the event log. First try to fix the critical errors under the **Block** tab of the **Monitoring > Events** page before trying to fix the critical errors under the **File** tab of the **Monitoring > Events** page.

Log into the CLI interface and run the CLI command, **lslog**. Review the results for problems that may need to be resolved.

If users or applications are having trouble accessing data that is held on the Storwize V7000 Unified system, or if the management GUI is not accessible or is running slowly, the Storwize V7000 control enclosure might have a problem.

If you cannot ping the management IP address for the Storwize V7000 control enclosure, try to access the control enclosure service assistant. Use the service IP address of the node canisters in the control enclosure to resolve any reported node errors. See “Procedure: Fixing node errors” on page 206.

Note: Use the access information that you previously recorded for the service IP address of the node canisters in the control enclosure. See “Record the access information” on page 3. If you do not know the service IP addresses for the node canisters in the control enclosure, see “Problem: Node canister service IP address unknown” on page 192.

If all nodes show either node error 550 or node error 578, you might need to perform a system recovery. See “Recover system procedure” on page 245 for more details.

For more information about determining and solving block storage problems that relate to the control enclosure, see “Resolving a problem” on page 186.

Check the intrasystem connectivity by using the management GUI. Navigate to **Monitoring > System**. Use the interactive graphic to determine the connection state by hovering over each connection in the graphic.

If either of the Fibre Channel links from the file modules shows an error or degraded state, see “Fibre Channel connectivity between file modules and control enclosure” on page 34.

If mgmt0, the direct Ethernet link between the file modules, shows an error or degraded state, see “Ethernet connectivity between file modules” on page 27.

If one or both of the Fibre Channel links from the file module to the control enclosure show an error or a degraded state, see “Ethernet connectivity from file modules to the control enclosure” on page 30.

Check the core component health. Navigate to **Monitoring > System Details > Interface Nodes > nodename > NAS Services**. In the Status panel, check the CTDB state and the GPFS state.

If the GPFS state is Active, but the CTDB state is not Active, see “Checking CTDB health” on page 153; otherwise, see “Checking the GPFS file system mount on each file module” on page 155.

If you have lost access to the files, but there is no sign that anything is wrong with the Storwize V7000 Unified system, see “Host to file modules connectivity” on page 25.

Installation troubleshooting

This topic provides information for troubleshooting problems encountered during the installation.

Software issues are often reported through CLI commands at system configuration and through error codes. Power problems can often be solved through identifying visual symptoms.

Problems with initial setup

This topic helps you to solve initial setup problems.

About this task

If USB flash drive is missing or faulty:

- Contact the IBM Support Center.
- Install the latest InitTool.exe (or reinstall if tool is not launching). Go to <http://www-933.ibm.com/support/fixcentral/options> and select the following options to locate the tool. The options are listed under the **Select product** tab, at the bottom of the page:
 - Product Group: **Storage Systems**

- Product Family: **Disk Systems**
- Product: **IBM Storwize V7000 Unified**
- Release: **All**
- Platform: **All**

Before loading the USB flash drive verify it has a FAT32 formatted file system. Plug the USB flash drive into the laptop. Go to Start (my computer), right-click the USB drive. The general tab next to File system should say FAT32.

- If the USB flash drive is not formatted as FAT32, format it. To format, right-click it, select format, under filesystem. Select FAT32 and then click Start. Continue as prompted.

InitTool.exe is not loaded on the USB flash drive or fails to launch:

- Install the latest InitTool.exe (or reinstall if tool is not launching). Go to <http://www-933.ibm.com/support/fixcentral/options> and select the following options to locate the tool. The options are listed under the **Select product** tab, at the bottom of the page:
 - Product Group: **Storage Systems**
 - Product Family: **Disk Systems**
 - Product: **IBM Storwize V7000 Unified**
 - Release: **All**
 - Platform: **All**

Amber LED on node canister does not stop flashing during install:

Allow at least 15 minutes for the LED to stop flashing. If flashing continues beyond 15 minutes, remove the USB flash drive and insert in your laptop. Navigate to the `satask_results.html` file and scan for errors and follow the service action recommendation. Take that action and retry installation.

An error is posted in the `satask_results.html`:

Take the recommended service action given by **sainfo lsservice recommendation** in the `satask_results.html` file, reboot the node, and restart the initial setup procedure.

If `satask_results.html` contains node error code 835 or node error code 550 then this can indicate that the node canisters were not able to communicate with each other at some time during the creation of the block cluster. This can occur because the PCIe link between the node canisters is temporarily broken when the nodes are restarted, as part of the create cluster process. This can generate node error codes 835 and 550. These are transitional errors that can be ignored if the nodes are now in active state with no errors. Follow this procedure to check that the errors are gone, using the USB flash drive:

- Save a copy of `satask.txt` and `satask_results.html`.
- Make sure that there is no `satask.txt` file on the USB flash drive before you plug it into the control enclosure. Plug the USB flash drive into the control enclosure. The orange fault light should go on for a short time only (such as a slow blink for a few seconds). Wait for the orange fault light to go out then unplug the USB flash drive and plug it into another computer so that you can look at the contents of the `satask_results.html` file on the USB flash drive. The `satask_results.html` will contain the output from a number of `sainfo` commands.
- Check the following:

- The cluster_status under **sainfo lsservicenodes** should be Active.
- The node_status should be Active for both node canisters in the cluster under **sainfo lsservicenodes**. Otherwise, follow the service action under **sainfo lsservicerecommendation**.
- There should be nothing in the error_data column against each node under **sainfo lsservicenodes**. Otherwise, follow the service action under **sainfo lsservicerecommendation**.

This is an example of what the satask_results.html can contain on a healthy storage system, with which you can compare your results:

```

Service Command Results
Thu Apr 19 08:23:42 UTC 2012
satask.txt file not found.

System Status

sainfo lsservicenodes
panel_name cluster_id cluster_name node_id node_name relation node_status
error_data
01-1 00000200A4E008BA Cluster_9.71.18.184 1 node1 local Active
01-2 00000200A4E008BA Cluster_9.71.18.184 2 node2 partner Active
sainfo lsservicestatus
panel_name 01-1
cluster_id 00000200a4e008ba
cluster_name Cluster_9.71.18.184
cluster_status Active
cluster_ip_count 2
cluster_port 1
cluster_ip 9.71.18.184
cluster_gw 9.71.18.1
cluster_mask 255.255.255.0
...
...
sainfo lsservicerecommendation
service_action
No service action required, use console to manage node.

```

Blue LED on file module, where the USB flash drive was inserted, keeps flashing (does not turn solid as stated in the instructions):

- Allow 5 minutes at least, remove the USB flash drive, insert it into your laptop. Verify that the InitTool set up information is correct, navigate to the SONAS_results.txt file, and open it. Check for errors and corrective actions. Refer to *Storwize V7000 Unified Problem Determination Guide* PDF on the CD.
- If no errors are listed, reboot the server (allow server to start), reinsert the USB flash drive, and try again.

Blue LED on the other file module (without USB flash drive) keeps flashing (does not turn solid or off as listed in instructions):

Wait for the primary file module to start flashing, remove the USB flash drive, insert it into you laptop, verify the InitTool set up information is correct , navigate to the SONAS_results.txt file and open it. Check for errors and corrective actions (refer to *Storwize V7000 Unified Problem Determination Guide* PDF on the CD). If no errors are listed, reboot both file modules, allow file modules to boot completely, reinsert the USB flash drive as originally instructed and try again.

Installed with the incorrect control enclosure or file module IP addresses:

If it is determined that the addresses were entered incorrectly, they can be changed at the command line as user **admin** with the following commands:

- For control enclosure IP changes use: **svctask chsystemip**
- For file module management node changes use: **chnwmgt**

Refer to the man pages for usage.

The file module initialization may have failed because of a duplicate IP address:

The control enclosure may have been set up with an IP address which is already in use by another machine on your network but the initial setup of the file modules has failed. Refer to Checking that IP addresses are not already in use from the Information Center, under the Installing topic.

Installation error codes

The system generates an error code that provides a recommended action if the installation fails.

Guide to using the error code table

1. Always check the entire system for any illuminated error lights first and refer to the problem systems appropriate maintenance manual. If no lights are illuminated, continue to step 2.
2. Match the error code noted in the results.txt file to the installation error codes list in Table 7 on page 14. If there are multiple errors, the first error listed is the most critical and should be addressed first.
3. Refer to Table 6 to match the code (A-I) to the recommended action. Follow the suggested action, in order, completing one before trying the next.
4. If the recommended action or actions fail, call the IBM Support Center.

Table actions defined

This table serves as a legend for defining the precise action to follow. The action legend defines the action that is correlated with each action key.

Table 6. Installation error code actions

| Action key | Action to be taken |
|------------|--|
| A | Power cycle both file modules with the power button. Wait for the file modules to come up and the flashing blue light on each to come on before proceeding, then reinsert the USB flash drive into the original file module. The installation continues from the last good checkpoint. |
| B | Power down both file modules, remove power from the power source (unplug it), reapply power, power up, wait for the file modules to come up and the flashing blue light on each to come on before proceeding, then reinsert the USB flash drive into the original file module. The installation continues from the last good checkpoint. |
| C | Verify that the cabling between file modules is correct and that the connections are seated properly. Then reinsert the USB flash drive into the original file module. The installation will continue from the last good checkpoint. |
| D | Verify that all IP/gateway/subnet address information is correct (InitTool) and that there are no duplicate IP's on the network. If a change is made, reinsert the USB flash drive. The installation continues from the last good checkpoint. |
| E | Insert the USB flash drive into the other file module and try again |

Table 6. Installation error code actions (continued)

| Action key | Action to be taken |
|------------|---|
| F | <p>The NAS private key is probably OK if you were able to start the management GUI, but if the USB flash drive step of initial set-up failed, then do the following:</p> <p>Retrieve the NAS private key from the Storwize V7000 by doing the following:</p> <ul style="list-style-type: none"> • Create a text file with the following line: satask chnaskey -privkeyfile NAS.ppk • Save the file as satask.txt on the USB flash drive. Insert the USB flash drive into one of the top control enclosure USB ports and wait at least 20 seconds. Reinsert the USB flash drive into the original management node. The installation continues from the last good checkpoint. |
| G | <p>Verify that the Ethernet cabling connections are seated properly between the Storwize V7000 Unified control enclosure and the customer network, as well as the file modules cabling to the customer network. Then press the Restart button if the management GUI has already started, otherwise, reinsert the USB flash drive into the original file module. The installation will continue from last good checkpoint.</p> |
| H | <p>This could be caused by a number of things so look in sonas_results.txt for an error code that could have caused this, and follow the recommended action. If there is no other error code in sonas_results.txt that could have caused this then refer to "Ethernet connectivity from file modules to the control enclosure" on page 30 for help troubleshooting the file module to control enclosure management connection.</p> |
| I | <p>Open the Storwize V7000 management GUI in a Web browser by using the Storwize V7000 system IP address. Go to the upgrade Software panel in the Storwize V7000 management GUI. Follow the instruction in the GUI to download and run the Storwize V7000 software upgrade checker for the latest Storwize V7000 software level that is compatible with the Storwize V7000 Unified software level that the file modules are currently at. Then select the retry option in the Storwize V7000 Unified management GUI if that is working or reinsert the USB flash drive into the original file module. The installation will continue from last good checkpoint.</p> |

Installation error codes

Table 7 lists the error messages and keyed actions. To match the actions, see Table 6 on page 13.

Table 7. Error messages and actions

| Error code | Error message | Action key |
|------------|--|------------|
| 0A01 | Unable to open /tmp/setup_hosts_\$\$. | A |
| 0A02 | Unable to create default users. | A |
| 0A05 | Unable to determine management IP address. | A |
| 0A06 | Unable to determine Management Mask Address. | A |
| 0A07 | Error updating /etc/hosts. | A |
| 0A08 | Unable to update VPD field. | A |
| 0A0A | Error opening /etc/sysconfig/network. | A |
| 0A0B | Error writing /etc/sysconfig/network. | A |
| 0A0C | Error updating host name. | A |
| 0A0D | Error querying settings through ASU. | B |

Table 7. Error messages and actions (continued)

| Error code | Error message | Action key |
|------------|--|-----------------|
| 0A0E | Error setting ASU command. | B |
| 0A0F | Unable to determine adapter name from VPD. | A |
| 0A10 | Unable to open the ifcfg file. | A |
| 0A11 | Unable to write to the ifcfg file. | A |
| 0A12 | Unable to bring adapter down. | A |
| 0A13 | Unable to bring adapter up. | D then C then B |
| 0A14 | Unable to determine adapter name from VPD. | A |
| 0A15 | Unable to open the ifcfg-alias file. | A |
| 0A16 | Unable to write to the ifcfg-alias file. | A |
| 0A17 | Unable to bring adapter-alias down. | A |
| 0A18 | Unable to bring adapter-alias up. | D then C then B |
| 0A19 | Unable to retrieve adapter name. | A |
| 0A1A | Incorrect parameters. | D |
| 0A1B | Adapter value not valid. | A |
| 0A1C | Alias value not valid. | A |
| 0A1D | DHCP is not valid on this adapter. | A |
| 0A1E | DHCP is not valid on aliases. | A |
| 0A1F | Invalid IP address. | D |
| 0A20 | Invalid netmask. | D |
| 0A21 | Invalid Gateway IP Address. | D |
| 0A22 | Gateway, netmask, and IP are incompatible. | D |
| 0A23 | Gateway is not valid on this adapter. | D |
| 0A24 | Alias is null. | A |
| 0A25 | Could not drop aliases. | A |
| 0A26 | Invalid adapter for Storwize V7000. | A |
| 0A27 | Invalid alias state argument. | A |
| 0AA5 | Invalid inputs. | A |
| 0AA6 | Called with invalid host name. | A |
| 0AA7 | Error sending password. | A |
| 0AA8 | A node name was not provided. | A |
| 0AA9 | Invalid management IP address. | A |
| 0AAB | Invalid RSA IP address. | A |
| 0AAC | Invalid IP for management node. | A |
| 0AAD | The node is already a part of a cluster. | A |
| 0AAE | Error while setting storage node peer. | A |
| 0AAF | Unable to get node roles from VPD. | A |
| 0AB0 | Error opening /etc/sysconfig/rsyslog. | A |
| 0AB1 | Error writing to /etc/sysconfig/rsyslog. | A |
| 0AB2 | Error reading /etc/rsyslog.conf. | A |

Table 7. Error messages and actions (continued)

| Error code | Error message | Action key |
|------------|---|------------|
| 0AB3 | Unable to open /opt/IBM/sonas/etc/rsyslog_template_mgmt.conf. | A |
| 0AB4 | Unable to open /opt/IBM/sonas/etc/rsyslog_template_int.conf. | A |
| 0AB5 | Unable to open /opt/IBM/sonas/etc/rsyslog_template_strg.conf. | A |
| 0AB6 | Unknown node roles. | A |
| 0AB7 | Error writing /etc/rsyslog.conf. | A |
| 0ABB | Unable to gather shared SSH keys. | A |
| 0ABC | Unable to copy new private keys. | A |
| 0ABD | Unable to copy new public keys. | A |
| 0ABE | Unable to copy shared keys to the remote system. | A |
| 0ABF | Unable to copy user keys on remote system. | A |
| 0AC0 | Unable to copy host keys on remote system. | A |
| 0AC1 | Unable to open local public RSA key file. | A |
| 0AC2 | Unable to parse local host's RSA public key file. | A |
| 0AC3 | Unable to open the local host public RSA key file. | A |
| 0AC4 | Unable to send local key to the remote system. | A |
| 0AC5 | Unable to access remote system after sending local key. | A |
| 0AC6 | Unable to gather remote system's public key. | A |
| 0AC7 | Unable to gather remote system's host public key. | A |
| 0AC8 | Unable to generate public/private keys. | A |
| 0AC9 | Unable to copy user SSH keys. | A |
| 0ACA | Unable to copy host SSH keys. | A |
| 0ACB | Unable to copy shared keys to remote host. | A |
| 0ACC | Unable to update keys on remote host. | A |
| 0ACD | Unable to read in shared user key. | A |
| 0ACE | Unable to read in shared host key. | A |
| 0ACF | Unable to open authorized keys file for reading. | A |
| 0AD0 | Unable to open temp file for writing. | A |
| 0AD1 | Error moving temporary file. | A |
| 0AD2 | Error opening known hosts file. | A |
| 0AD3 | Error opening temporary file. | A |
| 0AD4 | No host name provided to exchange keys with. | A |
| 0AD5 | Host name is invalid. | A |
| 0AD6 | Invalid parameters. | D |
| 0AD7 | Unable to open vpdnew.txt file. | A |
| 0AD8 | VPD failed to update a value. | A |
| 0AD9 | Invalid option. | D |
| 0ADA | Error while parsing adapter ID. | B |

Table 7. Error messages and actions (continued)

| Error code | Error message | Action key |
|------------|--|------------|
| 0ADB | Unable to open /proc/scsi/scsi. | B |
| 0AF8 | Trying to install management stack on non-management node. | A |
| 0AF9 | Invalid site ID. Curently only 'st001' is supported on physical systems. | A |
| 0AFA | This node is already a part of a cluster. Unable to configure. | E |
| 0AFB | Unable to generate public/private keys. | A |
| 0AFC | Unable to copy user SSH keys. | A |
| 0AFD | Unable to copy host SSH keys. | A |
| 0AFE | Unable to set the system's timezone. | A |
| 0AFF | Unable to write clock file. | A |
| 0B00 | Unable to write to /etc/ntp.conf. | A |
| 0B01 | Unable to parse internal IP range. | D |
| 0B08 | Unable to open dhcpd.conf template file. | A |
| 0B09 | Unable to open dhcpd.conf for writing. | A |
| 0B0A | Unable to copy dhcpd.conf to /etc/. | A |
| 0B0B | Unable to copy tftp to /etc/xinetd.d. | A |
| 0B0E | Unable to enable the TFTP server. | A |
| 0B12 | sonas_setup_security is not present. | A |
| 0B13 | No service IP provided. | D |
| 0B14 | Unable to create RSA1 SSH keys. | A |
| 0B15 | Unable to create RSA SSH keys. | A |
| 0B16 | Unable to create DSA SSH keys. | A |
| 0B17 | Exiting on trap. | A |
| 0B18 | No controllers found in this cluster. | A |
| 0B2F | Unable to set GPFS setting. Check logs for more details. | A |
| 0B30 | Unable to query current GPFS settings from mmlscluster. | A |
| 0B31 | There was an error while attempting to enable CTDB. | A |
| 0B32 | Unable to query current GPFS settings mmlsconfig. | A |
| 0B33 | Unable to open settings file. Check logs for more details. | A |
| 0B34 | Invalid arguments passed to the script. | A |
| 0B4F | add_new called with improper parameters. | A |
| 0B50 | Invalid serial number. | B |
| 0B51 | Invalid forced ID. | A |
| 0B52 | Invalid site. | A |
| 0B53 | Node with serial was not found in available list. | B |
| 0B54 | Storage nodes must be added in pairs. Invalid peer serial. | A |

Table 7. Error messages and actions (continued)

| Error code | Error message | Action key |
|------------|---|--|
| 0B55 | Storage node peer must be a different serial. | A |
| 0B56 | Peer node is not a storage node. | A |
| 0B57 | There is already a node with ID. | A |
| 0B58 | There is a node at the peer's ID. | A |
| 0B59 | No existing cluster found. Node ID must be specified. | A |
| 0B5A | Unable to determine management IP address of this node. | A |
| 0B5B | Unknown node type. | B |
| 0B5C | IP address conflict detected with the management IP. There is a node that already has this IP address. | D |
| 0B5E | IP address conflict detected with its peer management IP. There is a node that already has this IP address. | D |
| 0B5F | Error updating node's data in newnodes.dat. | B |
| 0B60 | Error writing temporary file. | A |
| 0B62 | Node did not finish configuration before timeout. | B |
| 0B7F | All nodes must be up before adding a new node. | A |
| 0B80 | Unable to find the peer storage node. | Check Fibre Channel cabling between the file modules and the control enclosure. Verify that the control enclosure is up. Refer to "Powering the system on and off" in the <i>IBM Storwize V7000 Unified Information Center</i> . |
| 0B81 | The host name was not set properly. | A |
| 0B82 | Unable to create temp file nodes.lst. | A |
| 0B85 | Error copying cluster configuration to node. | A |
| 0B86 | Error restoring cluster configuration on node. | A |
| 0B87 | There was an error while adding nodes to the GPFS cluster. | A |
| 0B88 | There was an error while configuring GPFS licensing. | A |
| 0B89 | There was an error while configuring GPFS quorum. | A |
| 0B8C | There was an error in updating the configuration on the new node. | A |
| 0B8D | Error reading checkpoint file. | A |
| 0B8E | Error writing to checkpoint file. | A |
| 0B8F | There was an error while installing GPFS callbacks. | A |
| 0B92 | Rsync failed between management nodes. | C |
| 0B94 | There were too many potential peer storage nodes. Storage controllers may be cabled incorrectly or UUIDs might not be set properly. | A |

Table 7. Error messages and actions (continued)

| Error code | Error message | Action key |
|------------|---|---------------------------------------|
| 0B95 | Invalid parameters. | D |
| 0B96 | Failed to configure the management processes on mgmt001st001 | D then A then B |
| 0B97 | IP is invalid. | D |
| 0B98 | Netmask is invalid. | D |
| 0B99 | IP, gateway, and netmask are not a valid combination. | D |
| 0B9A | There was an internal error. | A |
| 0B9B | Invalid NAS private key file. | F |
| 0B9C | Unable to copy the NAS private key file. | F |
| 0B9D | Internal error setting permissions on NAS private key file. | A |
| 0B9E | No NAS private key file found. Verify that the Storwize V7000 configuration ran properly. | F |
| 0B9F | Unable to find local serial number in new nodes. | B |
| 0BA0 | Unable to find node at new IP address. Check the node cabling. | C |
| 0BA1 | Remote node is at a higher code level. | E |
| 0BA2 | Management IP for node not found. | D |
| 0BA3 | The disk IP was not found in VPD. | D |
| 0BA4 | Unable to attach to Storwize V7000 system. Private key files might not match. | G then F |
| 0BA5 | Unable to add Storwize V7000 system to CLI. | A |
| 0BA6 | The addstoragesystem CLI command has failed. | G then D |
| 0BAC | Unable to find remote serial number in newnodes. | C then D then B |
| 0BAD | Remote node is at a higher code level. | E |
| 0BAE | Incorrect parameters. | A |
| 0BAF | Unable retrieve the node serial number. | A |
| 0BCC | Unable to configure policy routing | D then C then B |
| 0BB0 | Unable to open pxeboot data file. | A |
| 0BB1 | Unable to update pxeboot data file for node. | A |
| 0BB2 | Unable to set file permissions. | A |
| 0BB3 | Unable to find node serial in pxeboot data file. | A |
| 0BB4 | Node had an internal error during configuration. | A |
| 0BC6 | Unable to configure system. | A |
| 0BC9 | Invalid arguments passed to the script. | A |
| 01B2 | Unable to start performance collection daemon. | Contact IBM Remote Technical Support. |
| 01B3 | Failed to copy upgrade package to Storwize V7000 system. | H then G |
| 01B4 | Failed to start upgrade on Storwize V7000 with the svctask applysoftware command. | H then G then I |
| 01B5 | Storwize V7000 multipaths are unhealthy. | H then G |

Table 7. Error messages and actions (continued)

| Error code | Error message | Action key |
|------------|---|--|
| 01B6 | Storwize V7000 volumes are unhealthy as indicated using the lsvdisk command. | Check Fibre Channel cabling to storage and verify storage is up. |
| 01B7 | Failed to query status of upgrade by using the lsoftwareupgradestatus command. | H then G |
| 01B9 | Failed to check the Storwize V7000 version | H |
| 01B8 | Failed to query status of Storwize V7000 nodes using the lnodes command. | H |
| 01BE | Unable to distribute upgrade callback | Check on health of the cluster using lshhealth Contact IBM Remote Technical Support. |
| 01BF | Upgrade callback failed | Contact your customer advocate. Upgrade callbacks are custom steps placed on a system before the start of upgrade. Contact IBM Remote Technical Support. |
| 01CF | Unable to configure node | Pull both power supply cables from subject node, wait 10 seconds, plug back in, after system comes up try again. |
| 01C4 | Unable to remove callbacks | Contact IBM Remote Technical Support. |
| 01D5 | Storwize V7000 stalled. | Contact IBM Remote Technical Support. |
| 01D6 | Storwize V7000 stalled_non_redundant | H |
| 01DA | GPFS cluster is unhealthy | Refer to “Checking the GPFS file system mount on each file module” on page 155 |
| 01DB | Failed to stop performance center | Please attempt to stop performance center using /opt/IBM/sofs/cli/cfgperfcenter --stop . If successful restart upgrade. If you are unable to stop performance center please contact IBM Remote Technical Support. |

Problems reported by the CLI commands during software configuration

Use this information when troubleshooting problems reported by the CLI commands during software configurations.

The following table contains error messages that might be displayed when running the CLI commands during software configuration.

Table 8. CLI command problems

| CLI Command | Symptom/Message | Action |
|-------------|--|---|
| mkfs | SG0002C Command exception found : Disk <arrayname> might still belong to file system <filesystemname>. | <p>This message indicates that the arrays listed in the error message appear to already be part of a file system.</p> <ol style="list-style-type: none">1. Check the list of array names that you specified in the mkfs command. If the mkfs command has been used to create multiple file systems, you might have used the same array name in more than one file system. If this is the case, correct the list of array names.2. If you are certain there is no data on the system, this problem might have been caused by an error during the manufacturing cleanup process before the machine was shipped. In this case, you can work around the problem by appending the --noverify parameter to the mkfs command. Never use the --noverify parameter on a system with customer data unless directed to do so by support personnel; improper use can cause unrecoverable data loss. |

Management GUI wizard failure

DNS errors can cause management GUI wizard to fail with no clear error messages.

About this task

The management GUI wizard process can fail if there are issues with the DNS information entered into the system. Entering the incorrect information is a common problem, particularly in step 5. This step requires that you fill in the following fields:

- Domain name
- Domain Admin user ID
- Domain Admin user password

- DNS servers

Entering the incorrect information may result in messages such as **domain name not found** or **wrong user or password**. However, a failure can also occur when connecting or verifying the DNS server, which is the last entry in this step. In this case, an error message does not appear, but the step fails or hangs.

One known cause of this type of failure occurs when the DNS server Address Resolution Protocol (ARP) table shows the IP address entered was previously configured in the ARP table. In this case the DNS server does not allow the connection. An unused IP address needs to be entered or the address from the ARP table needs to be removed before restarting the management GUI wizard. Exit out of the management GUI wizard and restart the wizard again. You have to key in all fields for each step again. Once all steps are completed the system runs the configuration and restarts.

GUI access issues

This topic provides assistance in isolating and resolving problems with the GUI.

About this task

This section covers GUI access issues that allow you to isolate and resolve GUI problems. This section extends beyond the GUI in the case where a file module is not responding and requires a management switchover to the other file module. Accessing the GUI is critical to isolating and resolving system problems.

1. **Does the GUI launch and are there problems logging into the system?**
 - **Yes:** Check that the user ID being used was set up to access the GUI. Refer to “Authentication basic concepts” in the *IBM Storwize V7000 Unified Information Center*.
 - **No:** Proceed to next question.
2. **Does the GUI launch and are there problems logging into the system?**
 - **Yes:** Verify that you are using a supported browser and the browser settings are correct. Refer to “Checking your web browser settings for the management GUI” in the *IBM Storwize V7000 Unified Information Center*.
 - **No:** Proceed to next question.

Note: If the GUI does not load complete these steps.

3. **Are you able to initiate an ssh connection to either file node and log in to either file node?**
 - **Yes:**
 - a. Run the CLI command **l snode** and determine the status of the file nodes.
 - b. If the **l snode** reports the management service is not running, refer to “Management node role failover procedures” on page 149.
 - c. If **l snode** provides the system configuration information, check the connection status under the appropriate heading. Is the status set to **OK**:

Note: The Sample Output shown has been adjusted in regards to spacing and layout to accommodate this publication. It might not match exactly what is seen on your system.

```

Sample Output:
[root@kq186wx.mgmt001st001 ~]# lsnode

Hostname      IP          Description  Role          Product      Connection  GPFS    CTDB
mgmt001st001 172.31.8.2 active      management,  1.3.0.0-51c OK          active  active  9/19/11 8:02 AM
              management
              node
              storage
mgmt002st001 172.31.8.3 passive    management,  1.3.0.0-51c OK          active  active  9/19/11 8:02 AM
              management
              node
              storage

EFSSG1000I The command completed successfully.

```

- **Yes:** Run the CLI command **lshhealth**. Reference the active management node Hostname (mgmt001st001 or mgmt002st002) obtained from the **lsnode** command. Ensure that HOST_STATE, SERVICE, and NETWORK from **lshhealth** is set to OK.

```

Sample Output:
mgmt001st001 HOST_STATE      OK      OK
              SERVICE        OK      All services are running OK
              CTDB          OK      CTDBSTATE_STATE_ACTIVE
              GPFS          OK      ACTIVE
              SCM          OK      SCM system running as expected
              NETWORK      ERROR   Network interfaces have a degraded state
              CHECKOUT     OK      Disk Subsystem have a online state
mgmt002st001 HOST_STATE      OK      OK
              SERVICE        OK      All services are running OK
              CTDB          OK      CTDBSTATE_STATE_ACTIVE
              GPFS          OK      ACTIVE
              SCM          OK      SCM system running as expected
              MGMTNODE_REPL_STATE OK      OK
              NETWORK      ERROR   Network interfaces have a degraded state
V7000        CLUSTER        ERROR   Alert found in component cluster
              ENCLOSURE     ERROR   Alert found in component enclosure
              IO_GRP        OK      The component io_grp is running OK
              MDISK        OK      The component mdisk is running OK
              NODE         OK      The component node is running OK
              PORT         ERROR   Alert found in component port

EFSSG1000I The command completed successfully.

```

- **No:** Perform network connectivity isolation procedures. Refer to “Management node role failover procedures” on page 149.
- No:** Perform network connectivity isolation procedures. Refer to “Management node role failover procedures” on page 149.

If none of the previous steps resolved the GUI connectivity issues, perform the following procedure.

Network port isolation for GUI:

If none of the previous steps have resolved the problem and the network connectivity and system reports nothing wrong, there might be an issue with the port configuration of your network that is not detected in any of the previous steps. The internal management services use both port 443 and port 1081. Port 443 is redirected to port 1081 that the management service listens.

1. Check to see if you can access the GUI on the default https port (no port included in the URL). If all is good with firewall and management IP, the GUI will listen on **https://<Management IP>/** and provide a login prompt.
2. Check network port settings and firewall settings. If the previous step fails, investigate the following issues:

- The firewall is open between the administrative browser and the Primary Node Service IP but not between the administrative browser and the management IP. The firewall settings must have rules that allow port 1081 but not 443 between the administrative browser and the management IP.
- The management IP is up but the port redirection on the switch/router is not working as expected. Check the network settings.

Health status and recovery

Use this information to review the outstanding issues that cause the **Health Status** indicator at the bottom of all management GUI panels to be red (critical errors) or yellow (warnings or degradations).

Before you begin

Use this procedure after you resolve the events from the **Monitoring > Events** page to resolve the overall system health status indicators.

About this task

Within the Storwize V7000 Unified system, the system **Health Status** is based on a set of predefined software and hardware health status sensors that are reflected in the System Details page under the **Status** section for the corresponding logical host name.

For storage problems, resolve events and health status by running the recommended repair action or actions from the **Block** tab of **Monitoring > Events**.

For file module problems, the software and hardware sensors are different. Some of the sensors are automatic and actively reflect the current status of the system; whereas, some of the sensors, such as the hardware sensors, require a reset after the service actions are completed.

Note: For the file modules, the System Details page and sensors are separate from the events. Events that are displayed in the log might be reflected within a corresponding sensor with the **System Details > Status** indicator for the failing host name. However, be aware that resolving events and resetting the corresponding sensor changes the health status of the system but does not clear the corresponding event from the event log.

This topic instructs you where to go to view the information that is displayed, how to check the status of the various sensors, and how to manually close out sensor events. By performing these tasks, you ensure that the overall **Health Status** reflects the current system health.

To resolve the overall health status indicators, perform the following steps:

Procedure

1. Log on to the management GUI.
2. Navigate to **Monitoring > System Details**.
3. From the System Details page, use the navigation tree on the left to display the hardware components of the system.

The navigation reflects the overall hardware layout of the system. The structure begins with the overall cluster host name. Under the cluster host name are the

subcomponent areas of the system in which the interface nodes reflect the file module components, and the enclosure number represents the storage system.

- a. Expand the interface nodes to display the two individual file modules that are represented by the host names `mgmt001st001` and `mgmt002st001`. Expand each of these file modules to display further details.
For any critical or warning level events, the corresponding hardware reflects the status with a small red circle or yellow triangle next to the corresponding device.
- b. Navigate to the status by expanding the `mgmt00xst001` system that shows a problem.
- c. Select **Status** to produce a list of statuses.
4. Expand any `mgmt00xst001` subcomponent that shows a critical or warning event indication and select **Status**.
 - a. Review the **Sensor** column and the **Level** column for **Critical Error**, **Major Warning**, or **Minor Warning** items.
If the problem that caused the **Level** item is resolved, right-click the event and select the **Mark Event as Resolved** action.
 - b. Follow the online instructions to complete the change.
 - c. Review the status list for the other events that might cause the **Health Status** to be red or yellow.
 - d. Perform the same steps.

As long as there is a single sensor that is marked as **Critical Error**, **Major Warning**, or **Minor Warning**, the **Health Status** is red or yellow. When you use the **Mark Event as Resolved** action against the sensor, the sensor no longer shows in the status view. If the problem is still not resolved, a new sensor update occurs that reflects the problem. An example might be if a software error event is marked as resolved but the system still detects the problem; then the status is properly reflected in the **Status** display.

Connectivity issues for the 2073-720

This topic provides information for troubleshooting connectivity issues. The major focus is on connectivity between the file modules and the control enclosure. Good connectivity is required to troubleshoot control enclosure problems.

Host to file modules connectivity

This procedure is used to troubleshoot Ethernet network connectivity between the host and the file modules. These network paths are used for all system requests and management operations. The paths are also needed for Ethernet network connectivity between the file module and the Storwize V7000.

About this task

Within the file modules, two internal 1 GB network ports and two 10 GbE network ports can be configured for system operations.

Figure 1 on page 26 identifies the various rear ports and hardware for the file module.

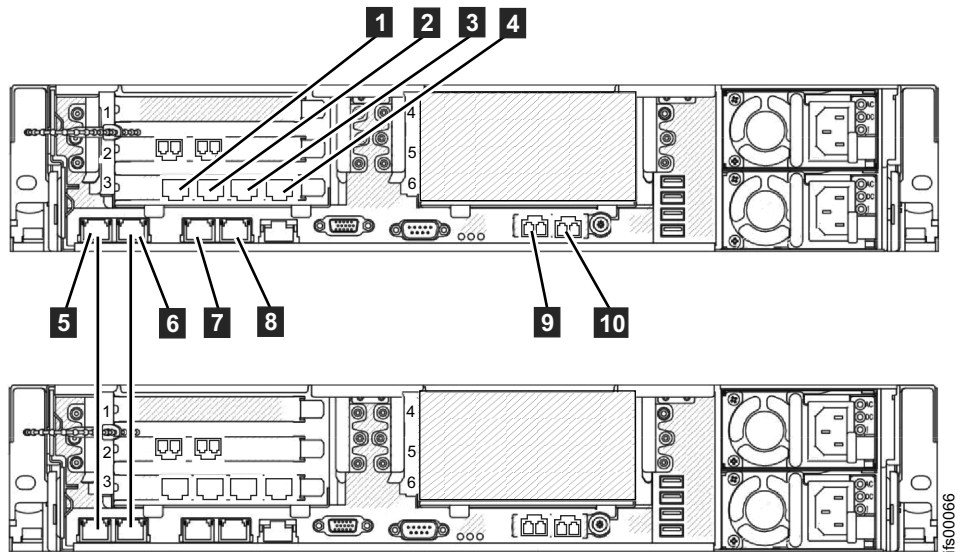


Figure 1. File module Ethernet connections.

Table 9. Ethernet connections available with the file modules

| Item | Port | IP address is assigned by InitTool | Use |
|-----------|------------------------------------|--|---|
| 1 | Ethernet port 7 | | Connect to a switch for public file access |
| 2 | Ethernet port 8 | | Connect to a switch for public file access |
| 3 | Ethernet port 9 | | Connect to a switch for public file access |
| 4 | Ethernet port 10 | | Connect to a switch for public file access |
| 5 | Ethernet port 1 | From the internal IP address range | Connect to the other file module |
| 6 | Ethernet port 2 | From the internal IP address range | Connect to the other file module |
| 7 | Ethernet port 3 | File module service and system management IP address | Connect to a switch for public file access and system management |
| 8 | Ethernet port 4 | | Connect to a switch for public file access |
| 9 | Ethernet port 5 (10 Gbps optical) | | Connect to a switch for public file access and optional system management |
| 10 | Ethernet port 6 (10 Gbps optical) | | Connect to a switch for public file access |

If you are looking at a problem regarding built-in Ethernet port 1 or built-in Ethernet port 2, refer to “Ethernet connectivity between file modules” on page 27.

Isolation procedures:

Ensure that the file module is powered up before you begin this procedure. The network connection being diagnosed must be connected to an active port on your Ethernet network.

- Determine the state of the Ethernet LEDs examining the LEDs of the Ethernet ports.
- The activity LED flashes when there is activity on the connection. The link state LED must be permanently on. If it is off, the link is not connected.

If your link is not connected, perform the following actions to check the port status each time until it is corrected or connected:

1. Verify that each end of the cable is securely connected.
2. Verify that the port on the Ethernet switch or hub is configured correctly. Contact your network administrator to verify the switch and network configuration information.
3. Connect the cable to a different port on your Ethernet network.
4. Replace the Ethernet cable.
5. For the 10 GbE Ethernet port, replace the small form-factor pluggable (SFP) transceiver. Refer to “Removing a PCI adapter from a PCI riser-card assembly” on page 109 and “Installing a PCI adapter in a PCI riser-card assembly” on page 111.

Ethernet connectivity between file modules

This topic covers troubleshooting Ethernet connectivity issues between the file modules. These connections are used for internal management operations between the file modules. They make use of the Internal IP address range that you provided during initializing the Storwize V7000 Unified system.

About this task

This procedure is used to troubleshoot Ethernet connectivity between the file modules. These network paths are used for all internal file system communication. Between the file module, there are two separate network paths for internal communication.

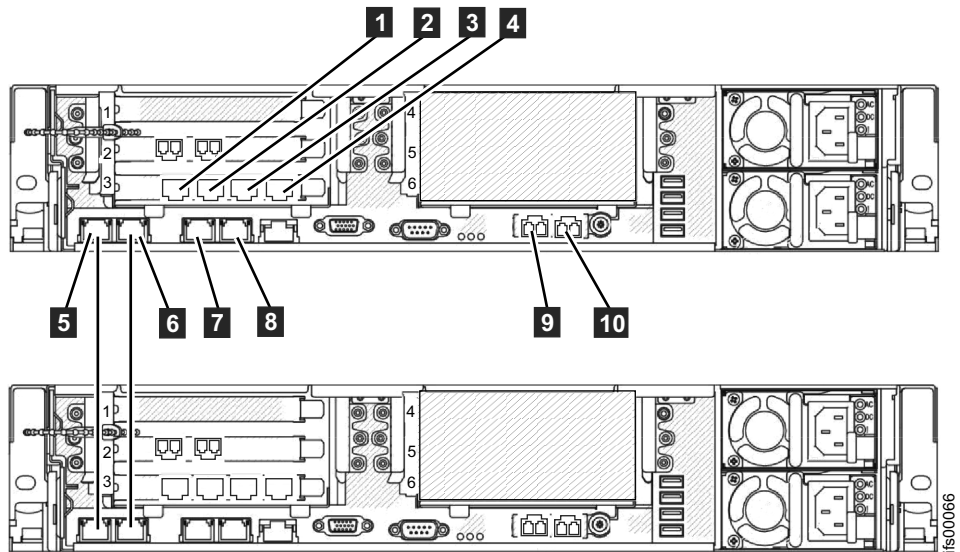


Figure 2. File module Ethernet connections.

Table 10. Ethernet connections available with the file modules

| Item | Port | IP address is assigned by InitTool | Use |
|-----------|------------------------------------|--|---|
| 1 | Ethernet port 7 | | Connect to a switch for public file access |
| 2 | Ethernet port 8 | | Connect to a switch for public file access |
| 3 | Ethernet port 9 | | Connect to a switch for public file access |
| 4 | Ethernet port 10 | | Connect to a switch for public file access |
| 5 | Ethernet port 1 | From the internal IP address range | Connect to the other file module |
| 6 | Ethernet port 2 | From the internal IP address range | Connect to the other file module |
| 7 | Ethernet port 3 | File module service and system management IP address | Connect to a switch for public file access and system management |
| 8 | Ethernet port 4 | | Connect to a switch for public file access |
| 9 | Ethernet port 5 (10 Gbps optical) | | Connect to a switch for public file access and optional system management |
| 10 | Ethernet port 6 (10 Gbps optical) | | Connect to a switch for public file access |

If you are looking at a problem regarding built-in Ethernet port 3, built-in Ethernet port 4, or any network connections to PCI slot 4, refer to “Host to file modules connectivity” on page 25.

Isolation procedures:

Ensure that both of the file module are powered up before you begin this procedure:

- Determine the state of the Ethernet LEDs by examining the Ethernet port LEDs.
- The activity LED flashes when there is activity on the connection. The link state LED must be permanently on. If it is off, the link is not connected.

If your link is not connected perform the following actions to check the port status until it is corrected or connected:

1. Verify that each end of the cable is securely connected.
2. Replace the Ethernet cable.
3. Replace the failed Ethernet port on the server by replacing the system planer. Refer to “Removing the system board” on page 142 and “Installing the system board” on page 144.

Duplicate IP address procedure:

If you are experiencing odd intermittent problems with communications between the file modules then it could be that some other machine on your network is using the same IP address as one of the four IP addresses used for the file modules to communicate with each other. These IP addresses were set during initial setup from the internal IP address range that you chose in the initialization tool.

It is always possible that somebody in your site could set up another machine to use one or more IP address that your Storwize V7000 Unified system is already using. Use the management GUI to check which four IP addresses the file modules are currently using to communicate with each other. See the device = mgmt0 box, in **Monitoring > System Details** in the **network** panel under each file module interface node name.

Follow this procedure:

1. Find the system IP address of the control enclosure in the **Settings > Network > IP Report**. Log on to the storage system CLI. For example: (default password is passw0rd):

```
ssh superuser@<system IP address>
```
2. Use ping from the storage system CLI to see if any packets are returned from each of the internal IP addresses used for file modules to communicate with each other. For example:

```
IBM_2076:mssystem:superuser>ping 10.254.8.1
PING 10.254.8.1 (10.254.8.1) 56(84) bytes of data.
--- 10.254.8.1 ping statistics ---
5 packets transmitted, 0 received, 100% packet loss, time 4005ms
```
3. You should get 100% packet loss. If you do not get 100% packet loss then some other machine on your network is using this IP address.

If you cannot stop other machines on your network using these IP addresses and must change the internal IP address range used then you need to contact IBM Remote Technical Support to help you to put your file modules back to an out-of-box state so you can choose a different internal IP address range. All other IP addresses used by the system can be changed without needing to put the file modules back to an out-of-box state.

Ethernet connectivity from file modules to the control enclosure

This topic covers troubleshooting Ethernet network connectivity issues between the file modules and the attached control enclosure. These network paths are used for all management operations between the file module and the control enclosure.

About this task

This procedure is used to troubleshoot Ethernet network connectivity between the file modules and the control enclosure. These connections are used for the active management node on one of the file modules to ssh storage command-line interface (CLI) commands to the main configuration node canister in a control enclosure.

There are no direct physical Ethernet connections between the file module hardware and the control enclosure. All network connections are done through your network infrastructure. When configuring your network switches, be sure that there is an available communication path between the file module network connections and the control enclosure network connections. Ideally the file modules and control enclosure should be connected to the same 1 Gbps Ethernet switch

If you want redundant connectivity to the control enclosure from the file modules, then both 1 Gbps ports from each node canister in the control enclosure are connected to your network. If you do not want redundancy, connecting port 2 of the control enclosure node canister to your network is optional.

If you seem to have intermittent management communication problems between the file module which is the active management node and the control enclosure CLI, then it is possible that another machine on your network could be using the IP address used by the control enclosure. Refer to “Problem: Another system may be using the system IP address” on page 187 for how to check for a duplicate IP address on your network and how to change the control enclosure IP address if necessary.

If the file modules can no longer ssh CLI commands to the storage system CLI then the first thing to do is make sure that the management IP addresses are correctly set. You may find the GUI works very slowly in this case, so access the CLI by using ssh to the log on to the management IP address as admin (default password **admin**).

For example:

```
ssh admin@<mangementIP>
```

Use the **lsnwmgt** CLI command to show you the IP addresses used by the file modules for management. For example:

```
[kd52y0g.ibm]$ lsnwmgt
Interface Service IP Node1 Service IP Node2 Management IP Network Gateway VLAN ID
ethX0 9.71.18.160 9.71.18.161 9.71.18.210 255.255.255.0 9.71.18.1
EFSSG1000I The command completed successfully.
```

Use the **lsstoragesystem** CLI command to show you the IP address that the active management node, running on one of the file modules, will use to ssh commands to the storage system CLI. For example:

```
[kd52y0g.ibm]$ lsstoragesystem
name          primaryIP    secondaryIP  id
StorwizeV7000 9.71.18.180 9.71.18.180 00000200A6002C08
EFSSG1000I The command completed successfully.
```

Check that these 5 or 6 IP addresses and sub net mask are as expected. Attempt the **lssystemip** CLI command which will probably fail when the active management node running on a file module attempts to ssh it to the storage system CLI running on a control enclosure. For example:

```
[kd52y6h.ibm]$ lssystemip
EFSSG0655C Error in communication with the storage system. Failed to open SSH connection
```

However, if this CLI command now works then the original problem with ssh to the storage system CLI may have gone away. Otherwise, use ping to check the network connections between the storage system and the file modules. It does not work from the management CLI but it should work from the storage system CLI.

From an external computer ssh as superuser to the primary IP given by the **lsstoragesystem** CLI. The IP that the active management node will be trying to ssh commands to the storage system CLI. For example (default password is passw0rd):
ssh superuser@9.71.18.180

If you can not ssh to the storage system primary IP or secondary IP (that was given by the **lsstoragesystem** CLI command) then follow the procedure to use the USB flash drive to discover the state and settings of the Storwize V7000. Make sure that there is no satask.txt file on the USB flash drive before you plug it into the control enclosure.

Plug the USB flash drive into the control enclosure. The orange fault light should go on for a short time only. (such as a slow blink for a few seconds) . Wait for the orange fault light to go out then unplug the USB flash drive and plug it into another computer so that you can look at the contents of the satask_results.html file on the USB flash drive. The satask_results.html will contain the output from a number of sainfo commands.

Check the following;

- The cluster_id under sainfo lsservicestatus should match the id (that was given by the **lsstoragesystem** CLI command). Otherwise you may have plugged the USB flash drive into the wrong control enclosure (such as one that is not part of this Storwize V7000 unified system). The node_status should be active for each node canister in the cluster under sainfo lsservicestatus. Otherwise follow the service action under sainfo lsservicerecommendation.
- The cluster_ip under sainfo lsservicestatus should match the Primary IP (that was given by the **lsstoragesystem** CLI command). Otherwise investigate which of the IP addresses is the correct one and make the other one match it. Refer to the instructions later on this page if you need to change the storage system IP address but can not log onto the storage system IP address to use the CLI.

This is an example of some of what the satask_results.html would contain on a healthy storage system for you to compare to your results:

```
Thu Apr 19 08:23:42 UTC 2012
satask.txt file not found.
System Status
sainfo lsservicenodes
panel_name cluster_id      cluster_name      node_id node_name relation node_status
error_data
01-1      00000200A4E008BA Cluster_9.71.18.184 1      node1      local      Active
```

```

01-2      00000200A4E008BA Cluster_9.71.18.184 2      node2      partner Active
sainfo lsservicestatus
panel_name 01-1
cluster_id 00000200a4e008ba
cluster_name Cluster_9.71.18.184
cluster_status Active
cluster_ip_count 2
cluster_port 1
cluster_ip 9.71.18.184
cluster_gw 9.71.18.1
cluster_mask 255.255.255.0

```

When you can ssh to the storage system IP then use the **lssystem** CLI command on the storage system CLI to show you what it thinks that its system IP address is:

```

IBM_2076:tbcluster-ifs4:superuser>lssystemip
cluster_id      cluster_name  location port_id IP_address  subnet_mask  gateway
IP_address_6 prefix_6 gateway_6
00000200A6402C08 tbcluster-ifs4 local 1      9.71.18.180 255.255.255.0 9.71.18.1
00000200A6402C08 tbcluster-ifs4 local 2

```

Check that these IP addresses and sub net mask are as expected. Use the **chsystemip** CLI if you must change anything. Use ping to check the path back to the management IP address.

```

IBM_2076:tbcluster-ifs4:superuser>ping 9.71.18.160
PING 9.71.18.160 (9.71.18.160) 56(84) bytes of data.
64 bytes from 9.71.18.160: icmp_seq=1 ttl=64 time=0.103 ms
64 bytes from 9.71.18.160: icmp_seq=2 ttl=64 time=0.096 ms
64 bytes from 9.71.18.160: icmp_seq=3 ttl=64 time=0.082 ms
64 bytes from 9.71.18.160: icmp_seq=4 ttl=64 time=0.081 ms
64 bytes from 9.71.18.160: icmp_seq=5 ttl=64 time=0.082 ms

--- 9.71.18.160 ping statistics ---
5 packets transmitted, 5 received, 0% packet loss, time 4001ms
rtt min/avg/max/mdev = 0.081/0.088/0.103/0.014 ms

```

If the ping from the storage system CLI back to the management IP has 100% packet loss then investigate the physical 1 Gbps Ethernet cabling and the configuration of the Ethernet switch. Also check the Ethernet port LEDs on:

- Built in Ethernet port 3 of each file module
- Ethernet port 1 on each node canister of the control enclosure

If the ping from the Storwize V7000 to each file module has 0% packet loss, then the ssh key should be reset. Follow the “Resetting the NAS ssh key for configuration communications” on page 263 procedure in the Infomation Center to reset the NAS key.

If you need to change the IP settings on the storage system but cannot use ssh to access the current system IP to run the **chsystemip** CLI command then refer to “Problem: Unable to change the system IP address because you cannot access the CLI” on page 188.

If you plan to change the system IP address and can ssh to the current system IP address, then you can run the **chsystemip** CLI command. Here is an example:

```

>ssh superuser@<system IP address>
$ chsystemip -clusterip 9.20.136.5 -gw 9.20.136.1 -mask 255.255.255.0 -port 1

```

The default password for superuser is **passw0rd**.

Update the file module's record of the control enclosure system IP:

To find the file module's current record of the control enclosure system IP address, use the Storwize V7000 Unified management CLI to issue the **lsstoragesystem** command. Here is an example:

```
>ssh admin@<management_IP>
[kd01ghf.ibm]$ lssstoragesystem
name          primaryIP    secondaryIP  id
StorwizeV7000 9.11.137.130 9.11.137.130 00000200A2601508
EFSSG1000I The command completed successfully.
```

If the primary and secondary IP address shown by the **lsstoragesystem** CLI do not match the system IP addresses shown in the output of the **lssystemip** CLI command, then it is necessary to update the record. The **chstoragesystem** command changes the file module record of the control enclosure system IP. Here is an example:

```
>[kd01ghf.ibm]$ chstoragesystem --ip1 9.71.18.136 --ip2 9.71.18.136
EFSSG1000I The command completed successfully.
```

Verify that communication from the file module to the control enclosure is now possible by running the **lssystemip** command on the Storwize V7000 Unified management CLI:

```
>ssh admin@<management IP address>
[kd01ghf.ibm]$ lssystemip
```

Changing the cluster IP of the file modules:

If the cluster IP address of the file modules is not known, or has been incorrectly set, the value can be changed by logging into the system using a console.

Connect a keyboard and monitor directly into the front of the file module which is the active management node. Login as a user with administrative access rights:

- Login: admin
- Password: <default is admin>

View the current cluster IP setting using the **lswmgmt** command:

```
>$ lswmgmt
[kd271f5.ibm]$ lswmgmt
Interface Service IP Node1 Service IP Node2 Management IP Network Gateway VLAN ID
ethX0 9.115.160.221 9.115.160.222 9.115.160.220 255.255.248.0 9.115.167.254
EFSSG1000I The command completed successfully
```

You may receive the following error:

```
$ lswmgmt
EFSSG0026I Cannot execute commands because Management Service is stopped. Use startmgtsrv
to restart the service.
```

This is an indication that the node you are currently connected to is not the active management node. Plug the keyboard and monitor into the other node, login again and retry the **lswmgmt** command.

To change the file module cluster IP to its new value, use the **chnwmgmt** command:

Here is an example:

```
>$ chnwmgmt -mgtp 9.115.160.210 -- netmask 255.255.255.0 -gateway 9.115.160.254
```

Checking the physical status of the Ethernet ports:

The following procedures require physical access to the system. If your link is not connected, perform the following actions to check the port status each time until it is corrected or connected.

- Examine the Ethernet ports LEDs. The activity LED flashes when there is activity on the connection. The link state LED must be permanently on. If it is off, the link is not connected.
- Verify that each end of the cables is securely connected.
- Verify that the port on the Ethernet switch or hub is configured correctly.
- Connect the cable to a different port on your Ethernet network.
- If the status is obtained using the USB flash drive, review all the node errors that are reported.
- Replace the Ethernet cable.
- Follow the hardware replacement procedures for a node canister.
- Follow the hardware replacement procedures for a file module.

If you are unable to change the service IP address, for example, because you cannot use a USB flash drive in the environment, see “Procedure: Accessing a canister using a directly attached Ethernet cable” on page 207.

Fibre Channel connectivity between file modules and control enclosure

This procedure is used to troubleshoot Fibre Channel connectivity issues between the file modules and the Storwize V7000 control enclosure. The Fibre Channel paths are the paths used for transferring data between the file module and the Storwize V7000 control enclosure.

Before you begin

Before beginning this troubleshooting procedure, review the events listed under the **Block** tab. Perform any recovery actions for events that are listed there.

About this task

Each file module has a dual port Fibre Channel adapter card located in PCI slot 2. Both ports are used to connect to the Storwize V7000 control enclosure with a connection going to each control canister.

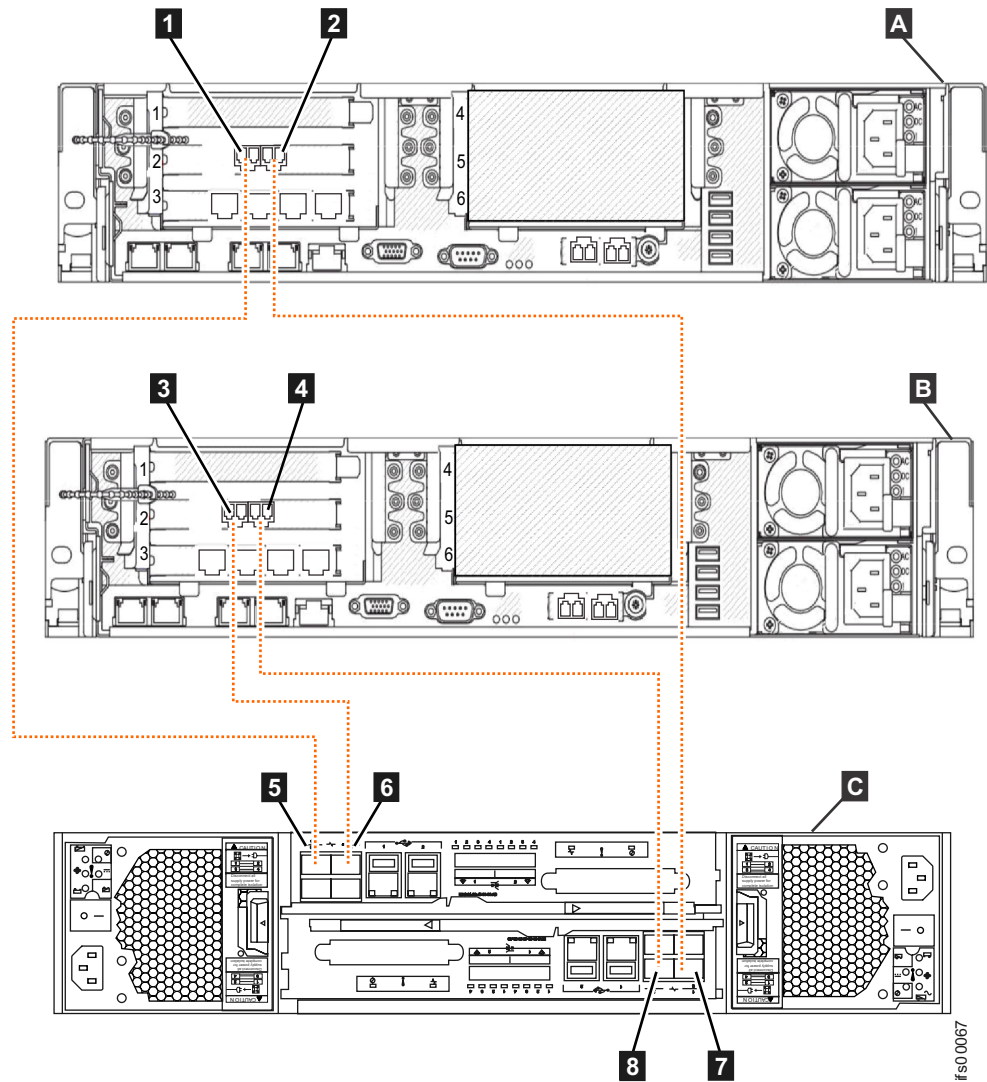


Figure 3. Connecting the file modules to the control enclosure using Fibre Channel cables.

- **A** File module 1
- **B** File module 2
- **C** Storwize V7000 control enclosure
- **1** File module 1 - Fibre Channel port 1
- **2** File module 1 - Fibre Channel port 2
- **3** File module 2 - Fibre Channel port 1
- **4** File module 2 - Fibre Channel port 2
- **5** Upper node canister - Fibre Channel port 1
- **6** Upper node canister - Fibre Channel port 2
- **7** Lower node canister - Fibre Channel port 1
- **8** Lower node canister - Fibre Channel port 2

The following table describes the diagram shown in Figure 3.

Table 11. How to connect Fibre Channel cables from file modules to the control enclosure.

| File module | Control enclosure |
|---------------------------------------|--|
| A File module 1 | C Control enclosure |
| 1 Fibre Channel slot 2, port 1 | 5 Upper canister Fibre Channel port 1 |
| 2 Fibre Channel slot 2, port 2 | 7 Lower canister Fibre Channel port 1 |
| B File module 2 | C Control enclosure |
| 3 Fibre Channel slot 2, port 1 | 6 Upper canister Fibre Channel port 2 |
| 4 Fibre Channel slot 2, port 2 | 8 Lower canister Fibre Channel port 2 |

The Storwize V7000 control enclosure contains an upper and lower (inverted) canister.

In isolating problems, be sure to review the labels on the rear of the systems for exact port plugging.

Software detected problems via event codes:

If a software event code directed you to this procedure, use the **Monitoring > System** page in the management GUI to identify the effected file module or refer to the following procedure to determine the logical to physical mapping of the event, then proceed to the physical hardware isolation procedures.

The isolation of Fibre Channel connections based on a single error event is not simple. As Figure 3 on page 35 shows, there are two file modules attached to the control enclosure; however, the logical host name of these systems does not map directly to the connections. The logical host name of the file module depends on which file module is used for initial USB flash drive installation. For example, in Figure 3 on page 35, file module **B** can have a host name of **mgmt001st001** if the installation was initiated on that node or it might have a host name of **mgmt002st001** if the installation was initiated on the second file module. Each error event is reported against the logical host name where the problem occurred.

For isolation of Fibre Channel connections, it is important with a single file module that both Fibre Channel connections go to the same port number on both the upper and lower Storwize V7000 node canisters. Port 1 always goes to the upper canister, and port 2 goes to the lower canister.

Use the following table for correlating the error code with the physical connections, then follow the procedures after the table for enabling the LED indicator on the front of the file module.

Table 12. Error code port location mapping

| Error code | Description | File Module Fibre Channel Location | Storage Node Canister Fibre Channel Port |
|------------|---|--|--|
| 4B0800C | Link failure. Fibre Channel adapter 1, port 1 not up. | PCI slot #2 – port 1 (right port when facing rear of system) | Upper node canister, port 1. OR Upper node canister, port 2. |
| 4B0801C | Link failure. Fibre Channel adapter 1, port 2 not up. | PCI slot #2 – port 2 (left port when facing rear of system) | Lower node canister, port 1. OR lower node canister, port 2. |

Table 12. Error code port location mapping (continued)

| Error code | Description | File Module Fibre Channel Location | Storage Node Canister Fibre Channel Port |
|------------|---|--|--|
| 4B0803C | Slow connection on Fibre Channel adapter 1, port 1. | PCI slot #2 – port 1 (right port when facing rear of system) | Upper node canister, port 1. OR upper node canister, port 2. |
| 4B0804C | Slow connection on Fibre Channel adapter 1, port 2. | PCI slot #2 – port 2 (left port when facing rear of system) | Lower node canister, port 1. OR lower node canister, port 2. |

To enable the LED indicator for the node reporting the problem, use the **Monitoring > System** page in the management GUI or follow this procedure:

1. Log onto the active file module via the CLI interface.
2. Run the command: **locatenode #HOSTNAME on #SECONDS**. **HOSTNAME** is the hostname associated with the error... either **mgmt001st001** or **mgmt002st001**. **#SECONDS** is the number of seconds for the LED indicator to be turned on.

Physical connection and repair:

Each file module has a dual port Fibre Channel adapter card located in PCI slot 2. Both ports are used to connect to the Storwize V7000 system with a connection going to each Storwize V7000 node canister.

Table 13. Fibre Channel cabling from the file module to the control enclosure.

| File Module Node # 1 | | File Module Storage Node # 2 | |
|---------------------------------------|---------------------------------------|---------------------------------------|---------------------------------------|
| PCI slot #2, port 1 | PCI slot #2, port 2 | PCI slot #2, port 1 | PCI slot #2, port 2 |
| Connects to Storwize V7000 | Connects to Storwize V7000 | Connects to Storwize V7000 | Connects to Storwize V7000 |
| Lower canister – Fibre Channel port 1 | Upper canister – Fibre Channel port 1 | Lower canister – Fibre Channel port 2 | Upper canister – Fibre Channel port 2 |

If a problem is detected with a Fibre Channel path between the storage node and the control enclosure, check the LED indicators next to the Fibre Channel connection ports on both the file module and the Storwize V7000 node canister.

Table 14. LED states and associated actions. For the Fibre Channel adapters on the file module check the amber LED lights next to the port.

| LED State | Definition and Action |
|-------------------------|--|
| Solid amber LED | This state indicates a good connection status. |
| Slow flashing amber LED | This state indicates a good connection at the Fibre Channel port but a broken connection at the Storwize V7000 node canister. This broken connection is most likely either a Fibre Channel cable or the Fibre Channel port is bad on the Storwize V7000 node canister. |

Table 14. LED states and associated actions. For the Fibre Channel adapters on the file module check the amber LED lights next to the port. (continued)

| LED State | Definition and Action |
|--------------------------|--|
| Rapid flashing amber LED | This state indicates the Fibre Channel adapter is attempting to resync the Fibre Channel connection. This situation is normally seen after a Fibre Channel connection is unplugged and then plugged back in. |
| No LED | There is no connection detected at all at the file module Fibre Channel port. This broken connection is most likely caused by a Fibre Channel cable or the Fibre Channel adapter has failed. |

Table 15. Fibre Channel connection on the node canister LED state and associated actions

| LED State | Definition and Action |
|-----------------|---|
| Solid green LED | This state indicates a good connection status. |
| No LED | There is no connection detected at all at the node canister Fibre Channel port. |

The recommended repair actions for Fibre Channel connections are as follows:

1. Reseat the Fibre Channel cable at both the Fibre Channel connection and the node canister.
2. Replace the Fibre Channel cable.
3. Replace the Fibre Channel adapter in the file module. Refer to “Removing a PCI adapter from a PCI riser-card assembly” on page 109 and “Installing a PCI adapter in a PCI riser-card assembly” on page 111
4. Replace the Storwize V7000 node canister. Refer to “Replacing a node canister” on page 210.

Understanding LED hardware indicators

This topic provides information for understanding the LED status of all system components. If you do not have an LED issue or direct access to the system, proceed to the next troubleshooting topic.

File node hardware indicators for 2073-720

Use this information to evaluate the system LEDs, which can often identify the source of an error.

Light path diagnostics is a system of LEDs on various external and internal components of the server. When an error occurs, LEDs are lit throughout the server. By viewing the LEDs in a particular order, you can often identify the source of the error.

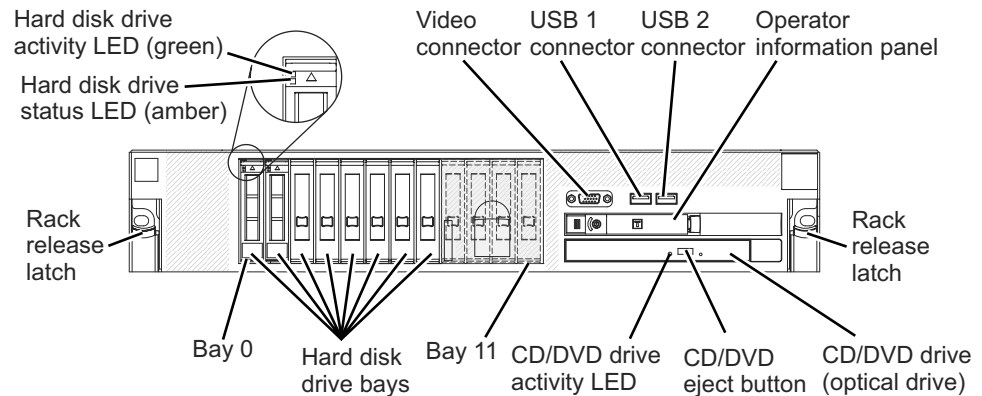
When LEDs are lit to indicate an error, they remain lit when the server is turned off, provided that the server is still connected to power and the power supply is operating correctly.

Before you work inside the server to view light path diagnostics LEDs, read the safety information.

If an error occurs, view the light path diagnostics LEDs in the following order:

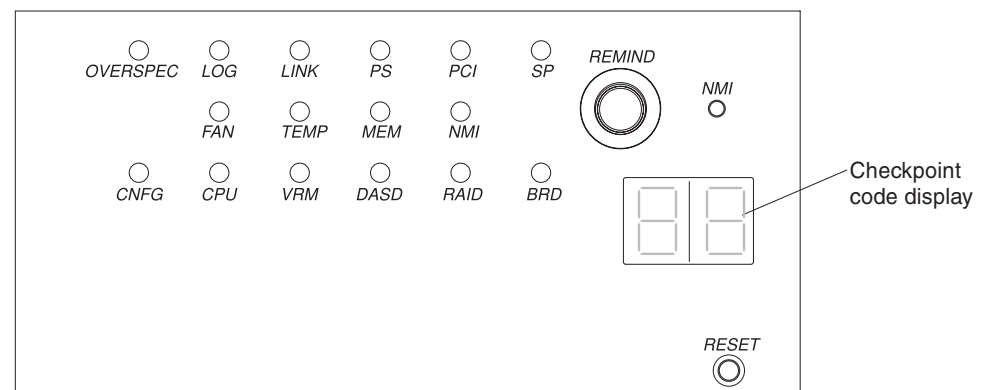
1. Look at the operator information panel on the front of the server.
 - If the information LED is lit, it indicates that information about a suboptimal condition in the server is available in the IMM event log or in the system event log.
 - If the system-error LED is lit, it indicates that an error has occurred; go to step 2.

The following illustration shows the operator information panel on the front of the file node.



2. To view the light path diagnostics panel, slide the latch to the left on the front of the operator information panel and pull the panel forward. This reveals the light path diagnostics panel. Lit LEDs on this panel indicate the type of error that has occurred.

The following illustration shows the light path diagnostics panel.



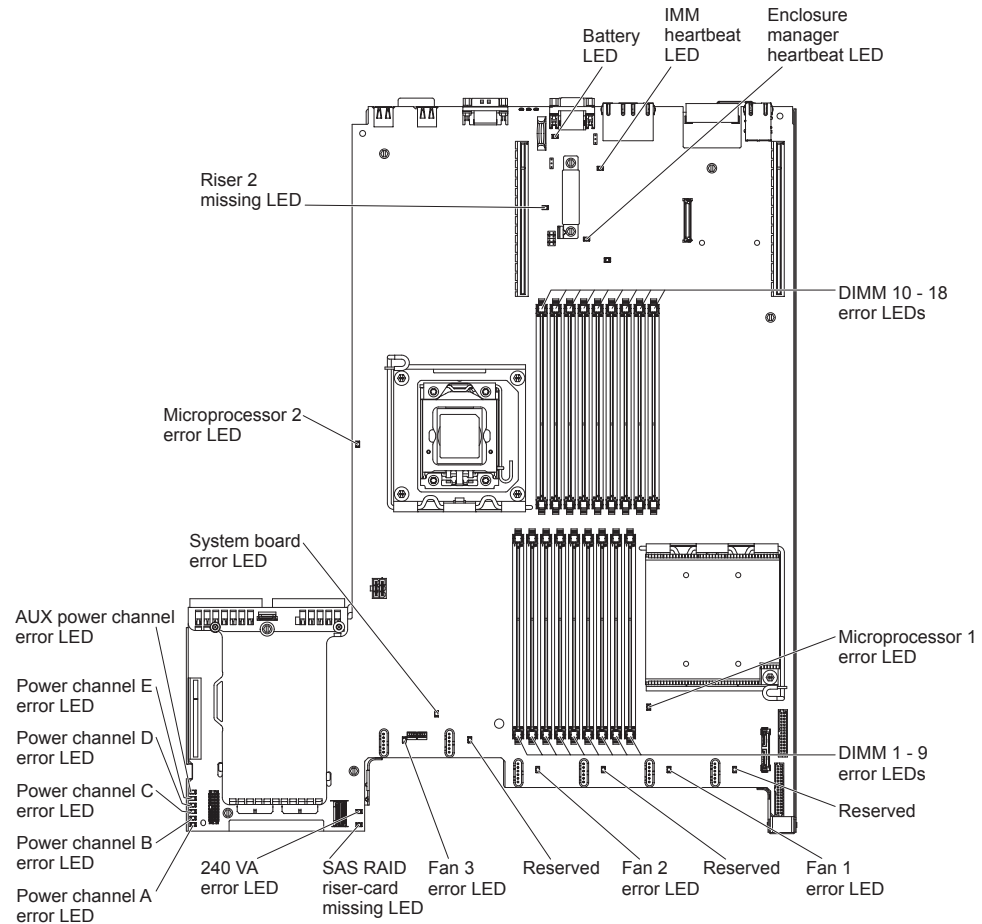
Note any LEDs that are lit, and then push the light path diagnostics panel back into the server.

Note:

- Do not run the server for an extended period of time while the light path diagnostics panel is pulled out of the server.
- Light path diagnostics LEDs remain lit only while the server is connected to power.

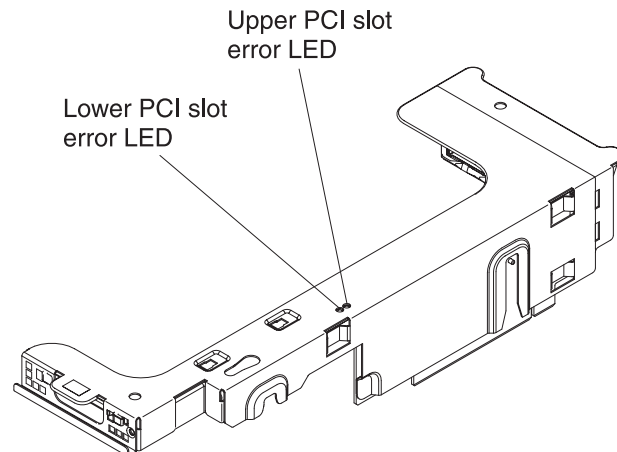
Look at the system service label on the top of the server, which gives an overview of internal components that correspond to the LEDs on the light path diagnostics panel. This information and the information in Light path diagnostics LEDs can often provide enough information to diagnose the error.

- Remove the server cover and look inside the server for lit LEDs. A lit LED on or beside a component identifies the component that is causing the error. The following illustration shows the LEDs on the system board.



12v channel error LEDs indicate an overcurrent condition. Refer to the procedure "Solving power problems" in the "Troubleshooting the System x3650" in the *IBM Storwize V7000 Unified Information Center* to identify the components that are associated with each power channel, and the order in which to troubleshoot the components.

The following illustration shows the LEDs on the riser card.



4. Check the Light path diagnostics LEDs for the correct combination of power LEDs that should be displayed during typical operation.

Light path diagnostics LEDs

LEDs on the light path diagnostics panel of the file module indicate the cause of a problem. The topic describes the suggested actions to correct the detected problems.

Table 16. LED indicators, corresponding problem causes, and corrective actions

| <ul style="list-style-type: none"> • Follow the suggested actions in the order in which they are listed in the Action column until the problem is solved. • If an action step is preceded by "(Trained technician only)," that step must be completed only by a trained technician. | | |
|---|--|---|
| LED | Problem | Action |
| Check log LED | An error occurred and cannot be isolated without completing certain procedures. | <ol style="list-style-type: none"> 1. Check the IMM2 system event log and the system-error log for information about the error. 2. Save the log if necessary and clear the log afterward. |
| System-error LED | An error occurred. | <ol style="list-style-type: none"> 1. Check the light path diagnostics LEDs and follow the instructions. 2. Check the IMM2 system event log and the system-error log for information about the error. 3. Save the log if necessary and clear the log afterward. |
| PS | When only the PS LED is lit, a power supply has failed. | <p>The system might detect a power supply error. Complete the following steps to correct the problem:</p> <ol style="list-style-type: none"> 1. Check the power-supply with a lit yellow LED. 2. Make sure that the power supplies are seated correctly and plugged in a good AC outlet. 3. Remove one of the power supplies to isolate the failed power supply. 4. Make sure that both power supplies installed in the file module are of the same AC input voltage. 5. Replace the failed power supply. |
| | PS + CONFIG When both the PS and CONFIG LEDs are lit, the power supply configuration is invalid. | If the PS LED and the CONFIG LED are lit, the system issues an invalid power configuration error. Make sure that both power supplies installed in the file module are of the same rating or wattage. |
| OVER SPEC | The system consumption reaches the power supply over current protection point or the power supplies are damaged. | <ol style="list-style-type: none"> 1. If the Power Rail (A, B, C, D, E, F, G, and H) error was not detected, complete the following steps: <ol style="list-style-type: none"> a. Use the IBM Power Configurator utility to determine current system power consumption. For more information and to download the utility, go to http://www-03.ibm.com/systems/bladecenter/resources/powerconfig.html. b. Replace the failed power supply. 2. If the Power Rail (A, B, C, D, E, F, G, and H) error was also detected, follow actions in the "Power problems" under the Troubleshooting tables and "Solving power problems" in the <i>Problem Determination and Service Guide</i>. |

Table 16. LED indicators, corresponding problem causes, and corrective actions (continued)

| LED | Problem | Action |
|-----|---|--|
| PCI | An error occurred on a PCI card, a PCI bus, or on the system board. An extra LED is lit next to a failing PCI slot. | <ul style="list-style-type: none"> 1. If the CONFIG LED is not lit, complete the following steps to correct the problem: <ul style="list-style-type: none"> a. Check the riser-card LEDs, the ServeRAID error LED, and the optional network adapter error LED to identify the component that caused the error. b. Check the system-error log for information about the error. c. If you cannot isolate the failing component by using the LEDs and the information in the system-error log, remove one component at a time; and restart the file module after each component is removed. d. Replace the following components, in the order that is shown, restarting the file module each time: <ul style="list-style-type: none"> • PCI riser cards • ServeRAID adapter • Optional network adapter • (Trained technician only) System board e. If the failure remains, go to http://www.ibm.com/systems/support/supportsite.wss/docdisplay?brandind=5000008&lnidocid=SERV-CALL. 2. If the PCI LED and the CONFIG LED are lit, complete the following steps to correct the problem: <ul style="list-style-type: none"> a. Check the microprocessor that is installed is Intel E5-2690. b. Remove the high-power (>25 Watt) adapter. c. Check the system-error logs for information about the error. Replace any component that is identified in the error log. |
| NMI | An interrupt that cannot be masked occurred, or the NMI button was pressed. | <ul style="list-style-type: none"> 1. Check the system-error log for information about the error. 2. Restart the file module. |

Table 16. LED indicators, corresponding problem causes, and corrective actions (continued)

| LED | Problem | Action |
|--------|--|---|
| CONFIG | A hardware configuration error occurred. | <ul style="list-style-type: none"> 1. If the CONFIG LED and the PS LED are lit, the system issues an invalid power configuration error. Make sure that both power supplies installed in the file module are of the same rating or wattage. 2. If the CONFIG LED and the PCI LED are lit, complete the following steps to correct the problem: <ul style="list-style-type: none"> a. Check the microprocessor that is installed is Intel E5-2690. b. Remove the high-power (>25 Watt) adapter. c. Check the system-error logs for information about the error. Replace any component that is identified in the error log. 3. If the CONFIG LED and the CPU LED are lit, complete the following steps to correct the problem: <ul style="list-style-type: none"> a. Check the microprocessors that were installed to make sure that they are compatible with each other. b. (Trained technician only) Replace the incompatible microprocessor. c. Check the system-error logs for information about the error. Replace any component that is identified in the error log. 4. If the CONFIG LED and the MEM LED are lit, check the system-event log in the Setup utility or IMM2 error messages. For more information, see the <i>Problem Determination and Service Guide</i>. 5. If the CONFIG LED and the HDD LED are lit, complete the following steps to correct the problem: <ul style="list-style-type: none"> a. Check the microprocessor that is installed is Intel E5-2690. If it is, check that the 2.5-inch hard disk drives installed are lesser than eight. b. Check the system-error logs for information about the error. Replace any component that is identified in the error log. |
| LINK | Reserved. | |

Table 16. LED indicators, corresponding problem causes, and corrective actions (continued)

| LED | Problem | Action |
|-----|--|---|
| CPU | When only the CPU LED is lit, a microprocessor has failed. When both the CPU and CONFIG LEDs are lit, the microprocessor configuration is invalid. | <ul style="list-style-type: none"> • Follow the suggested actions in the order in which they are listed in the Action column until the problem is solved. • If an action step is preceded by "(Trained technician only)," that step must be completed only by a trained technician. <ol style="list-style-type: none"> 1. If the CONFIG LED is not lit, a microprocessor failure occurs, complete the following steps: <ol style="list-style-type: none"> a. (Trained technician only) Make sure that the failing microprocessor and its heat sink, which are indicated by a lit LED on the system board, are installed correctly. b. (Trained technician only) Replace the failing microprocessor. c. For more information, go to http://www.ibm.com/systems/support/supportsite.wss/docdisplay?brandind=5000008&Indocid=SERV-CALL. 2. If the CONFIG LED and the CPU LED are lit, the system issues an invalid microprocessor configuration error. Complete the following steps to correct the problem: <ol style="list-style-type: none"> a. Check the microprocessors that were installed to make sure that they are compatible with each other. b. (Trained technician only) Replace the incompatible microprocessor. c. Check the system-error logs for information about the error. Replace any component that is identified in the error log. |
| MEM | When only the MEM LED is lit, a memory error has occurred. When both the MEM and CONFIG LEDs are lit, the memory configuration is invalid. | <p>Note: Each time that you install or remove a DIMM, you must disconnect the file module from the power source; then, wait 10 seconds before you restart the file module.</p> <ol style="list-style-type: none"> 1. If the CONFIG LED is not lit, the system might detect a memory error. Complete the following steps to correct the problem: <ol style="list-style-type: none"> a. Update the file module firmware to the latest level. For more information, see the <i>Problem Determination and Service Guide</i>. b. Reseat or swap the DIMMs. c. Check the system-event log in the Setup utility or IMM error messages. For more information, see the <i>Problem Determination and Service Guide</i>. d. Replace the failing DIMM. 2. If the MEM LED and the CONFIG LED are lit, check the system-event log in the Setup utility or IMM error messages. For more information, see the <i>Problem Determination and Service Guide</i>. |

Table 16. LED indicators, corresponding problem causes, and corrective actions (continued)

| LED | Problem | Action |
|-------|--|---|
| TEMP | The system or the system component temperature has exceeded a threshold level. A failing fan can cause the TEMP LED to be lit. | <ol style="list-style-type: none"> 1. Make sure that the heat sink is seated correctly. 2. Determine whether a fan has failed. If it has, replace it. 3. Make sure that the room temperature is not too high. 4. Make sure that the air vents are not blocked. 5. Make sure that the heat sink, the fan on the adapter, or the optional network adapter is seated correctly. If the fan has failed, replace it. 6. If the failure remains, go to http://www.ibm.com/systems/support/supportsite.wss/docdisplay?brandind=5000008&Indocid=SERV-CALL. |
| FAN | A fan that failed, is operating too slowly, or is removed. The TEMP LED might also be lit. | <ol style="list-style-type: none"> 1. Reseat the failing fan, which is indicated by a lit LED near the fan connector on the system board. 2. Replace the failing fan. |
| BOARD | An error occurred on the system board. | <ol style="list-style-type: none"> 1. Check the LEDs on the system board to identify the component that caused the error. The BOARD LED can be lit due to any of the following reasons: <ul style="list-style-type: none"> • Battery • (Trained technician only) System board 2. Check the system-error log for information about the error. 3. Replace the failing component: <ul style="list-style-type: none"> • Battery • (Trained technician only) System board |

Table 16. LED indicators, corresponding problem causes, and corrective actions (continued)

| LED | Problem | Action |
|-----|---|--|
| HDD | A hard disk drive has failed or is missing. | <ul style="list-style-type: none"> 1. If the CONFIG LED is not lit, complete the following steps to correct the problem: <ul style="list-style-type: none"> a. Check the LEDs on the hard disk drives for the drive with a lit status LED and reseal the hard disk drive. b. Reseat the hard disk drive backplane. c. For more information, see the "hard disk drive problems" under the Troubleshooting tables in the <i>Problem Determination and Service Guide</i>. d. If the error remains, replace the following components one at a time, in the order that is listed, restarting the file module after each: <ul style="list-style-type: none"> 1) Replace the hard disk drive. 2) Replace the hard disk drive backplane. e. If the problem remains, go to http://www.ibm.com/systems/support/supportsite.wss/docdisplay?brandind=5000008&Indocid=SERV-CALL. 2. If the HDD LED and the CONFIG LED are lit, complete the following steps to correct the problem: <ul style="list-style-type: none"> a. Check that the microprocessor installed is Intel E5-2690. If it is, check that the 2.5-inch hard disk drives installed are lesser than eight. b. Check the system-error logs for information about the error. Replace any component that is identified in the error log. |

Power-supply LEDs

LEDs on the operator information panel of the file module indicate the cause of a problem. The topic describes the suggested actions to correct the detected problems.

The following minimum configuration is required for the DC LED on the power supply to be lit:

- Power supply
- Power cord

Note: You must turn on the file module for the DC LED on the power supply to be lit.

The following minimum configuration is required for the file module to start:

- One microprocessor in microprocessor socket 1
- One 2 GB DIMM on the system board
- One power supply
- Power cord
- Four cooling fans (fan 1, 2, 3, and 5)
- One PCI riser-card assembly in PCI connector 1

The following illustration shows the locations of the power-supply LEDs on the AC power supply.

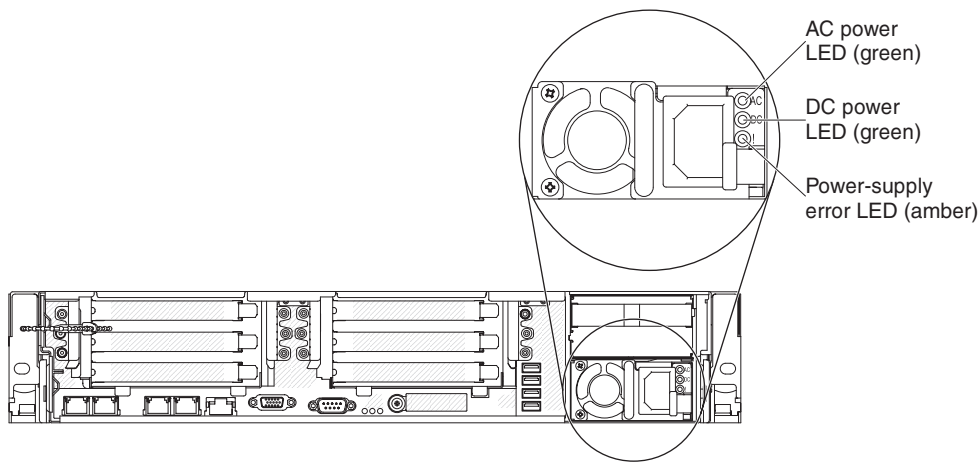


Figure 4. Locations of the power-supply LEDs

The following table describes the problems that are indicated by various combinations of the power-supply LEDs and the power-on LED on the operator information panel and suggested actions to correct the detected problems.

| AC power-supply LEDs | | | Description | Action | Notes |
|----------------------|-----|-----------|---|---|---|
| AC | DC | Error (!) | | | |
| On | On | Off | Normal operation. | | |
| Off | Off | Off | No AC power to the file module or a problem with the AC power source. | <ol style="list-style-type: none"> 1. Check the AC power to the file module. 2. Make sure that the power cord is connected to a functioning power source. 3. Restart the file module. If the error remains, check the power-supply LEDs. 4. If the problem remains, replace the power-supply. | This is a normal condition when no AC power is present. |
| Off | Off | On | The power supply has failed. | Replace the power supply. | |
| Off | On | Off | The power supply has failed. | Replace the power supply. | |
| Off | On | On | The power supply has failed. | Replace the power supply. | |

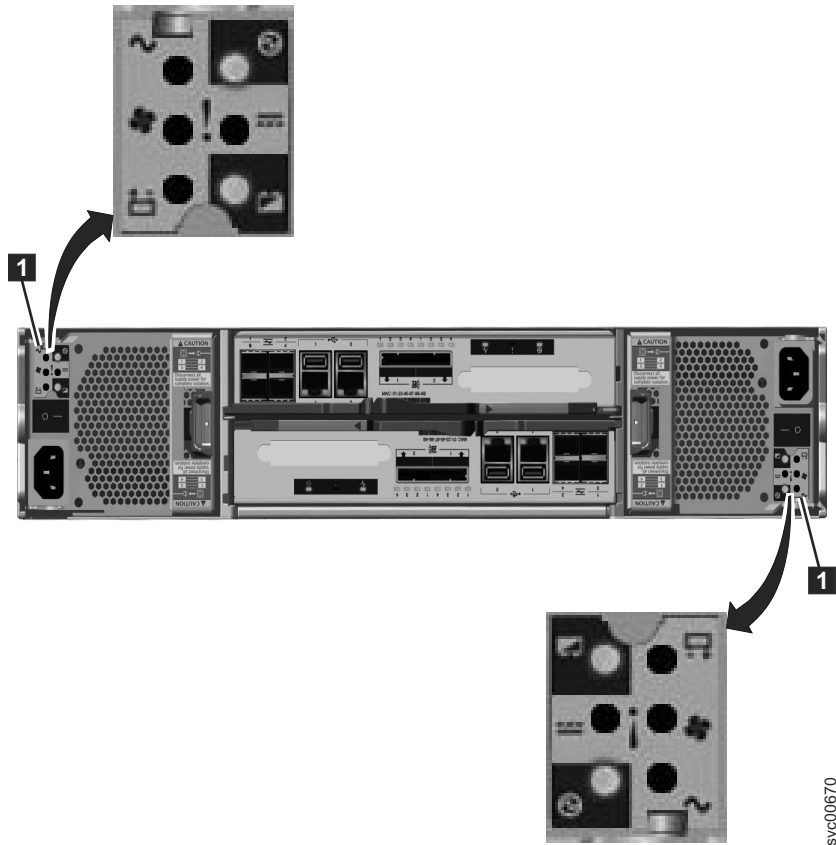
| AC power-supply LEDs | | | Description | Action | Notes |
|----------------------|-----|-----------|---|--|---|
| AC | DC | Error (!) | | | |
| On | Off | Off | Power supply not fully seated, faulty system board, or the power supply has failed. | <ol style="list-style-type: none"> 1. Reseat the power supply. 2. If the OVER SPEC LED on the light path diagnostics is lit, follow the actions in Light path diagnostics LEDs. 3. If the OVER SPEC LED on the light path diagnostics is not lit, check the error LEDs on the system board and the IMM2 error messages. | Typically indicates a power-supply is not fully seated. |
| On | Off | On | The power supply has failed. | Replace the power supply. | |
| On | On | On | The power supply has failed. | Replace the power supply. | |

Enclosure hardware indicators

The LEDs provide a general idea of the system status.

This topic shows the status for the control enclosure chassis, power supply units and batteries, and canisters. It does not show the status for the drives.

Table 17 on page 49 shows the power supply LEDs. Figure 5 on page 49 shows the LEDs on the power supply unit for the 2076-112 or the 2076-124. The LEDs on the power supply units for the 2076-312 and 2076-324 are similar, but they are not shown here.



svc00670

Figure 5. LEDs on the power supply units of the control enclosure

Table 17. Power-supply unit LEDs





| Power supply OK  | ac failure  | Fan failure  | dc failure  | Status | Action |
|--|---|--|---|--|--|
| On | On | On | On | Communication failure between the power supply unit and the enclosure chassis | Replace the power supply unit. If failure is still present, replace the enclosure chassis. |
| Off | Off | Off | Off | No ac power to the enclosure. | Turn on power. |
| Off | Off | Off | On | The ac power is on but power supply unit is not seated correctly in the enclosure. | Seat the power supply unit correctly in the enclosure. |

Table 17. Power-supply unit LEDs (continued)





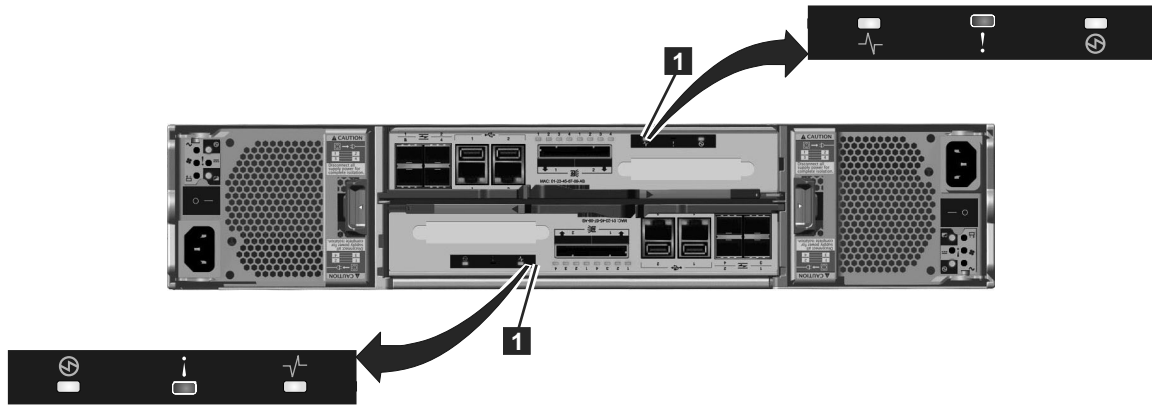
| Power supply OK  | ac failure  | Fan failure  | dc failure  | Status | Action |
|--|---|--|---|--|--|
| Off | On | Off | On | No ac power to this power supply | <ol style="list-style-type: none"> 1. Check that the switch on the power supply unit is on. 2. Check that the ac power is on. 3. Reseat and replace the power cable. |
| On | Off | Off | Off | Power supply is on and operational. | No actions |
| Off | Off | On | Off | Fan failure | Replace the power supply unit. |
| Off | On | On | On | Communication failure and power supply problem | Replace the power supply unit. If replacing the power supply unit does not fix the problem, replace the enclosure chassis. |
| Flashing | X | X | X | No canister is operational. | Both canisters are either off or not seated correctly. Turn off the switch on both power supply units and then turn on both switches. If this action does not resolve the problem, remove both canisters slightly and then push the canisters back in. |
| Off | Flashing | Flashing | Flashing | Firmware is downloading. | No actions. Do not remove ac power. Note: In this case, if there is a battery in a power supply unit, its LEDs also flash. |

Table 18 on page 51 shows the three canister status LEDs on each of the node canisters. Figure 6 on page 51 shows the LEDs on the node canister.



svc00672

Figure 6. LEDs on the node canisters

Table 18. Power LEDs


| Power LED status  | Description |
|--|---|
| Off | There is no power to the canister. Try reseating the canister. Go to “Procedure: Reseating a node canister” on page 208. If the state persists, follow the hardware replacement procedures for the parts in the following order: node canister, enclosure chassis. |
| Slow flashing (1 Hz) | Power is available, but the canister is in standby mode. Try to start the node canister by reseating it. Go to “Procedure: Reseating a node canister” on page 208. |
| Fast flashing (2 Hz) | The canister is running its power-on self-test (POST). Wait for the test to complete. If the canister remains in this state for more than 10 minutes, try reseating the canister. Go to “Procedure: Reseating a node canister” on page 208. If the state persists, follow the hardware replacement procedure for the node canister. |

Table 19 shows the states of the system status and fault LEDs.

Table 19. System status and fault LEDs




| System status LED  | Fault LED  | Status  | Action |
|---|---|--|--|
| Off | Off | Code is not active. | <ul style="list-style-type: none"> Follow procedures for reviewing power LEDs. If the power LEDs show green, reseat the node canister. See “Procedure: Reseating a node canister” on page 208. If the LED status does not change, see “Replacing a node canister” on page 210. |
| Off | On | Code is not active. The BIOS or the service processor has detected a hardware fault. | Follow the hardware replacement procedures for the node canister. |

Table 19. System status and fault LEDs (continued)




| System status LED  | Fault LED  | Status  | Action |
|--|---|---|---|
| On | Off | Code is active. Node state is active. | No action. The node canister is part of a clustered system and can be managed by the management GUI. |
| On | On | Code is active and is in starting state. However, it does not have enough resources to form the clustered system. | The node canister cannot become active in a clustered system. There are no detected problems on the node canister itself. However, it cannot connect to enough resources to safely form a clustered system. Follow the procedure to fix the node errors. Go to "Procedure: Fixing node errors" on page 206. |
| Flashing | Off | Code is active. Node state is candidate. | Create a clustered system on the node canister, or add the node canister to the clustered system. If the other node canister in the enclosure is in active state, it automatically adds this node canister into the clustered system. A node canister in this state can be managed using the service assistant. |
| Flashing | On | Code is active. Node state is service. | The node canister cannot become active in a clustered system. Several problems can exist: hardware problem, a problem with the environment or its location, or problems with the code or data on the canister. Follow the procedure to fix the node errors. Go to "Procedure: Fixing node errors" on page 206. |
| Any | Flashing | The node canister is being identified so that you can locate it. | The fix procedures in the management GUI might have identified the component because it requires servicing. Continue to follow the fix procedures. The service assistant has a function to identify node canisters. If the identification LED is on in error, use the service assistant node actions to turn off the LED. |

Table 20 shows the status of the control enclosure batteries.

Table 20. Control enclosure battery LEDs





| Battery Good  | Battery Fault  | Description | Action |
|---|--|--|--------|
| On | Off | Battery is good and fully charged. | None |
| Flashing | off | Battery is good but not fully charged. The battery is either charging or a maintenance discharge is being performed. | None |

Table 20. Control enclosure battery LEDs (continued)

| Battery Good  | Battery Fault  | Description | Action |
|---|--|--|--|
| Off | On | Nonrecoverable battery fault. | Replace the battery. If replacing the battery does not fix the issue, replace the power supply unit. |
| Off | Flashing | Recoverable battery fault. | None |
| Flashing | Flashing | The battery cannot be used because the firmware for the power supply unit is being downloaded. | None |

Management GUI interface

The management GUI is a browser-based GUI for configuring and managing all aspects of your system. It provides extensive facilities to help troubleshoot and correct problems.

About this task

You use the management GUI to manage and service your system. The **Monitoring > Events** panel provides access to problems that must be fixed and maintenance procedures that step you through the process of correcting the problem.

Two tabs are available for monitoring events:

- A **Block** tab for monitoring the SAN volume events and the file system volume events from the control enclosure.
- A **File** tab for monitoring the NAS events from the Storwize V7000 Unified file modules.

When you click the **Block** tab, a **Next recommended action** is shown. Perform the next recommended action before attempting any other recommended actions.

The information on the Events panel can be filtered three ways:

Recommended action (default)

Shows only the alerts that require attention. Alerts are listed in priority order and should be fixed sequentially by using the available fix procedures. For each problem that is selected, you can:

- Run a fix procedure.
- View the properties.

Unfixed messages and alerts

Displays only the alerts and messages that are not fixed. For each entry that is selected, you can:

- Run a fix procedure.
- Mark an event as fixed.
- Filter the entries to show them by specific minutes, hours, or dates.
- Reset the date filter.
- View the properties.

Show all

Displays all event types whether they are fixed or unfixed. For each entry that is selected, you can:

- Run a fix procedure.
- Mark an event as fixed.
- Filter the entries to show them by specific minutes, hours, or dates.
- Reset the date filter.
- View the properties.

Some events require a certain number of occurrences in 25 hours before they are displayed as unfixed. If they do not reach this threshold in 25 hours, they are flagged as expired. Monitoring events are below the coalesce threshold and are usually transient.

You can also sort events by time or error code. When you sort by error code, the most serious events, those with the lowest numbers, are displayed first. You can select any event that is listed and select **Actions > Properties** to view details about the event.

- Recommended Actions. For each problem that is selected, you can:
 - Run a fix procedure.
 - View the properties.
- Event log. For each entry that is selected, you can:
 - Run a fix procedure.
 - Mark an event as fixed.
 - Filter the entries to show them by specific minutes, hours, or dates.
 - Reset the date filter.
 - View the properties.

When to use the management GUI

The management GUI is the primary tool that is used to service your system.

Regularly monitor the status of the system using the management GUI. If you suspect a problem, use the management GUI first to diagnose and resolve the problem.

Use the views that are available in the management GUI to verify the status of the system, the hardware devices, the physical storage, and the available volumes. The **Monitoring > Events** panel provides access to all problems that exist on the system. Use the **Recommended Actions** filter to display the most important events that need to be resolved.

If there is a service error code for the alert, you can run a fix procedure that assists you in resolving the problem. These fix procedures analyze the system and provide more information about the problem. They suggest actions to take and step you through the actions that automatically manage the system where necessary. Finally, they check that the problem is resolved.

If there is an error that is reported, always use the fix procedures within the management GUI to resolve the problem. Always use the fix procedures for both system configuration problems and hardware failures. The fix procedures analyze the system to ensure that the required changes do not cause volumes to be

inaccessible to the hosts. The fix procedures automatically perform configuration changes that are required to return the system to its optimum state.

Accessing the Storwize V7000 Unified management GUI

This procedure describes how to access the Storwize V7000 Unified management GUI.

About this task

You must use a supported web browser. Verify that you are using a supported web browser. Checking your web browser settings for the management GUI from the Storwize V7000 Information Center.

www.ibm.com/storage/support/storwize/v7000/unified

You can use the management GUI to manage your system as soon as you have completed the USB flash drive initialization.

Procedure

1. Start a supported web browser and point the browser to the management IP address of the file module.
The management IP address is set during the USB flash drive initialization.
2. When the connection is successful, you see a login panel.
3. Log on by using your user name and password. The default user name is admin.
4. When you have logged on, select **Monitoring > Events**.
5. Ensure that the events log is filtered by using **Recommended actions**.
6. Select the recommended action and run the fix procedure.
7. Continue to work through the alerts in the order suggested, if possible.

Results

After all the alerts are fixed, check the status of your system to ensure that it is operating as intended.

If you encounter problems logging on the management GUI or connecting to the management GUI, see “Problem: Unable to log on to the management GUI” on page 191 or “Problem: Unable to connect to the management GUI” on page 190.

Using fix procedures

You can use fix procedures to diagnose and resolve problems with the Storwize V7000 Unified.

About this task

For example, to repair a Storwize V7000 Unified system, you might perform the following tasks:

- Analyze the event log
- Replace failed components
- Verify the status of a repaired device
- Restore a device to an operational state in the system
- Mark the error as fixed in the event log

Fix procedures help simplify these tasks by automating as many of the tasks as possible.

Many of the file module fix procedures are not automated. In these cases, you are directed to a documented procedure in the Storwize V7000 Unified Information Center.

The example uses the management GUI to repair a Storwize V7000 Unified system. Perform the following steps to start the fix procedure:

Procedure

1. Click **Monitoring > Events** and ensure that you are filtering the event log to display **Recommended actions**.

The list might contain any number of errors that must be repaired. If there is more than one error on the list, the error at the top of the list has the highest priority and must always be fixed first. If you do not fix the higher priority errors first, you might not be able to fix the lower priority errors.

2. Select the error at the top of the list or select the **Next recommended action**.
3. Click **Run Fix Procedure**.

The panel displays the error code and provides a description of the condition.

4. Click **Next** to go forward or **Cancel** to return to the previous panel.
5. One or more panels might be displayed with instructions for you to replace parts or perform other repair activity. If you are not able to complete the actions at this time, click **Cancel** until you return to the previous panel. Click **Cancel** until you are returned to the Next Recommended Actions panel. When you return to the fix procedures, the repair can be restarted from step 1. When the actions that you are instructed to perform are complete, click **OK**. When the last repair action is completed, the procedures might attempt to restore failed devices to the system.
6. After you complete the fix, you see the statement Click OK to mark the error as fixed. Click **OK**. This action marks the error as fixed in the event log and prevents this instance of the error from being listed again.
7. When you see the statement The repair has been completed., click **Exit**. If other errors must be fixed, those errors are displayed and the fix procedures continue.
8. If no errors remain, you are shown the following statement: There are no unfixed errors in the event log.

Chapter 4. File module

This topic provides information about troubleshooting the file module, which includes error codes, problem scenarios, software troubleshooting, and removal and replacement instructions.

General file module procedures

This section covers file module general maintenance and repair issues.

Rebooting a file module

Use this procedure to initiate a file module reboot.

Before you begin

Events can occur on a file module that require the hardware to be rebooted.

Procedure

1. To shut down and restart a node by using the management GUI, follow these steps:
 - a. Click **Monitoring > System Details**.
 - b. Click the **Interface Nodes** tab.
 - c. In the left pane, select the node to reboot. In the right pane, click **Actions > Restart**.

Note: If the file module to be rebooted is the active management node, the management GUI will also shut down and cause the management GUI to become unresponsive. After the management services have failed over to the other file module, a refresh of the management GUI in the browser reestablishes the connection.

2. To shut down and reboot a node by using the command-line interface (CLI) command, enter:

```
stopcluster -node mgmt00Xst001 -restart
```

where *X* is the logical ID of the node to reboot.

3. The node reboot restarts all services that were previously running *g* but does not resume the node on to the cluster.

```
resumenode mgmt00Xst001
```

Removing a file module to perform a maintenance action

You can remove an IBM Storwize V7000 Unified file module to perform maintenance. The procedure that you follow differs slightly, depending on whether you must unplug the power cables.

Before you begin

If you receive an alert event that requires you to service a file module, use the following procedure to remove the file module from the system and perform the required service.

About this task

Some field replaceable units (FRUs) are redundant and hot swappable, such as power supplies. When replacing a hot-swap FRU, you have the option of leaving the file module turned on and the power cables connected. Always follow the remove and replace procedure for the FRU. The procedure for the FRU indicates whether the FRU is hot swappable.

If the removal and replacement procedure does not indicate whether the FRU is hot swappable, assume that it is not. In that case use the file module-removal procedure that requires you to disconnect the power cords.

Note: Before removing an file module, you must suspend the file module.

Procedure

- Remove a file module from the system to replace a hot swappable FRU, as described in “Removing a file module without disconnecting power” on page 59.
- Remove a file module from the system, turn off the node, and disconnect the power cords, as described in “Removing a file module and disconnecting power.”

Removing a file module and disconnecting power

You must remove an IBM Storwize V7000 file module from the file cluster and disconnect it from its power line cords before performing a maintenance action that requires the file module to have no power.

About this task

To identify and perform a service action on any file module that requires you to turn off the power before performing the service action, perform the following procedure.

Procedure

1. Access and log in to the Storwize V7000 Unified system from the command-line interface.
2. Suspend the file module. Use the `suspendnode` command on one of the file modules that you need to maintain, as shown in the following examples, to stop a file module from providing the services.

- `suspendnode mgmt001st001`
- `suspendnode mgmt002st001`

A suspended file module does not participate in the cluster and does not host any records for the clustered trivial database (CTDB). The IP addresses of a file module are taken over by the other file module and no services are lost. You can review the status of the file module by using the `lsnode` command with the `-r` option. Review the row for the file module that was suspended and the column for the **Connection Status**.

3. Use the `stopcluster` command to remove the file module from the system and shut down the file module.

If you are shutting down the `mgmt001st001` file module, for example, issue the following command:

```
stopcluster -n mgmt001st001
```

4. After the file module shuts down and the power indicator light on the front of the file module is flashing slowly, pull the file module out on its rails.

Note: Label and disconnect both power cords and all external cables from the file module.

5. Remove the file module from the rack if necessary, or locate and use the service ladder, if necessary, to perform the maintenance action on the file module when it is fully extended from the rack.
6. Locate and perform the correct removal and replacement procedure.
Attention: You can replace only one of the disk drives in the file module. If you must replace both disk drives, contact IBM Remote Technical Support.
7. After replacing the failing part and replacing the file module cover, replace the file module in the rack, if necessary, and reconnect the power cords.
After reconnecting the power cords, the power indicator LED on the front of the file module begins to flash quickly.
8. Push the file module back into the rack.
9. After the power indicator LED on the front of the file module begins to flash slowly, press the power switch that surrounds the indicator light to turn on the file module.
As the file module reboots, the Storwize V7000 Unified system reintegrates it back into the cluster.
10. After the file module is fully booted back into the system, resume the file module using the `resumenode` command that was previously suspended and shutdown.

Removing a file module without disconnecting power

You can work on an IBM Storwize V7000 Unified file module to perform a maintenance action that does not require you to remove its power cords.

About this task

Perform the following procedure to remove and replace a hot swappable field replaceable unit (FRU) in a file module when you do not have to remove the file module from the rack to work on it.

Procedure

1. Access and log in to the Storwize V7000 Unified system from the command-line interface.
2. Issue the **suspendnode** command to remove the file module from the system so that you can work on it.

To remove the `mgmt001st001` file module from the system, for example, issue the following command:

```
# suspendnode mgmt001st001
```

3. Wait for the Storwize V7000 Unified system to stop the file module at the clustered trivial database (CTDB) level. The command does not unmount any mounted file systems.

A stopped file module does not participate in the cluster and does not host any records for the clustered trivial database. The IP address of a file module is taken over by another file module and no services are hosted.

You can issue the **lsnode -r** command to view the state of the file module.

The results from running the **lsnode -r** command are similar to the following example:

```
# lsnode -r
```

| Hostname | IP | Description | Role |
|--------------|------------|------------------------|------------------------------|
| mgmt001st001 | 10.254.8.2 | active management node | management,interface,storage |

```
mgmt002st001 10.254.8.3 passive management node management,interface,storage
```

| Product Version | Connection status | GPFS status | CTDB status | Last updated |
|-----------------|-------------------|-------------|---------------------|-----------------|
| 1.3.0.2-02 | OK | active | active | 1/17/12 4:39 PM |
| 1.3.0.2-02 | SUSPEND | active | SUSPEND_MAINTENANCE | 1/17/12 4:39 PM |

4. Pull the file module out from the rack on its rails.
5. Locate and use the service ladder, if necessary, to perform the maintenance action on the file module when it is fully extended from the rack.
6. Locate and perform the correct removal and replacement procedure.
Attention: You can replace only one of the disk drives in the file module. If you must replace both disk drives, contact IBM Remote Technical Support.
7. After replacing the failing part and replacing the file module cover, push the file module back in the rack.
8. Use the **resumenode** command to add the file module back into the system so that it can begin to host services.
To add the mgmt001st001 file module back into the system, for example, issue the following command:

```
# resumenode mgmt001st001
```
9. After the Storwize V7000 Unified system reintegrates the file module back into the cluster, the `ctdb status` command shows that the service is active on the file module.

Removing and replacing file module components

The IBM Storwize V7000 Unified system contains parts that are both customer replaceable units (CRUs) and field replaceable units (FRUs). CRUs can be installed by the customer, but all FRUs must be installed by trained service technicians.

About this task

Installation guidelines

To help you work safely with IBM Storwize V7000 Unified file modules, read the safety information in , Safety information statements, and these guidelines.

Before you remove or replace a component, read the following information:

- When you install a file module, take the opportunity to download and apply the most recent firmware updates. This step helps to ensure that any known issues are addressed and that your file module is ready to function at maximum levels of performance.
- Before you install any hardware, make sure that the file module is working correctly. Start the file module, and make sure that the Linux operating system starts. If the file module is not working correctly, see Chapter 3, “Getting started troubleshooting,” on page 9 for diagnostic information.
- Observe good housekeeping in the area where you are working. Place removed covers and other parts in a safe place.
- If you must start the file module while the cover is removed, make sure that no one is near the file module and that no tools or other objects have been left inside the file module.
- Do not attempt to lift an object that you think is too heavy for you. If you have to lift a heavy object, observe the following precautions:
 - Make sure that you can stand safely without slipping.
 - Distribute the weight of the object equally between your feet.
 - Use a slow lifting force. Never move suddenly or twist when you lift a heavy object.

- To avoid straining the muscles in your back, lift by standing or by pushing up with your leg muscles.
- Make sure that you have an adequate number of properly grounded electrical outlets for the PDUs.
- Back up all important data before you make changes to disk drives.
- Have a small flat-blade screwdriver available.
- To view the error LEDs on the system board and internal components, leave the file module connected to power.
- You do not have to turn off the file module to install or replace hot-swap fans, redundant hot-swap ac power supplies, or hot-plug Universal Serial Bus (USB) devices. However, you must turn off the file module before performing any steps that involve removing or installing adapter cables or non-hot-swap optional devices or components.
- Blue on a component indicates touch points, where you can grip the component to remove it from or install it in the file module, open or close a latch, and so on.
- Orange on a component or an orange label on or near a component indicates that the component can be hot-swapped, which means that if the file module and operating system support hot-swap capability, you can remove or install the component while the file module is running. (Orange can also indicate touch points on hot-swap components.) See the instructions for removing or installing a specific hot-swap component for any additional procedures that you might have to perform before you remove or install the component.
- When you are finished working on the file module, reinstall all safety shields, guards, labels, and ground wires.

Node reliability guidelines

To help ensure proper cooling and system reliability, make sure that:

- Each of the drive bays has a drive or a filler panel and electromagnetic compatibility (EMC) shield installed in it.
- If the server has redundant power, each of the power-supply bays has a power supply installed in it.
- There is adequate space around the server to allow the server cooling system to work properly. Leave approximately 50 mm (2.0 in.) of open space around the front and rear of the server. Do not place objects in front of the fans. For proper cooling and airflow, replace the server cover before turning on the server. Operating the server for extended periods of time (more than 30 minutes) with the server cover removed might damage server components.
- You have followed the cabling instructions that come with optional adapters.
- You have replaced a failed fan within 48 hours.
- You have replaced a hot-swap drive within 2 minutes of removal.
- You operate the server with the air baffles installed. Operating the server without the air baffles might cause the microprocessor to overheat.

Working inside the file module with the power on

Attention: Static electricity that is released to internal file module components when the file module is powered-on might cause the file module to halt, which could result in the loss of data. To avoid this potential problem, always use an electrostatic-discharge wrist strap or other grounding system when working inside the file module with the power on.

The file module supports hot-plug, hot-add, and hot-swap devices and is designed to operate safely while it is turned on and the cover is removed. Follow these guidelines when you work inside a file module that is turned on:

- Avoid wearing loose-fitting clothing on your forearms. Button long-sleeved shirts before working inside the file module; do not wear cuff links while you are working inside the file module.
- Do not allow your necktie or scarf to hang inside the file module.
- Remove jewelry, such as bracelets, necklaces, rings, and loose-fitting wrist watches.
- Remove items from your shirt pocket, such as pens and pencils, that could fall into the file module as you lean over it.
- Avoid dropping any metallic objects, such as paper clips, hairpins, and screws, into the file module.

Handling static-sensitive devices

Attention: Static electricity can damage the server and other electronic devices. To avoid damage, keep static-sensitive devices in their static-protective packages until you are ready to install them.

To reduce the possibility of damage from electrostatic discharge, observe the following precautions:

- Limit your movement. Movement can cause static electricity to build up around you.
- The use of a grounding system is recommended. For example, wear an electrostatic-discharge wrist strap, if one is available. Always use an electrostatic-discharge wrist strap or other grounding system when working inside the server with the power on.
- Handle the device carefully, holding it by its edges or its frame.
- Do not touch solder joints, pins, or exposed circuitry.
- Do not leave the device where others can handle and damage it.
- While the device is still in its static-protective package, touch it to an unpainted metal surface on the outside of the server for at least 2 seconds. This drains static electricity from the package and from your body.
- Remove the device from its package and install it directly into the server without setting down the device. If it is necessary to set down the device, put it back into its static-protective package. Do not place the device on the server cover or on a metal surface.
- Take additional care when handling devices during cold weather. Heating reduces indoor humidity and increases static electricity.

Returning a device or component

When returning a device or component, follow all packaging instructions and use any supplied packaging materials for shipping.

Resolving hard disk drive problems

Use this information to address various hard disk drive issues.

About this task

| <ul style="list-style-type: none"> • Before running a procedure, refer to “Removing a file module to perform a maintenance action” on page 57. • Follow the suggested actions for a Symptom in the order in which they are listed in the Action column until the problem is solved. • If an action step is preceded by “(Trained service technician only)”, that step must be performed only by a trained service technician. | |
|--|--|
| Symptom | Action |
| A hard disk drive has failed and the associated amber hard disk drive status LED is lit. | Replace the failed hard disk drive. |
| An installed hard disk drive is not recognized. | <ol style="list-style-type: none"> 1. Observe the associated amber hard disk drive status LED. If the LED is lit, it indicates a drive fault. 2. If the LED is lit, remove the drive from the bay, wait 45 seconds, then reinsert the drive, ensuring that the drive assembly connects to the hard disk drive backplane. 3. Observe the associated green hard disk drive activity LED and the amber status LED: <ul style="list-style-type: none"> • If the green activity LED is flashing and the amber status LED is not lit, the drive is recognized by the controller and is working correctly. Run the DSA hard disk drive test to determine whether the drive is detected. • If the green activity LED is flashing and the amber status LED is flashing slowly, the drive is recognized by the controller and is rebuilding. • If neither LED is lit or flashing, check the hard disk drive backplane (go to step 4). • If the green activity LED is flashing and the amber status LED is lit, replace the drive. If the activity of the LEDs remains the same, go to step 4. If the activity of the LEDs changes, return to step 1. 4. Ensure that the hard disk drive backplane is correctly seated. When it is correctly seated, the drive assemblies correctly connect to the backplane without bowing or causing movement of the backplane. 5. Move the hard disk drives to different bays to determine if the drive or the backplane is not functioning. 6. Re-seat the backplane power cable and repeat steps 1 through 3. 7. Re-seat the backplane signal cable and repeat steps 1 through 3. 8. Suspect the backplane signal cable or the backplane: <ul style="list-style-type: none"> • If the server has eight hot-swap bays: <ol style="list-style-type: none"> a. Replace the affected backplane signal cable. b. Replace the affected backplane. • If the server has 12 hot-swap bays: <ol style="list-style-type: none"> a. Replace the backplane signal cable. b. Replace the backplane. c. Replace the SAS expander card. |
| Multiple hard disk drives fail. | <p>Ensure that the hard disk drive, SAS RAID controller, and server device drivers and firmware are of the latest version.</p> <p>Important: Some cluster solutions require specific code levels or coordinated code updates. If the device is part of a cluster solution, check whether the latest code version is supported before you update the code.</p> |
| Multiple hard disk drives are offline. | <ol style="list-style-type: none"> 1. Review the storage subsystem logs for indications of problems within the storage subsystem, such as backplane or cable problems. |

| <ul style="list-style-type: none"> • Before running a procedure, refer to “Removing a file module to perform a maintenance action” on page 57. • Follow the suggested actions for a Symptom in the order in which they are listed in the Action column until the problem is solved. • If an action step is preceded by “(Trained service technician only)”, that step must be performed only by a trained service technician. | |
|--|---|
| Symptom | Action |
| A replacement hard disk drive does not rebuild. | <ol style="list-style-type: none"> 1. Ensure that the hard disk drive is recognized by the controller (the green hard disk drive activity LED is flashing). 2. Review the SAS RAID controller documentation to determine the correct configuration parameters and settings. |
| A green hard disk drive activity LED does not accurately represent the actual state of the associated drive. | <ol style="list-style-type: none"> 1. If the green hard disk drive activity LED does not flash when the drive is in use, run the DSA Preboot diagnostic programs to collect error logs. Refer to the “Diagnostics” or “Running the diagnostic programs” section in “Troubleshooting the System x3650” in the <i>IBM Storwize V7000 Unified Information Center</i>. 2. Use one of the following procedures: <ul style="list-style-type: none"> • If the drive passes the test, replace the backplane. • If the drive fails the test, replace the drive. |
| An amber hard disk drive status LED does not accurately represent the actual state of the associated drive. | <ol style="list-style-type: none"> 1. If the amber hard disk drive LED and the RAID controller software do not indicate the same status for the drive, complete the following steps: <ol style="list-style-type: none"> a. Turn off the server. b. Re-seat the SAS controller. c. Re-seat the backplane signal cable, backplane power cable, and SAS expander card (if the server has 12 drive bays). d. Re-seat the hard disk drive. e. Turn on the server and observe the activity of the hard disk drive LEDs. |

Displaying node mirror and hard drive status

The Storwize V7000 Unified system provides a method to check the node mirror status and hard drive status for each file module.

About this task

As the root user, you can run a perl script to verify whether or not mirroring is configured. By displaying the mirror status, you can view information that shows the location of each hard drive, the status values of each hard drive, and any errors, if applicable. If the mirror status is re-synchronizing, information that shows the percentage complete for the resynchronization is displayed.

Procedure

1. Ensure that you are logged into the file module as root.
2. To display mirror status and hard drive status, run the following perl script:

```
# /opt/IBM/sonas/bin/cnrspromptnode.pl -a -c "/opt/IBM/sonas/bin/cnrsQueryNodeDrives.pl"
```

File modules in this Storwize V7000 Unified Cluster

| Node | Node Name | Node Details |
|------|--------------|-----------------|
| 1. | mgmt001st001 | x3650m3 KQ186WX |
| 2. | mgmt002st001 | x3650m3 KQ186WV |

B. Back to Menu
Choice:

Figure 7. Selecting a file module to display node status

3. Select the number for a file module to display its status. For example, type **1** to select **mgmt001st001**. Press **Enter** to display the information in Figure 8 on page 66, which shows an example of a healthy status for the mirroring and drive status. The output shows a file module with two hard disk drives.

```

Mirror Information:
  Volume ID                : 3
  Status of volume         : Okay (OKY)
  RAID level               : 1
  Size (in MB)             : 285148
  Physical hard disks (Target ID) : 6 5
  Current operation        : None
  Physical disk I/Os       : Not quiesced

Drive Information:
Total number of drives found: 2

Target on ID #5
  Device is a Hard disk
  Enclosure #              : 1
  Slot #                   : 1
  Connector ID             : 1
  Target ID                : 5
  State                    : Online (ONL)
  Size (in MB)/(in sectors) : 286102/585937500
  Manufacturer             : IBM-ESXS
  Model Number             : XXXXXXXXXXXXX
  Firmware Revision        : XXXX
  Serial No                : XXXXXXXXXXXXXXXXXXXXX
  Drive Type               : SAS
  Protocol                 : SAS
  Error Information
    SMART Error Count      : none
    SMART ASC              : none
    SMART ASCQ             : none

Target on ID #6
  Device is a Hard disk
  Enclosure #              : 1
  Slot #                   : 0
  Connector ID             : 0
  Target ID                : 6
  State                    : Online (ONL)
  Size (in MB)/(in sectors) : 286102/585937500
  Manufacturer             : IBM-ESXS
  Model Number             : XXXXXXXXXXXXX
  Firmware Revision        : XXXX
  Serial No                : XXXXXXXXXXXXXXXXXXXXX
  Drive Type               : SAS
  Protocol                 : SAS
  Error Information
    SMART Error Count      : none
    SMART ASC              : none
    SMART ASCQ             : none

```

Figure 8. Displaying node status

- Review the section for **Mirror Information** and the value for **Status of volume**, then see Table 21 for the possible values for **Status of volume**.

Table 21. Status of volume

| Status of volume | Description |
|--------------------------------------|---|
| Okay (OKY) | The volume is Active and the drives are functioning correctly. The user data is protected if the volume is integrated mirroring or integrated mirroring enhanced. |
| Degraded (DGD) | The volume is Active. The user data is not fully protected due to a configuration change or drive failure. |
| Rebuilding (RBLD) or Resyncing (RSY) | A data resynchronization or rebuild might be in progress. |

Table 21. Status of volume (continued)

| Status of volume | Description |
|--------------------------|--|
| Inactive, Okay (OKY) | The volume is inactive and the drives are functioning correctly. The user data is protected if the current RAID level is RAID 1 (IM) or RAID 1E (IME). |
| Inactive, Degraded (DGD) | The volume is inactive and the user data is not fully protected due to a configuration change or drive failure; a data resync or rebuild might be in progress. |

5. Review the section for **Drive information** and the value for **State** Figure 8 on page 66, then see Table 22 to see the possible values for **State** of the drives.

Table 22. State of drives

| Status of drives | Description |
|-------------------|--|
| Online (ONL) | The drive is operational and is part of a logical drive. |
| Hot Spare (HSP) | The drive is a hot spare that is available for replacing a failed drive in an array. |
| Ready (RDY) | The drive is ready for use as a normal disk drive; or it is available to be assigned to a disk array or hot spare pool. |
| Available (AVL) | The drive might or might not be ready, and it is not suitable for inclusion in an array or hot spare pool (for example, it did not spin up, its block size is incorrect, or its media is removable). |
| Failed (FLD) | The drive was part of a logical drive or was a hot spare drive, and it has failed. It has been taken offline. |
| Standby (SBY) | This status is used to tag all non-hard disk drive devices. |
| Missing (MIS) | The hard drive might be removed. |
| Out of Sync (OSY) | A data resynchronization or rebuild might be in progress. |

6. See Figure 9 on page 68 for an example that shows that mirroring is re-synchronizing. If a hard disk drive is removed and reinserted, the array starts to resynchronize automatically.

Notelist: You can tell that the mirroring is re-synchronizing when the following conditions are true:

- **State of volume** is **Resyncing (RSY)**
- **Current operation** is **Synchronize**
- **Percentage complete** is displayed

A mirror/volume consists of two hard drives. In Figure 9 on page 68, the section for **Mirror Information** has a status line called **Physical hard disk (Target ID)**. The line shows which drives are part of the mirror/volume.

The **Status of volume** shows **Resyncing (RSY)**.

The mirror consists of **Physical hard disk (Target ID)** of **6** and **9**. Drive 9 is in a **State of Out of Sync (OSY)**. The **Mirror Information** will also show you the percentage complete for the resynchronization. For example, the percentage complete in Figure 9 on page 68 is **5.23%**.

```

Mirror Information:
Volume ID : 3 <---
Status of volume : Resyncing (RSY) <---
RAID level : 1
Size (in MB) : 285148
Physical hard disks (Target ID) : 6 5 <---
Current operation : Synchronize <---
Physical disk I/Os : Not quiesced
Volume size (in sectors) : 583983104
Number of remaining sectors : 553462899
Percentage complete : 5.23% <---

```

```

Drive Information:
Total number of drives found: 2

```

```

Target on ID #5
Device is a Hard disk
Enclosure # : 1
Slot # : 1
Connector ID : 1
Target ID : 5
State : Ready (RDY)
Size (in MB)/(in sectors) : 286102/585937500
Manufacturer : IBM-ESXS
Model Number : XXXXXXXXXXXXX
Firmware Revision : XXXX
Serial No : XXXXXXXXXXXXXXXXXXXXX
Drive Type : SAS
Protocol : SAS
Error Information
  SMART Error Count : none
  SMART ASC : none
  SMART ASCQ : none

```

```

Target on ID #6 <---
Device is a Hard disk
Enclosure # : 1
Slot # : 0
Connector ID : 0
Target ID : 6
State : Online (ONL)
Size (in MB)/(in sectors) : 286102/585937500
Manufacturer : IBM-ESXS
Model Number : XXXXXXXXXXXXX
Firmware Revision : XXXX
Serial No : XXXXXXXXXXXXXXXXXXXXX
Drive Type : SAS
Protocol : SAS
Error Information
  SMART Error Count : none
  SMART ASC : none
  SMART ASCQ : none

```

Figure 9. Example that shows that mirroring is re-synchronizing

If a drive were not synchronized, the status might appear like the status shown in Figure 10 on page 69:


```

Target on ID #5
Device is a Hard disk
Enclosure #           : 1
Slot #                : 1
Connector ID          : 1
Target ID             : 5
State                : Out of Sync (OSY) <---
Size (in MB)/(in sectors) : 286102/585937500
Manufacturer          : IBM-ESXS
Model Number         : XXXXXXXXXXXXX
Firmware Revision    : XXXX
Serial No            : XXXXXXXXXXXXXXXXXXXXX
Drive Type           : SAS
Protocol             : SAS
Error Information
  SMART Error Count   : none
  SMART ASC           : none
  SMART ASCQ         : none

```

Figure 10. Example that shows that a drive is not synchronized

7. See Figure 11 on page 70 for an example of status when there is no mirror. If mirroring is not enabled, the output under **Mirror Information** displays a message that says: **The mirror is not created/configured.** If the mirror is not created, refer to “Troubleshooting the System x3650” in the *IBM Storwize V7000 Unified Information Center* for information on launching the LSI configuration tool.

```

Mirror Information:
  NOTICE: The mirror is not created/configured.      <---

Drive Information:
Total number of drives found: 2
Target on ID #4
  Device is a Hard disk
  Enclosure #           : 1
  Slot #                : 1
  Connector ID          : 1
  Target ID             : 4
  State                 : Ready (RDY)
  Size (in MB)/(in sectors) : 286102/585937500
  Manufacturer          : IBM-ESXS
  Model Number          : XXXXXXXXXXXXX
  Firmware Revision     : XXXX
  Serial No             : XXXXXXXXXXXXXXXXXXXXX
  Drive Type            : SAS
  Protocol              : SAS
  Error Information
    SMART Error Count   : none
    SMART ASC           : none
    SMART ASCQ          : none

Target on ID #6
  Device is a Hard disk
  Enclosure #           : 1
  Slot #                : 0
  Connector ID          : 0
  Target ID             : 6
  State                 : Ready (RDY)
  Size (in MB)/(in sectors) : 286102/585937500
  Manufacturer          : IBM-ESXS
  Model Number          : XXXXXXXXXXXXX
  Firmware Revision     : XXXX
  Serial No             : XXXXXXXXXXXXXXXXXXXXX
  Drive Type            : SAS
  Protocol              : SAS
  Error Information
    SMART Error Count   : none
    SMART ASC           : none
    SMART ASCQ          : none

```

Figure 11. Example that shows that the mirror is not created

8. See Figure 12 on page 71 for an example of a Self-Monitoring, Analysis and Reporting Technology (**SMART**) error found for a hard drive. SMART adds monitoring and troubleshooting functionality by automatically checking a disk drive's health and reporting potential problems. If any **SMART** errors are detected for a hard drive, you can see the status in the section for **Error Information** as shown in Figure 12 on page 71.

Note: In Figure 12 on page 71 the hard disk drive with **Target ID #6** has a **ASC/ ASCQ** error of **05/00**.

For isolation and the repair of hard disk problems, refer to “Troubleshooting the System x3650” in the *IBM Storwize V7000 Unified Information Center*.

For a list of **SMART** (ASC/ASCQ) error codes and their descriptions, go to “SMART ASC/ASCQ error codes and messages” on page 71.

```

Mirror Information:
  Volume ID           : 4
  Status of volume    : Resyncing (RSY)
  RAID level         : 1
  Size (in MB)       : 285148
  Physical hard disks (Target ID) : 6 9
  Current operation   : Synchronize
  Physical disk I/Os  : Not quiesced

```

```

Drive Information:
Total number of drives found: 2

```

```

Target on ID #6
  Device is a Hard disk
  Enclosure #         : 1
  Slot #              : 0
  Connector ID        : 0
  Target ID           : 6
  State               : Online (ONL)
  Size (in MB)/(in sectors) : 286102/585937500
  Manufacturer        : IBM-ESXS
  Model Number        : MBD2300RC
  Firmware Revision   : SB19
  Serial No           : D009P9A01SJC
  Drive Type          : SAS
  Protocol            : SAS
  Error Information
    SMART Error Count : 1
    SMART ASC          : 05*      <---
    SMART ASCQ         : 00*      <---

```

*See Infocenter for SMART ASC/ASCQ error codes and messages

```

Target on ID #9
  Device is a Hard disk
  Enclosure #         : 1
  Slot #              : 1
  Connector ID        : 1
  Target ID           : 9
  State               : Out of Sync (OSY)
  Size (in MB)/(in sectors) : 286102/585937500
  Manufacturer        : IBM-ESXS
  Model Number        : MBD2300RC
  Firmware Revision   : SB19
  Serial No           : D009P990184N
  Drive Type          : SAS
  Protocol            : SAS
  Error Information
    SMART Error Count : none
    SMART ASC          : none
    SMART ASCQ         : none

```

Figure 12. Example of a SMART error

SMART ASC/ASCQ error codes and messages

Table 23 on page 72 shows descriptions of common Self-Monitoring, Analysis and Reporting Technology (SMART) ASC/ASCQ error codes that are classified for a direct access device. The ASC (additional sense code) and ASCQ (additional sense code qualifier) are known as SCSI additional sense data codes, as defined by SCSI standards. SMART adds monitoring and troubleshooting functionality by automatically checking a disk drive's health and reporting potential problems.

Note: Values in the following table such as “5D” are the same as the “5DH” displayed in the tool; some values such as “0” might have additional padding, so that “0” will be the same as “00.”

Table 23. SMART ASC/ASCQ error codes and messages

| ASC | ASCQ | Description |
|-----|------|---|
| 00 | 00 | NO ADDITIONAL SENSE INFORMATION |
| 00 | 06 | I/O PROCESS TERMINATED |
| 00 | 16 | OPERATION IN PROGRESS |
| 00 | 17 | CLEANING REQUESTED |
| 00 | 1D | ATA PASS THROUGH INFORMATION AVAILABLE |
| 00 | 1E | CONFLICTING SA CREATION REQUEST |
| 00 | 1F | LOGICAL UNIT TRANSITIONING TO ANOTHER POWER CONDITION |
| 01 | 00 | NO INDEX/SECTOR SIGNAL |
| 02 | 00 | NO SEEK COMPLETE |
| 03 | 00 | PERIPHERAL DEVICE WRITE FAULT |
| 04 | 00 | LOGICAL UNIT NOT READY |
| 04 | 01 | LOGICAL UNIT IS IN PROCESS OF BECOMING READY |
| 04 | 02 | LOGICAL UNIT NOT READY, INITIALIZING COMMAND REQUIRED |
| 04 | 03 | LOGICAL UNIT NOT READY, MANUAL INTERVENTION REQUIRED |
| 04 | 04 | LOGICAL UNIT NOT READY, FORMAT IN PROGRESS |
| 04 | 05 | LOGICAL UNIT NOT READY, REBUILD IN PROGRESS |
| 04 | 06 | LOGICAL UNIT NOT READY, RECALCULATION IN PROGRESS |
| 04 | 07 | LOGICAL UNIT NOT READY, OPERATION IN PROGRESS |
| 04 | 09 | LOGICAL UNIT NOT READY, SELF-TEST IN PROGRESS |
| 04 | 0A | LOGICAL UNIT NOT ACCESSIBLE, ASYMMETRIC ACCESS STATE TRANSITION |
| 04 | 0B | LOGICAL UNIT NOT ACCESSIBLE, TARGET PORT IN STANDBY STATE |
| 04 | 0C | LOGICAL UNIT NOT ACCESSIBLE, TARGET PORT IN UNAVAILABLE STATE |
| 04 | 10 | LOGICAL UNIT NOT READY, AUXILIARY MEMORY NOT ACCESSIBLE |
| 04 | 11 | LOGICAL UNIT NOT READY, NOTIFY (ENABLE SPINUP) REQUIRED |
| 04 | 13 | LOGICAL UNIT NOT READY, SA CREATION IN PROGRESS |
| 04 | 14 | LOGICAL UNIT NOT READY, SPACE ALLOCATION IN PROGRESS |
| 04 | 1A | LOGICAL UNIT NOT READY, START STOP UNIT COMMAND IN PROGRESS |
| 05 | 00 | LOGICAL UNIT DOES NOT RESPOND TO SELECTION |
| 06 | 00 | NO REFERENCE POSITION FOUND |
| 07 | 00 | MULTIPLE PERIPHERAL DEVICES SELECTED |
| 08 | 00 | LOGICAL UNIT COMMUNICATION FAILURE |
| 08 | 01 | LOGICAL UNIT COMMUNICATION TIME-OUT |
| 08 | 02 | LOGICAL UNIT COMMUNICATION PARITY ERROR |

Table 23. SMART ASC/ASCQ error codes and messages (continued)

| ASC | ASCQ | Description |
|-----|------|--|
| 08 | 03 | LOGICAL UNIT COMMUNICATION CRC ERROR (ULTRA-DMA/32) |
| 08 | 04 | UNREACHABLE COPY TARGET |
| 09 | 00 | TRACK FOLLOWING ERROR |
| 09 | 04 | HEAD SELECT FAULT |
| 0A | 00 | ERROR LOG OVERFLOW |
| 0B | 00 | WARNING |
| 0B | 01 | WARNING - SPECIFIED TEMPERATURE EXCEEDED |
| 0B | 02 | WARNING - ENCLOSURE DEGRADED |
| 0B | 03 | WARNING - BACKGROUND SELF-TEST FAILED |
| 0B | 04 | WARNING - BACKGROUND PRE-SCAN DETECTED MEDIUM ERROR |
| 0B | 05 | WARNING - BACKGROUND MEDIUM SCAN DETECTED MEDIUM ERROR |
| 0B | 06 | WARNING - NON-VOLATILE CACHE NOW VOLATILE |
| 0B | 07 | WARNING - DEGRADED POWER TO NON-VOLATILE CACHE |
| 0B | 08 | WARNING - POWER LOSS EXPECTED |
| 0C | 02 | WRITE ERROR - AUTO REALLOCATION FAILED |
| 0C | 03 | WRITE ERROR - RECOMMEND REASSIGNMENT |
| 0C | 04 | COMPRESSION CHECK MISCOMPARE ERROR |
| 0C | 05 | DATA EXPANSION OCCURRED DURING COMPRESSION |
| 0C | 06 | BLOCK NOT COMPRESSIBLE |
| 0C | 0B | AUXILIARY MEMORY WRITE ERROR |
| 0C | 0C | WRITE ERROR - UNEXPECTED UNSOLICITED DATA |
| 0C | 0D | WRITE ERROR - NOT ENOUGH UNSOLICITED DATA |
| 0D | 00 | ERROR DETECTED BY THIRD PARTY TEMPORARY INITIATOR |
| 0D | 01 | THIRD PARTY DEVICE FAILURE |
| 0D | 02 | COPY TARGET DEVICE NOT REACHABLE |
| 0D | 03 | INCORRECT COPY TARGET DEVICE TYPE |
| 0D | 04 | COPY TARGET DEVICE DATA UNDERRUN |
| 0D | 05 | COPY TARGET DEVICE DATA OVERRUN |
| 0E | 00 | INVALID INFORMATION UNIT |
| 0E | 01 | INFORMATION UNIT TOO SHORT |
| 0E | 02 | INFORMATION UNIT TOO LONG |
| 0E | 03 | INVALID FIELD IN COMMAND INFORMATION UNIT |
| 10 | 00 | ID CRC OR ECC ERROR |
| 10 | 01 | LOGICAL BLOCK GUARD CHECK FAILED |
| 10 | 02 | LOGICAL BLOCK APPLICATION TAG CHECK FAILED |
| 10 | 03 | LOGICAL BLOCK REFERENCE TAG CHECK FAILED |
| 11 | 00 | UNRECOVERED READ ERROR |
| 11 | 01 | READ RETRIES EXHAUSTED |

Table 23. SMART ASC/ASCQ error codes and messages (continued)

| ASC | ASCQ | Description |
|-----|------|---|
| 11 | 02 | ERROR TOO LONG TO CORRECT |
| 11 | 03 | MULTIPLE READ ERRORS |
| 11 | 04 | UNRECOVERED READ ERROR - AUTO REALLOCATE FAILED |
| 11 | 0A | MISCORRECTED ERROR |
| 11 | 0B | UNRECOVERED READ ERROR - RECOMMEND REASSIGNMENT |
| 11 | 0C | UNRECOVERED READ ERROR - RECOMMEND REWRITE THE DATA |
| 11 | 0D | DE-COMPRESSION CRC ERROR |
| 11 | 0E | CANNOT DECOMPRESS USING DECLARED ALGORITHM |
| 11 | 12 | AUXILIARY MEMORY READ ERROR |
| 11 | 13 | READ ERROR - FAILED RETRANSMISSION REQUEST |
| 11 | 14 | READ ERROR - LBA MARKED BAD BY APPLICATION CLIENT |
| 12 | 00 | ADDRESS MARK NOT FOUND FOR ID FIELD |
| 13 | 00 | ADDRESS MARK NOT FOUND FOR DATA FIELD |
| 14 | 00 | RECORDED ENTITY NOT FOUND |
| 14 | 01 | RECORD NOT FOUND |
| 14 | 05 | RECORD NOT FOUND - RECOMMEND REASSIGNMENT |
| 14 | 06 | RECORD NOT FOUND - DATA AUTO-REALLOCATED |
| 15 | 00 | RANDOM POSITIONING ERROR |
| 15 | 01 | MECHANICAL POSITIONING ERROR |
| 15 | 02 | POSITIONING ERROR DETECTED BY READ OF MEDIUM |
| 16 | 00 | DATA SYNCHRONIZATION MARK ERROR |
| 16 | 01 | DATA SYNC ERROR - DATA REWRITTEN |
| 16 | 02 | DATA SYNC ERROR - RECOMMEND REWRITE |
| 16 | 03 | DATA SYNC ERROR - DATA AUTO-REALLOCATED |
| 16 | 04 | DATA SYNC ERROR - RECOMMEND REASSIGNMENT |
| 17 | 00 | RECOVERED DATA WITH NO ERROR CORRECTION APPLIED |
| 17 | 01 | RECOVERED DATA WITH RETRIES |
| 17 | 02 | RECOVERED DATA WITH POSITIVE HEAD OFFSET |
| 17 | 03 | RECOVERED DATA WITH NEGATIVE HEAD OFFSET |
| 17 | 05 | RECOVERED DATA USING PREVIOUS SECTOR ID |
| 17 | 06 | RECOVERED DATA WITHOUT ECC - DATA AUTO-REALLOCATED |
| 17 | 07 | RECOVERED DATA WITHOUT ECC - RECOMMEND REASSIGNMENT |
| 17 | 08 | RECOVERED DATA WITHOUT ECC - RECOMMEND REWRITE |
| 17 | 09 | RECOVERED DATA WITHOUT ECC - DATA REWRITTEN |
| 18 | 00 | RECOVERED DATA WITH ERROR CORRECTION APPLIED |
| 18 | 01 | RECOVERED DATA WITH ERROR CORR. & RETRIES APPLIED |
| 18 | 02 | RECOVERED DATA - DATA AUTO-REALLOCATED |
| 18 | 05 | RECOVERED DATA - RECOMMEND REASSIGNMENT |

Table 23. SMART ASC/ASCQ error codes and messages (continued)

| ASC | ASCQ | Description |
|-----|------|---|
| 18 | 06 | RECOVERED DATA - RECOMMEND REWRITE |
| 18 | 07 | RECOVERED DATA WITH ECC - DATA REWRITTEN |
| 19 | 00 | DEFECT LIST ERROR |
| 19 | 01 | DEFECT LIST NOT AVAILABLE |
| 19 | 02 | DEFECT LIST ERROR IN PRIMARY LIST |
| 19 | 03 | DEFECT LIST ERROR IN GROWN LIST |
| 1A | 00 | PARAMETER LIST LENGTH ERROR |
| 1B | 00 | SYNCHRONOUS DATA TRANSFER ERROR |
| 1C | 00 | DEFECT LIST NOT FOUND |
| 1C | 01 | PRIMARY DEFECT LIST NOT FOUND |
| 1C | 02 | GROWN DEFECT LIST NOT FOUND |
| 1D | 00 | MISCOMPARE DURING VERIFY OPERATION |
| 1D | 01 | MISCOMPARE VERIFY OF UNMAPPED LBA |
| 1E | 00 | RECOVERED ID WITH ECC CORRECTION |
| 1F | 00 | PARTIAL DEFECT LIST TRANSFER |
| 20 | 00 | INVALID COMMAND OPERATION CODE |
| 20 | 01 | ACCESS DENIED - INITIATOR PENDING-ENROLLED |
| 20 | 02 | ACCESS DENIED - NO ACCESS RIGHTS |
| 20 | 03 | ACCESS DENIED - INVALID MGMT ID KEY |
| 20 | 08 | ACCESS DENIED - ENROLLMENT CONFLICT |
| 20 | 09 | ACCESS DENIED - INVALID LU IDENTIFIER |
| 20 | 0A | ACCESS DENIED - INVALID PROXY TOKEN |
| 20 | 0B | ACCESS DENIED - ACL LUN CONFLICT |
| 21 | 00 | LOGICAL BLOCK ADDRESS OUT OF RANGE |
| 21 | 01 | INVALID ELEMENT ADDRESS |
| 22 | 00 | ILLEGAL FUNCTION (USE 20 00, 24 00, OR 26 00) |
| 24 | 00 | INVALID FIELD IN CDB |
| 24 | 01 | CDB DECRYPTION ERROR |
| 24 | 08 | INVALID XCDB |
| 25 | 00 | LOGICAL UNIT NOT SUPPORTED |
| 26 | 00 | INVALID FIELD IN PARAMETER LIST |
| 26 | 01 | PARAMETER NOT SUPPORTED |
| 26 | 02 | PARAMETER VALUE INVALID |
| 26 | 03 | THRESHOLD PARAMETERS NOT SUPPORTED |
| 26 | 04 | INVALID RELEASE OF PERSISTENT RESERVATION |
| 26 | 05 | DATA DECRYPTION ERROR |
| 26 | 06 | TOO MANY TARGET DESCRIPTORS |
| 26 | 07 | UNSUPPORTED TARGET DESCRIPTOR TYPE CODE |
| 26 | 08 | TOO MANY SEGMENT DESCRIPTORS |
| 26 | 09 | UNSUPPORTED SEGMENT DESCRIPTOR TYPE CODE |

Table 23. SMART ASC/ASCQ error codes and messages (continued)

| ASC | ASCQ | Description |
|-----|------|--|
| 26 | 0A | UNEXPECTED INEXACT SEGMENT |
| 26 | 0B | INLINE DATA LENGTH EXCEEDED |
| 26 | 0C | INVALID OPERATION FOR COPY SOURCE OR DESTINATION |
| 26 | 0D | COPY SEGMENT GRANULARITY VIOLATION |
| 26 | 0E | INVALID PARAMETER WHILE PORT IS ENABLED |
| 27 | 00 | WRITE PROTECTED |
| 27 | 01 | HARDWARE WRITE PROTECTED |
| 27 | 02 | LOGICAL UNIT SOFTWARE WRITE PROTECTED |
| 27 | 07 | SPACE ALLOCATION FAILED WRITE PROTECT |
| 28 | 00 | NOT READY TO READY CHANGE, MEDIUM MAY HAVE CHANGED |
| 28 | 01 | IMPORT OR EXPORT ELEMENT ACCESSED |
| 29 | 00 | POWER ON, RESET, OR BUS DEVICE RESET OCCURRED |
| 29 | 01 | POWER ON OCCURRED |
| 29 | 02 | SCSI BUS RESET OCCURRED |
| 29 | 03 | BUS DEVICE RESET FUNCTION OCCURRED |
| 29 | 04 | DEVICE INTERNAL RESET |
| 29 | 05 | TRANSCEIVER MODE CHANGED TO SINGLE-ENDED |
| 29 | 06 | TRANSCEIVER MODE CHANGED TO LVD |
| 29 | 07 | I_T NEXUS LOSS OCCURRED |
| 2A | 00 | PARAMETERS CHANGED |
| 2A | 01 | MODE PARAMETERS CHANGED |
| 2A | 02 | LOG PARAMETERS CHANGED |
| 2A | 03 | RESERVATIONS PREEMPTED |
| 2A | 04 | RESERVATIONS RELEASED |
| 2A | 05 | REGISTRATIONS PREEMPTED |
| 2A | 06 | ASYMMETRIC ACCESS STATE CHANGED |
| 2A | 07 | IMPLICIT ASYMMETRIC ACCESS STATE TRANSITION FAILED |
| 2A | 08 | PRIORITY CHANGED |
| 2A | 09 | CAPACITY DATA HAS CHANGED |
| 2A | 0A | ERROR HISTORY I_T NEXUS CLEARED |
| 2A | 0B | ERROR HISTORY SNAPSHOT RELEASED |
| 2A | 10 | TIMESTAMP CHANGED |
| 2A | 14 | SA CREATION CAPABILITIES DATA HAS CHANGED |
| 2B | 00 | COPY CANNOT EXECUTE SINCE HOST CANNOT DISCONNECT |
| 2C | 00 | COMMAND SEQUENCE ERROR |
| 2C | 05 | ILLEGAL POWER CONDITION REQUEST |
| 2C | 07 | PREVIOUS BUSY STATUS |
| 2C | 08 | PREVIOUS TASK SET FULL STATUS |
| 2C | 09 | PREVIOUS RESERVATION CONFLICT STATUS |

Table 23. SMART ASC/ASCQ error codes and messages (continued)

| ASC | ASCQ | Description |
|-----|------|---|
| 2C | 0C | ORWRITE GENERATION DOES NOT MATCH |
| 2F | 00 | COMMANDS CLEARED BY ANOTHER INITIATOR |
| 2F | 01 | COMMANDS CLEARED BY POWER LOSS NOTIFICATION |
| 2F | 02 | COMMANDS CLEARED BY DEVICE SERVER |
| 30 | 00 | INCOMPATIBLE MEDIUM INSTALLED |
| 30 | 01 | CANNOT READ MEDIUM - UNKNOWN FORMAT |
| 30 | 02 | CANNOT READ MEDIUM - INCOMPATIBLE FORMAT |
| 30 | 03 | CLEANING CARTRIDGE INSTALLED |
| 30 | 04 | CANNOT WRITE MEDIUM - UNKNOWN FORMAT |
| 30 | 05 | CANNOT WRITE MEDIUM - INCOMPATIBLE FORMAT |
| 30 | 06 | CANNOT FORMAT MEDIUM - INCOMPATIBLE MEDIUM |
| 30 | 07 | CLEANING FAILURE |
| 30 | 0A | CLEANING REQUEST REJECTED |
| 31 | 00 | MEDIUM FORMAT CORRUPTED |
| 31 | 01 | FORMAT COMMAND FAILED |
| 32 | 00 | NO DEFECT SPARE LOCATION AVAILABLE |
| 32 | 01 | DEFECT LIST UPDATE FAILURE |
| 34 | 00 | ENCLOSURE FAILURE |
| 35 | 00 | ENCLOSURE SERVICES FAILURE |
| 35 | 01 | UNSUPPORTED ENCLOSURE FUNCTION |
| 35 | 02 | ENCLOSURE SERVICES UNAVAILABLE |
| 35 | 03 | ENCLOSURE SERVICES TRANSFER FAILURE |
| 35 | 04 | ENCLOSURE SERVICES TRANSFER REFUSED |
| 35 | 05 | ENCLOSURE SERVICES CHECKSUM ERROR |
| 37 | 00 | ROUNDED PARAMETER |
| 38 | 07 | THIN PROVISIONING SOFT THRESHOLD REACHED |
| 39 | 00 | SAVING PARAMETERS NOT SUPPORTED |
| 3A | 00 | MEDIUM NOT PRESENT |
| 3A | 01 | MEDIUM NOT PRESENT - TRAY CLOSED |
| 3A | 02 | MEDIUM NOT PRESENT - TRAY OPEN |
| 3A | 03 | MEDIUM NOT PRESENT - LOADABLE |
| 3A | 04 | MEDIUM NOT PRESENT - MEDIUM AUXILIARY MEMORY ACCESSIBLE |
| 3B | 0D | MEDIUM DESTINATION ELEMENT FULL |
| 3B | 0E | MEDIUM SOURCE ELEMENT EMPTY |
| 3B | 11 | MEDIUM MAGAZINE NOT ACCESSIBLE |
| 3B | 12 | MEDIUM MAGAZINE REMOVED |
| 3B | 13 | MEDIUM MAGAZINE INSERTED |
| 3B | 14 | MEDIUM MAGAZINE LOCKED |
| 3B | 15 | MEDIUM MAGAZINE UNLOCKED |

Table 23. SMART ASC/ASCQ error codes and messages (continued)

| ASC | ASCQ | Description |
|-----|------|---|
| 3D | 00 | INVALID BITS IN IDENTIFY MESSAGE |
| 3E | 00 | LOGICAL UNIT HAS NOT SELF-CONFIGURED YET |
| 3E | 01 | LOGICAL UNIT FAILURE |
| 3E | 02 | TIMEOUT ON LOGICAL UNIT |
| 3E | 03 | LOGICAL UNIT FAILED SELF-TEST |
| 3E | 04 | LOGICAL UNIT UNABLE TO UPDATE SELF-TEST LOG |
| 3F | 00 | TARGET OPERATING CONDITIONS HAVE CHANGED |
| 3F | 01 | MICROCODE HAS BEEN CHANGED |
| 3F | 02 | CHANGED OPERATING DEFINITION |
| 3F | 03 | INQUIRY DATA HAS CHANGED |
| 3F | 04 | COMPONENT DEVICE ATTACHED |
| 3F | 05 | DEVICE IDENTIFIER CHANGED |
| 3F | 06 | REDUNDANCY GROUP CREATED OR MODIFIED |
| 3F | 07 | REDUNDANCY GROUP DELETED |
| 3F | 08 | SPARE CREATED OR MODIFIED |
| 3F | 09 | SPARE DELETED |
| 3F | 0A | VOLUME SET CREATED OR MODIFIED |
| 3F | 0B | VOLUME SET DELETED |
| 3F | 0C | VOLUME SET DEASSIGNED |
| 3F | 0D | VOLUME SET REASSIGNED |
| 3F | 0E | REPORTED LUNS DATA HAS CHANGED |
| 3F | 0F | ECHO BUFFER OVERWRITTEN |
| 3F | 10 | MEDIUM LOADABLE |
| 3F | 11 | MEDIUM AUXILIARY MEMORY ACCESSIBLE |
| 3F | 12 | ISCSI IP ADDRESS ADDED |
| 3F | 13 | ISCSI IP ADDRESS REMOVED |
| 3F | 14 | ISCSI IP ADDRESS CHANGED |
| 40 | 00 | RAM FAILURE |
| 40 | NN | DIAGNOSTIC FAILURE ON COMPONENT NN |
| 41 | 00 | DATA PATH FAILURE |
| 42 | 00 | POWER-ON OR SELF-TEST FAILURE |
| 43 | 00 | MESSAGE ERROR |
| 44 | 00 | INTERNAL TARGET FAILURE |
| 44 | 71 | ATA DEVICE FAILED SET FEATURES |
| 45 | 00 | SELECT OR RESELECT FAILURE |
| 46 | 00 | UNSUCCESSFUL SOFT RESET |
| 47 | 00 | SCSI PARITY ERROR |
| 47 | 01 | DATA PHASE CRC ERROR DETECTED |
| 47 | 02 | SCSI PARITY ERROR DETECTED DURING ST DATA PHASE |
| 47 | 03 | INFORMATION UNIT IUCRC ERROR DETECTED |

Table 23. SMART ASC/ASCQ error codes and messages (continued)

| ASC | ASCQ | Description |
|-----|------|--|
| 47 | 04 | ASYNCHRONOUS INFORMATION PROTECTION ERROR DETECTED |
| 47 | 05 | PROTOCOL SERVICE CRC ERROR |
| 47 | 06 | PHY TEST FUNCTION IN PROGRESS |
| 47 | 7F | SOME COMMANDS CLEARED BY ISCSI PROTOCOL EVENT |
| 48 | 00 | INITIATOR DETECTED ERROR MESSAGE RECEIVED |
| 49 | 00 | INVALID MESSAGE ERROR |
| 4A | 00 | COMMAND PHASE ERROR |
| 4B | 00 | DATA PHASE ERROR |
| 4B | 01 | INVALID TARGET PORT TRANSFER TAG RECEIVED |
| 4B | 02 | TOO MUCH WRITE DATA |
| 4B | 03 | ACK/NAK TIMEOUT |
| 4B | 04 | NAK RECEIVED |
| 4B | 05 | DATA OFFSET ERROR |
| 4B | 06 | INITIATOR RESPONSE TIMEOUT |
| 4B | 07 | CONNECTION LOST |
| 4C | 00 | LOGICAL UNIT FAILED SELF-CONFIGURATION |
| 4D | NN | TAGGED OVERLAPPED COMMANDS (NN = TASK TAG) |
| 4E | 00 | OVERLAPPED COMMANDS ATTEMPTED |
| 53 | 00 | MEDIA LOAD OR EJECT FAILED |
| 53 | 02 | MEDIUM REMOVAL PREVENTED |
| 55 | 01 | SYSTEM BUFFER FULL |
| 55 | 02 | INSUFFICIENT RESERVATION RESOURCES |
| 55 | 03 | INSUFFICIENT RESOURCES |
| 55 | 04 | INSUFFICIENT REGISTRATION RESOURCES |
| 55 | 05 | INSUFFICIENT ACCESS CONTROL RESOURCES |
| 55 | 06 | AUXILIARY MEMORY OUT OF SPACE |
| 55 | 0B | INSUFFICIENT POWER FOR OPERATION |
| 5A | 00 | OPERATOR REQUEST OR STATE CHANGE INPUT |
| 5A | 01 | OPERATOR MEDIUM REMOVAL REQUEST |
| 5A | 02 | OPERATOR SELECTED WRITE PROTECT |
| 5A | 03 | OPERATOR SELECTED WRITE PERMIT |
| 5B | 00 | LOG EXCEPTION |
| 5B | 01 | THRESHOLD CONDITION MET |
| 5B | 02 | LOG COUNTER AT MAXIMUM |
| 5B | 03 | LOG LIST CODES EXHAUSTED |
| 5C | 00 | RPL STATUS CHANGE |
| 5C | 01 | SPINDLES SYNCHRONIZED |
| 5C | 02 | SPINDLES NOT SYNCHRONIZED |
| 5D | 00 | FAILURE PREDICTION THRESHOLD EXCEEDED |
| 5D | 05 | HARDWARE IMPENDING FAILURE HARD DISK DRIVE ERROR |

Table 23. SMART ASC/ASCQ error codes and messages (continued)

| ASC | ASCQ | Description |
|-----|------|--|
| 5D | 10 | HARDWARE IMPENDING FAILURE GENERAL HARD DRIVE FAILURE |
| 5D | 11 | HARDWARE IMPENDING FAILURE DRIVE ERROR RATE TOO HIGH |
| 5D | 12 | HARDWARE IMPENDING FAILURE DATA ERROR RATE TOO HIGH |
| 5D | 13 | HARDWARE IMPENDING FAILURE SEEK ERROR RATE TOO HIGH |
| 5D | 14 | HARDWARE IMPENDING FAILURE TOO MANY BLOCK REASSIGNS |
| 5D | 15 | HARDWARE IMPENDING FAILURE ACCESS TIMES TOO HIGH |
| 5D | 16 | HARDWARE IMPENDING FAILURE START UNIT TIMES TOO HIGH |
| 5D | 17 | HARDWARE IMPENDING FAILURE CHANNEL PARAMETRICS |
| 5D | 18 | HARDWARE IMPENDING FAILURE CONTROLLER DETECTED |
| 5D | 19 | HARDWARE IMPENDING FAILURE THROUGHPUT PERFORMANCE |
| 5D | 1A | HARDWARE IMPENDING FAILURE SEEK TIME PERFORMANCE |
| 5D | 1B | HARDWARE IMPENDING FAILURE SPIN-UP RETRY COUNT |
| 5D | 1C | HARDWARE IMPENDING FAILURE DRIVE CALIBRATION RETRY COUNT |
| 5D | 20 | CONTROLLER IMPENDING FAILURE GENERAL HARD DRIVE FAILURE |
| 5D | 21 | CONTROLLER IMPENDING FAILURE DRIVE ERROR RATE TOO HIGH |
| 5D | 22 | CONTROLLER IMPENDING FAILURE DATA ERROR RATE TOO HIGH |
| 5D | 23 | CONTROLLER IMPENDING FAILURE SEEK ERROR RATE TOO HIGH |
| 5D | 24 | CONTROLLER IMPENDING FAILURE TOO MANY BLOCK REASSIGNS |
| 5D | 25 | CONTROLLER IMPENDING FAILURE ACCESS TIMES TOO HIGH |
| 5D | 26 | CONTROLLER IMPENDING FAILURE START UNIT TIMES TOO HIGH |
| 5D | 27 | CONTROLLER IMPENDING FAILURE CHANNEL PARAMETRICS |
| 5D | 28 | CONTROLLER IMPENDING FAILURE CONTROLLER DETECTED |
| 5D | 29 | CONTROLLER IMPENDING FAILURE THROUGHPUT PERFORMANCE |
| 5D | 2A | CONTROLLER IMPENDING FAILURE SEEK TIME PERFORMANCE |
| 5D | 2B | CONTROLLER IMPENDING FAILURE SPIN-UP RETRY COUNT |
| 5D | 2C | CONTROLLER IMPENDING FAILURE DRIVE CALIBRATION RETRY COUNT |
| 5D | 30 | DATA CHANNEL IMPENDING FAILURE GENERAL HARD DRIVE FAILURE |
| 5D | 31 | DATA CHANNEL IMPENDING FAILURE DRIVE ERROR RATE TOO HIGH |
| 5D | 32 | DATA CHANNEL IMPENDING FAILURE DATA ERROR RATE TOO HIGH |
| 5D | 33 | DATA CHANNEL IMPENDING FAILURE SEEK ERROR RATE TOO HIGH |

Table 23. SMART ASC/ASCQ error codes and messages (continued)

| ASC | ASCQ | Description |
|-----|------|--|
| 5D | 34 | DATA CHANNEL IMPENDING FAILURE TOO MANY BLOCK REASSIGNS |
| 5D | 35 | DATA CHANNEL IMPENDING FAILURE ACCESS TIMES TOO HIGH |
| 5D | 36 | DATA CHANNEL IMPENDING FAILURE START UNIT TIMES TOO HIGH |
| 5D | 37 | DATA CHANNEL IMPENDING FAILURE CHANNEL PARAMETRICS |
| 5D | 38 | DATA CHANNEL IMPENDING FAILURE CONTROLLER DETECTED |
| 5D | 39 | DATA CHANNEL IMPENDING FAILURE THROUGHPUT PERFORMANCE |
| 5D | 3A | DATA CHANNEL IMPENDING FAILURE SEEK TIME PERFORMANCE |
| 5D | 3B | DATA CHANNEL IMPENDING FAILURE SPIN-UP RETRY COUNT |
| 5D | 3C | DATA CHANNEL IMPENDING FAILURE DRIVE CALIBRATION RETRY COUNT |
| 5D | 40 | SERVO IMPENDING FAILURE GENERAL HARD DRIVE FAILURE |
| 5D | 41 | SERVO IMPENDING FAILURE DRIVE ERROR RATE TOO HIGH |
| 5D | 42 | SERVO IMPENDING FAILURE DATA ERROR RATE TOO HIGH |
| 5D | 43 | SERVO IMPENDING FAILURE SEEK ERROR RATE TOO HIGH |
| 5D | 44 | SERVO IMPENDING FAILURE TOO MANY BLOCK REASSIGNS |
| 5D | 45 | SERVO IMPENDING FAILURE ACCESS TIMES TOO HIGH |
| 5D | 46 | SERVO IMPENDING FAILURE START UNIT TIMES TOO HIGH |
| 5D | 47 | SERVO IMPENDING FAILURE CHANNEL PARAMETRICS |
| 5D | 48 | SERVO IMPENDING FAILURE CONTROLLER DETECTED |
| 5D | 49 | SERVO IMPENDING FAILURE THROUGHPUT PERFORMANCE |
| 5D | 4A | SERVO IMPENDING FAILURE SEEK TIME PERFORMANCE |
| 5D | 4B | SERVO IMPENDING FAILURE SPIN-UP RETRY COUNT |
| 5D | 4C | SERVO IMPENDING FAILURE DRIVE CALIBRATION RETRY COUNT |
| 5D | 50 | SPINDLE IMPENDING FAILURE GENERAL HARD DRIVE FAILURE |
| 5D | 51 | SPINDLE IMPENDING FAILURE DRIVE ERROR RATE TOO HIGH |
| 5D | 52 | SPINDLE IMPENDING FAILURE DATA ERROR RATE TOO HIGH |
| 5D | 53 | SPINDLE IMPENDING FAILURE SEEK ERROR RATE TOO HIGH |
| 5D | 54 | SPINDLE IMPENDING FAILURE TOO MANY BLOCK REASSIGNS |
| 5D | 55 | SPINDLE IMPENDING FAILURE ACCESS TIMES TOO HIGH |
| 5D | 56 | SPINDLE IMPENDING FAILURE START UNIT TIMES TOO HIGH |
| 5D | 57 | SPINDLE IMPENDING FAILURE CHANNEL PARAMETRICS |
| 5D | 58 | SPINDLE IMPENDING FAILURE CONTROLLER DETECTED |
| 5D | 59 | SPINDLE IMPENDING FAILURE THROUGHPUT PERFORMANCE |
| 5D | 5A | SPINDLE IMPENDING FAILURE SEEK TIME PERFORMANCE |
| 5D | 5B | SPINDLE IMPENDING FAILURE SPIN-UP RETRY COUNT |
| 5D | 5C | SPINDLE IMPENDING FAILURE DRIVE CALIBRATION RETRY COUNT |

Table 23. SMART ASC/ASCQ error codes and messages (continued)

| ASC | ASCQ | Description |
|-----|------|--|
| 5D | 60 | FIRMWARE IMPENDING FAILURE GENERAL HARD DRIVE FAILURE |
| 5D | 61 | FIRMWARE IMPENDING FAILURE DRIVE ERROR RATE TOO HIGH |
| 5D | 62 | FIRMWARE IMPENDING FAILURE DATA ERROR RATE TOO HIGH |
| 5D | 63 | FIRMWARE IMPENDING FAILURE SEEK ERROR RATE TOO HIGH |
| 5D | 64 | FIRMWARE IMPENDING FAILURE TOO MANY BLOCK REASSIGNS |
| 5D | 65 | FIRMWARE IMPENDING FAILURE ACCESS TIMES TOO HIGH |
| 5D | 66 | FIRMWARE IMPENDING FAILURE START UNIT TIMES TOO HIGH |
| 5D | 67 | FIRMWARE IMPENDING FAILURE CHANNEL PARAMETRICS |
| 5D | 68 | FIRMWARE IMPENDING FAILURE CONTROLLER DETECTED |
| 5D | 69 | FIRMWARE IMPENDING FAILURE THROUGHPUT PERFORMANCE |
| 5D | 6A | FIRMWARE IMPENDING FAILURE SEEK TIME PERFORMANCE |
| 5D | 6B | FIRMWARE IMPENDING FAILURE SPIN-UP RETRY COUNT |
| 5D | 6C | FIRMWARE IMPENDING FAILURE DRIVE CALIBRATION RETRY COUNT |
| 5D | FF | FAILURE PREDICTION THRESHOLD EXCEEDED (FALSE) |
| 5E | 00 | LOW POWER CONDITION ON |
| 5E | 01 | IDLE CONDITION ACTIVATED BY TIMER |
| 5E | 02 | STANDBY CONDITION ACTIVATED BY TIMER |
| 5E | 03 | IDLE CONDITION ACTIVATED BY COMMAND |
| 5E | 04 | STANDBY CONDITION ACTIVATED BY COMMAND |
| 5E | 05 | IDLE_B CONDITION ACTIVATED BY TIMER |
| 5E | 06 | IDLE_B CONDITION ACTIVATED BY COMMAND |
| 5E | 07 | IDLE_C CONDITION ACTIVATED BY TIMER |
| 5E | 08 | IDLE_C CONDITION ACTIVATED BY COMMAND |
| 5E | 09 | STANDBY_Y CONDITION ACTIVATED BY TIMER |
| 5E | 0A | STANDBY_Y CONDITION ACTIVATED BY COMMAND |
| 65 | 00 | VOLTAGE FAULT |
| 67 | 0A | SET TARGET PORT GROUPS COMMAND FAILED |
| 67 | 0B | ATA DEVICE FEATURE NOT ENABLED |
| 74 | 08 | DIGITAL SIGNATURE VALIDATION FAILURE |
| 74 | 0C | UNABLE TO DECRYPT PARAMETER LIST |
| 74 | 10 | SA CREATION PARAMETER VALUE INVALID |
| 74 | 11 | SA CREATION PARAMETER VALUE REJECTED |
| 74 | 12 | INVALID SA USAGE |
| 74 | 30 | SA CREATION PARAMETER NOT SUPPORTED |
| 74 | 40 | AUTHENTICATION FAILED |
| 74 | 71 | LOGICAL UNIT ACCESS NOT AUTHORIZED |
| 74 | 79 | SECURITY CONFLICT IN TRANSLATED DEVICE |

Monitoring memory usage on a file module

Use this procedure to monitor memory usage on a file module.

Procedure

1. Log in to the file module and issue the command `lsperfdata -g memory_free_usage -t hour -n <node> | tail`.
2. If the file module shows diminishing memory and is reaching full capacity, initiate a file module reboot. See “Shut down or reboot a file module or clustered system” in the *IBM Storwize V7000 Unified Information Center*.

Errors and messages

System errors and messages can be triggered by conditions that range from simple typing errors to problems with system devices or programs.

About this task

Refer to the following topics for information about errors and messages.

Example

Note: For reference to or repair-information about non-Storwize V7000 Unified components, refer to the user documentation provided with those components.

Understanding error codes

The Storwize V7000 Unified error codes convey specific information in an alphanumeric sequence.

Tip: Search for error codes or event IDs by using EFS on the front. For 66012FC, for example, search on EFS66012FC. For a broader range of results, use a wildcard at the end and shorten the search appropriately. For example, search on EFS66012* or EFS660*, and so on.

Error code information

The following tables show the error code elements: ACDDDDx and provide information on what the various elements represent.

Table 24. Error code information.

Listing the code element information in the sequence of ACDDDDx.

| Code element | Information |
|--------------|---------------------------------------|
| A | Originating role information |
| C | Originating hardware or software code |
| DDDD | Specific error code |
| x | Severity of the error code |

Originating device information

The alphanumeric symbol or code in the A position indicates the originating device.

Table 25. Originating role information.

Listing devices for A in sequence ACDDDD.

| A = Originating role information in sequence ACDDDD | |
|---|-------------------------------|
| Code | Device |
| 0/1 | Management node error codes |
| 2/3 | File Module role error codes |
| 4/5 | Storage node role error codes |
| 6 | Storage node role error codes |
| 8 | Ethernet switch error codes. |

Originating specific hardware and software codes

The alphanumeric symbol in the C position represents the originating specific hardware and software code.

- For the originating file module and file module specific hardware code (code 0, 2, 4), go to Table 26.
- For the originating file module specific software code (code 1, 3, 5), go to Table 27 on page 85.
- For the storage enclosure hardware code (code 6), go to Table 28 on page 85.
- For the Ethernet switches (code 8): The Ethernet switches are a single field replaceable unit (FRU) and have no unique failing hardware code. The Ethernet switches use 0 for the originating specific hardware or software code.

Table 26. Originating file module and file module specific hardware code – Code 0, 2, 4.

Listing devices for variable C in the specific hardware code sequence of ABBCDDDD.

| C = Originating specific hardware code in sequence ABBCDDDD | |
|---|--|
| Code | Device |
| 0 | System x hardware (CPU, memory, powers supplies, etc.) |
| 1 | Built-in Ethernet port 0 |
| 2 | Built-in Ethernet port 1 |
| 3 | Built-in Ethernet port 2 |
| 4 | Built-in Ethernet port 3 |
| 5 | Optional Ethernet port 4 (Dual Port 10G card) |
| 6 | Optional Ethernet port 5 (Dual Port 10G card) |
| 7 | Optional Ethernet port 6 (Dual Port 10G card) |
| 8 | Optional Ethernet port 7 (Dual Port 10G card) |
| B | Fibre channel adapter 1 (both ports) – Storage node only |
| C | Fibre channel adapter 2 (both ports) – Storage node only |
| D | Bonded device (data0 mgmt0) |
| E | System x internal hard disk drives |

Table 27. Originating file module specific software code – Code 1, 3, 5.

Listing devices for variable C in the specific software code sequence of ABBCDDDD.

| C = Originating specific software code in sequence ABBCDDDD | |
|---|----------------|
| Code | Device |
| 0 | Red Hat Linux |
| 1 | GPFS |
| 2 | CIFS server |
| 3 | CTDB |
| 4 | SoFS |
| 5 | winbind |
| 6 | multipathd |
| 7 | nscd |
| 8 | sshd |
| 9 | httpd |
| A | vsftpd |
| B | nmbd |
| C | nfsd |
| D | cpu |
| E | multipath/disk |

Table 28. Storage enclosure hardware code – Code 6.

Listing devices for variable C in the specific hardware code sequence of ABBCDDDD.

| C = Originating specific software code in sequence ABBCDDDD | |
|---|--|
| Code | Device |
| 0 | Generic value for storage enclosure hardware |
| 1 | Disk drive in controller drawer |
| 2 | RAID controller card 0 |
| 3 | RAID controller card 1 |
| 4 | Power supply in controller drawer |
| 5 | RAID array/LUN issue in controller drawer |
| 6 | Disk drive in expansion drawer |
| 7 | Expansion fibre channel card 0 |
| 8 | Expansion fibre channel card 1 |
| 9 | Power supply in expansion drawer |
| A | RAID array/LUN issue in expansion drawer |

Severity of the error

The element *x* indicates the severity of the error. The value *x* can be:

- **A for Action:** GUI error messages. The user must perform a specific action.
- **C for Critical:** A critical error occurred which must be corrected by the user or system administrator.

- **D for Debug:** Used only for debug purposes.
- **I for Informational:** No operation action required.
- **W for Warning:** An error occurred that should be investigated and fixed.

Error code example

The following error code example illustrates how to interpret the alphanumeric elements based on the information provided above.

Error code and message:

4E0013C – Controller cache discarded due to firmware version incompatibility.

The following table shows the break down of the error code's alphanumeric elements:

Table 29. Error code break down.

This identifies the variables of 4 E 0 nnn x in the sequence of ACDXXXx.

| | |
|---------|------------------------------------|
| ACDXXXx | |
| 4E0013C | |
| 4 | File Module |
| E | System x internal hard disk drives |
| 0 | Originated with system checkout |
| nnn | Unique error code |
| x | Severity of the error |

Understanding event IDs

The Storwize V7000 Unified messages follow a specific format, which is detailed here.

About this task

Tip: Search for error codes or event IDs by using EFS on the front. For 66012FC, for example, search on EFS66012FC. For a broader range of results, use a wildcard at the end and shorten the search appropriately. For example, search on EFS66012* or EFS660*, and so on.

The format of system messages is *cnmnnx*. The elements—*cnmnnx*—represent the following information:

- The element *c* is an alphabetic identifier assigned to a component. The message component identifiers are assigned as follows:
 - A for Common or Access Layer
 - B for Space
 - C for GPFS
 - D for Wizards
 - F for Statistics
 - G for CLI
 - H for Health Center

I for Asynchronous Replication

J for SCM

L for HSM

AK for NDMP

- The element *nnnn* is a 4 digit message number
- The element *x* indicates the severity of the error. The value *x* can be:
 - A for Action:** GUI error messages. The user must perform a specific action.
 - C for Critical:** A critical error occurred which must be corrected by the user or system administrator.
 - D for Debug:** Used only for debug purposes.
 - I for Informational:** No operation action required.
 - W for Warning:** An error occurred that can cause problems in the future. The problem should be investigated and fixed.

File module hardware problems

This section helps you to identify and resolve file module hardware problems.

Removing and replacing parts for the 2073-720

About this task

Illustrations in this section might differ slightly from the actual hardware.

Table 30. Components identified as customer replaceable units (CRUs) and field replaceable units (FRUs)

| Types of replaceable parts | Explanation of each type of replaceable part | Procedures categorized under each type of replaceable part |
|--|--|--|
| Tier 1 Customer replaceable units (CRUs) | Tier 1 CRUs are your responsibility. If IBM installs a Tier 1 CRU at your request, you will be charged for the installation. Service agreements can be purchased so that you can ask IBM to replace these. | <p>“Removing the cover” on page 89</p> <p>“Installing the cover” on page 90</p> <p>“Removing the bezel” on page 91</p> <p>“Installing the bezel” on page 92</p> <p>“Disk drive cable connections” on page 95</p> <p>“Removing the battery” on page 97</p> <p>“Installing the battery” on page 101</p> <p>“Removing the air baffle” on page 103</p> <p>“Installing the air baffle” on page 104</p> <p>“Removing the fan bracket” on page 105</p> <p>“Installing the fan bracket” on page 106</p> <p>“Removing a PCI riser-card assembly” on page 107</p> <p>“Installing a PCI riser-card assembly” on page 108</p> <p>“Removing a PCI adapter from a PCI riser-card assembly” on page 109</p> <p>“Installing a PCI adapter in a PCI riser-card assembly” on page 111</p> <p>“Removing a Fibre Channel PCI adapter” on page 112</p> <p>“Installing a Fibre Channel PCI adapter” on page 112</p> <p>“Removing a 10-Gbps Ethernet adapter” on page 112</p> <p>“Installing a 10-Gbps Ethernet adapter” on page 113</p> <p>“Removing a hot-swap hard disk drive” on page 114</p> <p>“Installing a hot-swap hard disk drive” on page 115</p> <p>“Removing the DVD drive” on page 116</p> <p>“Installing the DVD drive” on page 118</p> <p>“Removing a memory module” on page 118</p> <p>“Installing a memory module” on page 119</p> <p>“Removing a hot-swap fan” on page 121</p> <p>“Installing a hot-swap fan” on page 123</p> <p>“Removing a hot-swap ac power supply” on page 124</p> <p>“Installing a hot-swap ac power supply” on page 125</p> <p>“Removing the operator information panel assembly” on page 128</p> <p>“Installing the operator information panel assembly” on page 128</p> <p>“Removing the hot-swap drive backplane” on page 129</p> <p>“Installing the hot-swap drive backplane” on page 130</p> <p>“Removing the 240 VA safety cover” on page 93</p> |

Table 30. Components identified as customer replaceable units (CRUs) and field replaceable units (FRUs) (continued)

| Types of replaceable parts | Explanation of each type of replaceable part | Procedures categorized under each type of replaceable part |
|--------------------------------|---|--|
| Field replaceable units (FRUs) | FRUs must be installed only by trained service technicians. | "Installing the 240 VA safety cover" on page 94 "Removing a microprocessor and heat sink" on page 131 "Installing a microprocessor and heat sink" on page 135 "Removing and replacing the thermal grease" on page 139 "Removing a heat-sink retention module" on page 141 "Installing a heat-sink retention module" on page 141 "Removing the system board" on page 142 "Installing the system board" on page 144 "Setting the machine type, model, and serial number" on page 147 |

Removing the cover

The following procedure is for a Tier 1 customer replaceable unit (CRU). Replacement of Tier 1 CRUs is your responsibility. If IBM installs a Tier 1 CRU at your request, you will be charged for the installation. Service agreements can be purchased so that you can ask IBM to replace these units.

About this task

To remove the cover, complete the following steps.

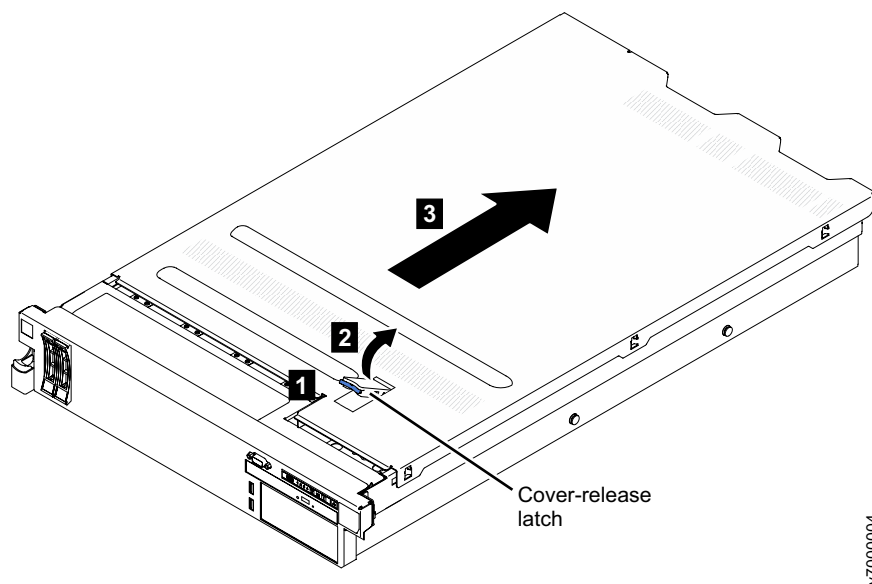


Figure 13. Removing the cover

Procedure

1. Read the safety information that begins on page Safety and “Installation guidelines” on page 60.
2. If you are planning to view the error LEDs that are on the system board and components, leave the file module connected to power and go directly to step 4.
3. If you are planning to install or remove a microprocessor, memory module, PCI adapter, battery, or other non-hot-swap optional device, follow the procedure in “Removing a file module and disconnecting power” on page 58 to suspend the file module from the cluster and shut it down and disconnect all power cords and external cables.
4. Press down on the left and right side latches and pull the file module out of the rack enclosure until both slide rails lock.

Note: You can reach the cables on the back of the file module when the file module is in the locked position.

5. Push the cover-release latch back **1**, then lift it up **2**.
6. Slide the cover back **3**, then lift the cover off the file module and set it aside.

Attention: For proper cooling and airflow, replace the cover before you turn on the file module. Operating the file module for extended periods of time (over 30 minutes) with the cover removed might damage the file module components.

7. If you are instructed to return the cover, follow all packaging instructions, and use any packaging materials for shipping that are supplied to you.

Installing the cover

The following procedure is for a Tier 1 customer replaceable unit (CRU).

Replacement of Tier 1 CRUs is your responsibility. If IBM installs a Tier 1 CRU at your request, you will be charged for the installation. Service agreements can be purchased so that you can ask IBM to replace these units.

About this task

To install the cover, complete the following steps.

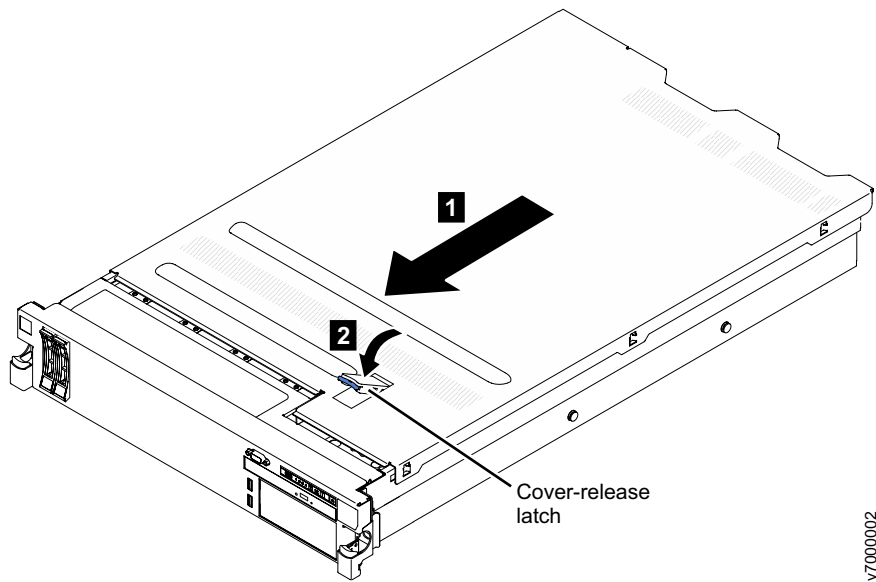


Figure 14. Installing the cover

Procedure

1. Make sure that all cables, adapters, and other components are installed and seated correctly and that there are no loose tools or parts inside the file module. Also, ensure that all internal cables are correctly routed.

Important: Before you slide the cover forward, make sure that all the tabs on the front, rear, and side of the cover engage the chassis correctly. If all the tabs do not engage the chassis correctly, it can cause difficulty in removing the cover later on.

2. Place the cover-release latch in the open (up) position.
3. Insert the bottom tabs of the top cover into the matching slots in the file module chassis.
4. Press down on the cover-release latch to lock the cover in place.
5. Slide the file module into the rack until it latches.
6. Follow the steps at the end of the procedure in “Removing a file module and disconnecting power” on page 58 to suspend the file module to reconnect the file module and resume its use in the cluster.

Removing the bezel

The following procedure is for a Tier 1 customer replaceable unit (CRU). Replacement of Tier 1 CRUs is your responsibility. If IBM installs a Tier 1 CRU at your request, you will be charged for the installation. Service agreements can be purchased so that you can ask IBM to replace these units.

About this task

To remove the bezel, complete the following steps.

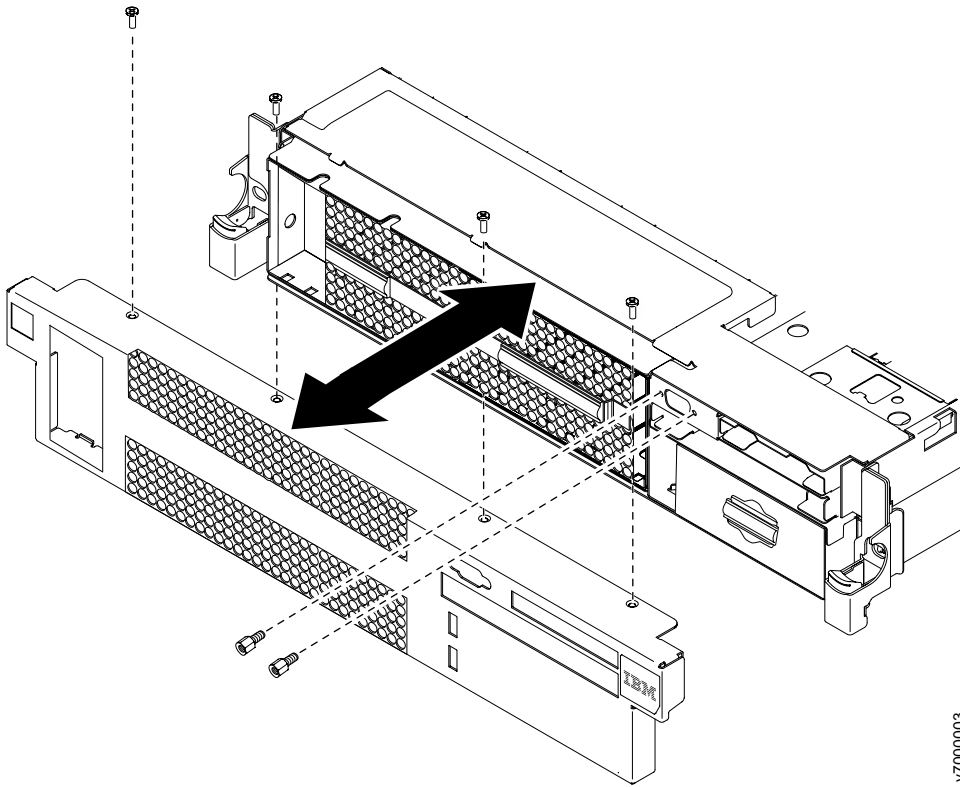


Figure 15. Removing the bezel

Procedure

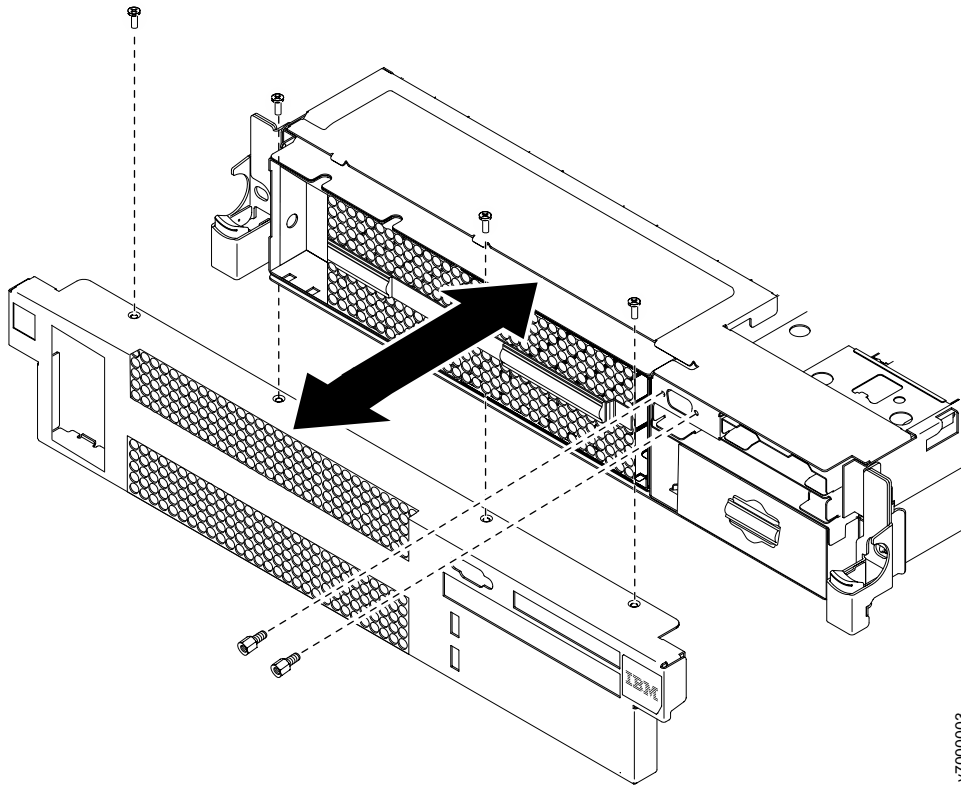
1. Read the safety information that begins on page Safety and “Installation guidelines” on page 60.
2. Remove all the cables that are connected to the front of the file module.
3. Remove the cable retention bolts from the VGA port.
4. Remove the screws from the bezel.
5. Rotate the top of the bezel away from the file module.

Installing the bezel

The following procedure is for a Tier 1 customer replaceable unit (CRU). Replacement of Tier 1 CRUs is your responsibility. If IBM installs a Tier 1 CRU at your request, you will be charged for the installation. Service agreements can be purchased so that you can ask IBM to replace these units.

About this task

To install the bezel, complete the following steps.



v7000003

Figure 16. Installing the bezel

Procedure

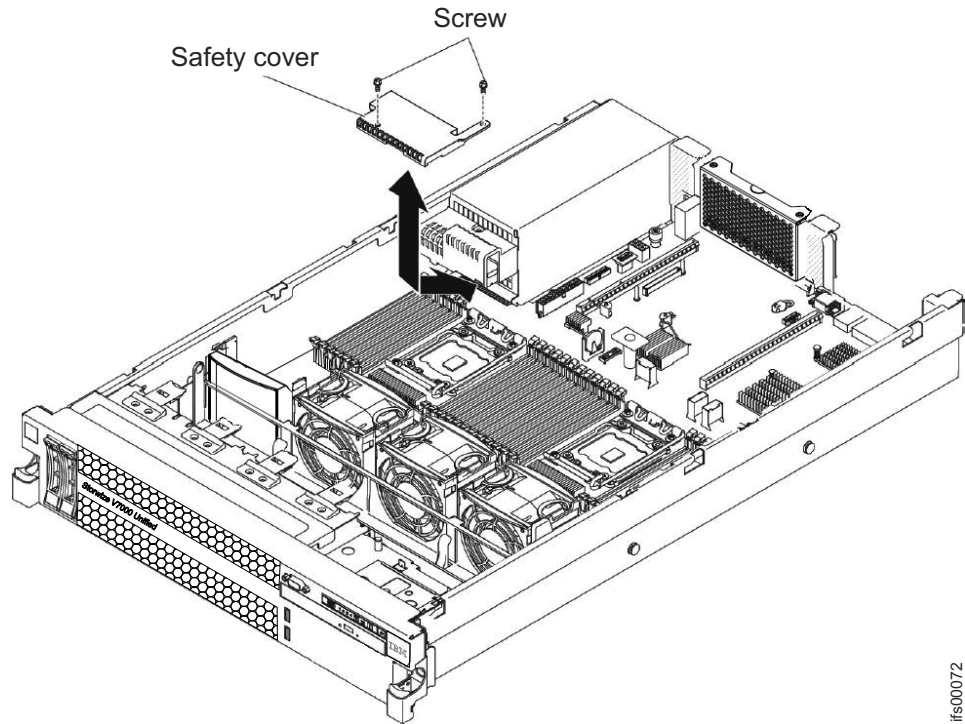
1. Insert the tabs on the bottom of the bezel into the slots on the underside of the chassis and attach it with the screws.
2. Connect any cables that you previously removed from the front of the file module.

Removing the 240 VA safety cover

The following procedure is for a Tier 1 customer replaceable unit (CRU). Replacement of Tier 1 CRUs is your responsibility. If IBM installs a Tier 1 CRU at your request, you will be charged for the installation. Service agreements can be purchased so that you can ask IBM to replace these units.

To remove the 240 VA safety cover, complete the following steps:

1. Read the Safety information and “Installation guidelines” on page 60.
2. Follow the procedure in “Removing a file module and disconnecting power” on page 58 to suspend the file module from the cluster and shut it down, and then disconnect all power cords and external cables.
3. Pull the file module out of the rack.
4. Remove the file module cover (see “Removing the cover” on page 89).



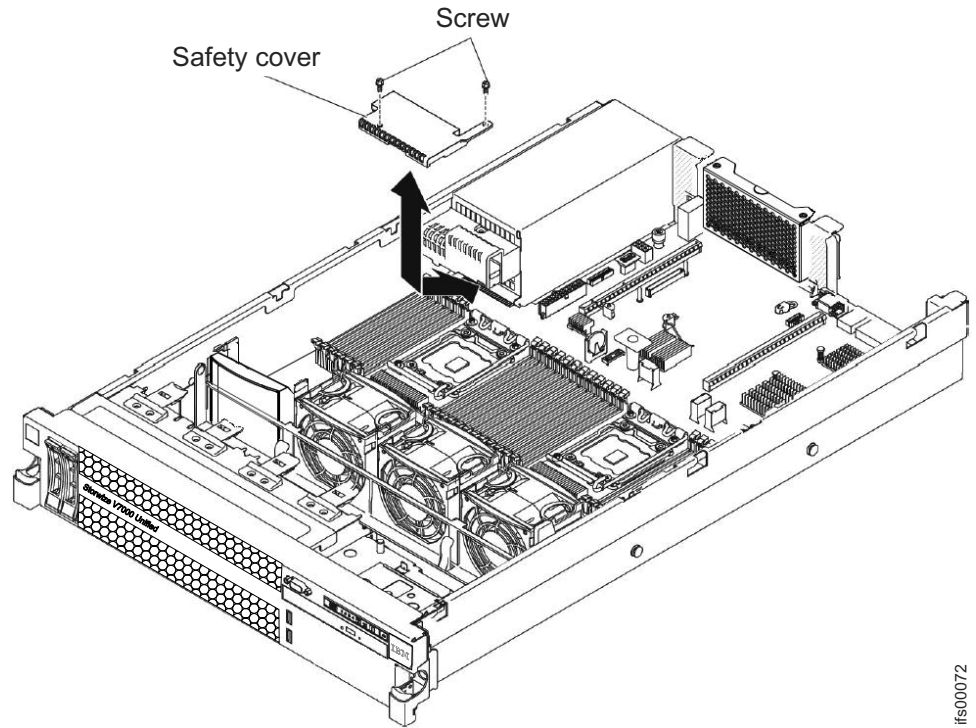
ifs00072

5. Remove the screw from the safety cover.
6. Disconnect the hard disk drive backplane power cables from the connector in front of the safety cover.
7. Slide the cover forward to disengage it from the system board, and then lift it out of the file module.
8. If you are instructed to return the 240 VA safety cover, follow all packaging instructions, and use any packaging materials for shipping that are supplied to you.

Installing the 240 VA safety cover

The following procedure is for a Tier 1 customer replaceable unit (CRU). Replacement of Tier 1 CRUs is your responsibility. If IBM installs a Tier 1 CRU at your request, you will be charged for the installation. Service agreements can be purchased so that you can ask IBM to replace these units.

To install the 240 VA safety cover, complete the following steps.

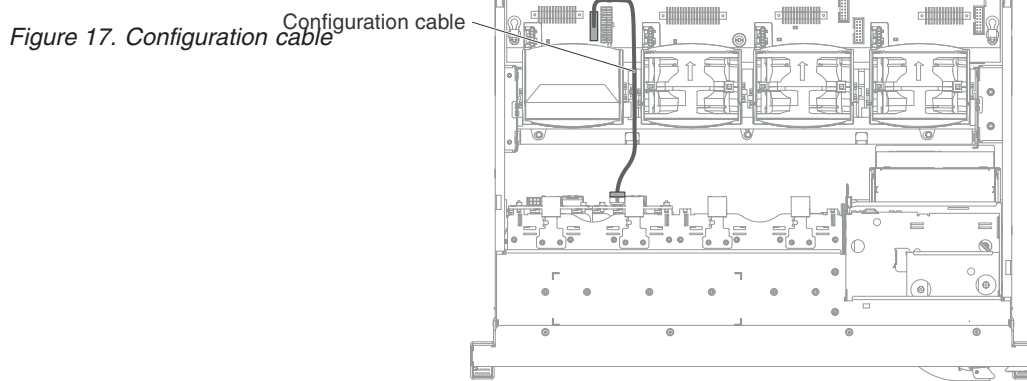


1. Line up and insert the tabs on the bottom of the safety cover into the slots on the system board.
2. Slide the safety cover toward the back of the file module until it is secure.
3. Connect the hard disk drive backplane power cables to the connector in front of the safety cover.
4. Install the screw into the safety cover.
5. Install the file module cover (see "Installing the cover" on page 90).
6. Slide the file module into the rack.
7. Follow the steps at the end of the procedure "Removing a file module and disconnecting power" on page 58 to reconnect the file module and resume its use in the cluster.

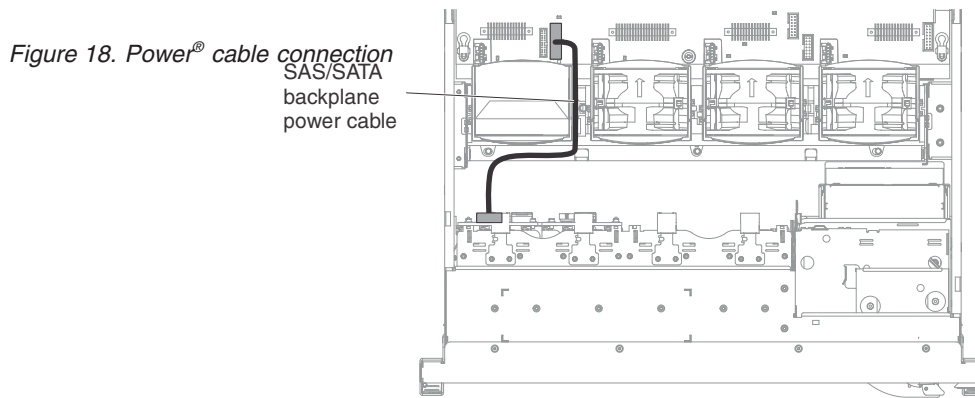
Disk drive cable connections

Use the information described here to know about the cabling structure for the 8 x 2.5-inch hot-swap drive bays.

The following illustration shows the cabling information for the configuration cable in the file module:



The following illustration shows the internal routing for the hard disk drive power cable.

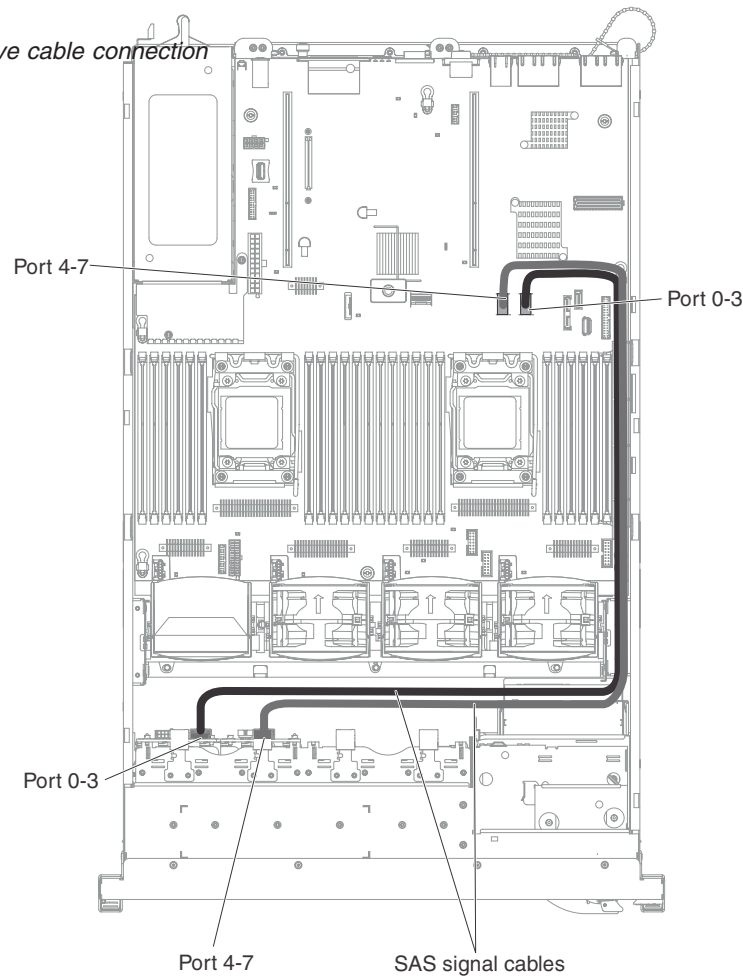


The following illustration shows the internal routing and connectors for the two SAS signal cables.

Note:

1. To connect the SAS signal cables, make sure that you first connect the signal cable, and then the power cable and configuration cable.
2. To disconnect the SAS signal cables, make sure that you first disconnect the power cable, and then the signal cable and configuration cable.

Figure 19. Hard disk drive cable connection



Removing the battery

The following procedure is for a Tier 1 customer replaceable unit (CRU). Replacement of Tier 1 CRUs is your responsibility. If IBM installs a Tier 1 CRU at your request, you will be charged for the installation. Service agreements can be purchased so that you can ask IBM to replace these units.

About this task

Note: Before running a procedure, refer to “Removing a file module to perform a maintenance action” on page 57.

The following notes describe information that you must consider when replacing the battery:

- IBM has designed this product with your safety in mind. The lithium battery must be handled correctly to avoid possible danger. If you replace the battery, you must adhere to the following instructions.

Note: In the U. S., call 1-800-IBM-4333 for information about battery disposal.

- If you replace the original lithium battery with a heavy-metal battery or a battery with heavy-metal components, be aware of the following environmental consideration. Batteries and accumulators that contain heavy metals must not be

disposed of with normal domestic waste. They will be taken back free of charge by the manufacturer, distributor, or representative, to be recycled or disposed of in a proper manner.

- To order replacement batteries, call 1-800-IBM-SERV within the United States, and 1-800-465-7999 or 1-800-465-6666 within Canada. Outside the US and Canada, call your support center or IBM Business Partner.

Note: After you replace the battery, you must reconfigure the file module and reset the system date and time.

Statement 2



CAUTION:

When you are replacing the lithium battery, use only IBM Part Number 33F8354 or an equivalent type battery that is recommended by the manufacturer. If your system has a module that contains a lithium battery, replace it only with the same module type made by the same manufacturer. The battery contains lithium and can explode if not properly used, handled, or disposed of.

Do not:

- Throw or immerse into water
- Heat to more than 100°C (212°F)
- Repair or disassemble

Dispose of the battery as required by local ordinances or regulations.

To remove the battery, complete the following steps:

Procedure

1. Read the safety information that begins on page Safety and “Installation guidelines” on page 60.
2. Follow any special handling and installation instructions that come with the battery.
3. Follow the procedure in “Removing a file module and disconnecting power” on page 58 to suspend the file module from the cluster and shut it down and disconnect all power cords and external cables.
4. Slide the file module out of the rack.
5. Remove the cover. For more information, see Removing the cover.
6. Disconnect any internal cables, as necessary.
7. Locate the battery on the system board.
8. Remove the battery:
 - a. If there is a rubber cover on the battery holder, use your fingers to lift the battery cover from the battery connector.
 - b. Use one finger to push the battery horizontally away from the PCI riser card in slot 2 and out of its housing.

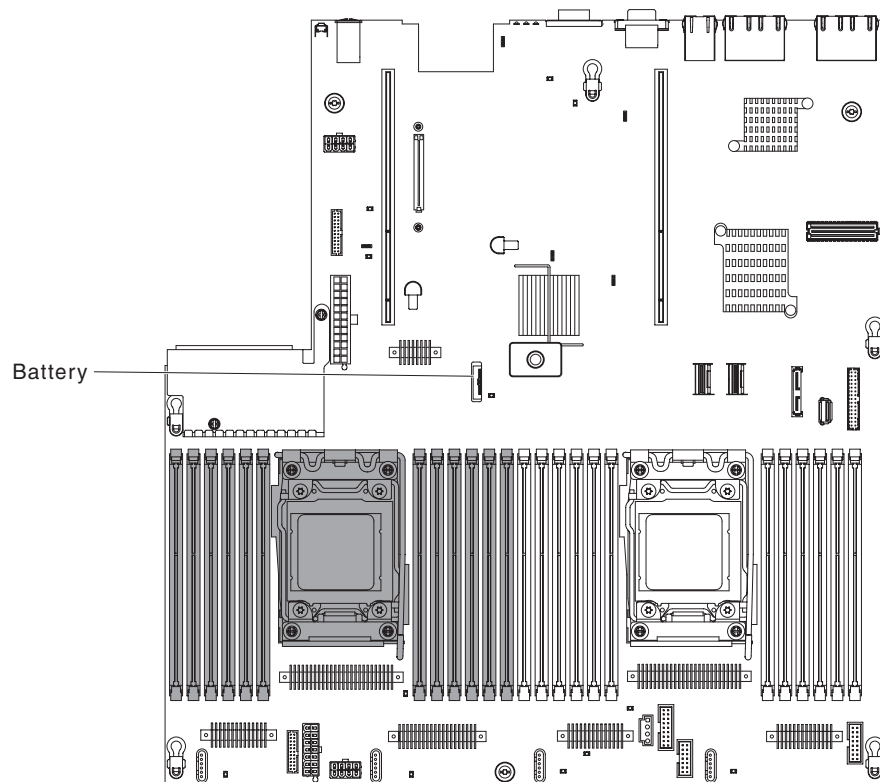


Figure 20. Removing the battery

Attention: You must not tilt or push the battery by using excessive force.
 c. Use your thumb and index finger to lift the battery from the socket.

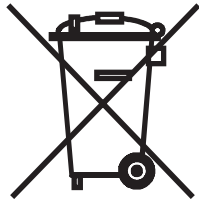
Attention: Do not lift the battery by using excessive force. Failing to remove the battery properly might damage the socket on the system board. Any damage to the socket might require replacing the system board.

9. Dispose of the battery as required by local ordinances or regulations. For more information, see the *IBM Environmental Notices and User's Guide* on the IBM Documentation CD.

Battery return program: This product may contain sealed lead acid, nickel cadmium, nickel metal hydride, lithium, or lithium ion battery. Consult your user manual or service manual for specific battery information. The battery must be recycled or disposed of properly. Recycling facilities may not be available in your area. For information on disposal of batteries outside the United States, go to www.ibm.com/ibm/environment/products/index.shtml or contact your local waste disposal facility.

In the United States, IBM has established a return process for reuse, recycling, or proper disposal of used IBM sealed lead acid, nickel cadmium, nickel metal hydride, and other battery packs from IBM Equipment. For information on proper disposal of these batteries, contact IBM at 1-800-426-4333. Please have the IBM part number listed on the battery available prior to your call.

The following applies for countries within the European Union:



For Taiwan:



Please recycle batteries.

廢電池請回收

Batteries or packaging for batteries are labeled in accordance with European Directive 2006/66/EC concerning batteries and accumulators and waste batteries and accumulators. The Directive determines the framework for the return and recycling of used batteries and accumulators as applicable throughout the European Union. This label is applied to various batteries to indicate that the battery is not to be thrown away, but rather reclaimed upon end of life per this Directive.

Les batteries ou emballages pour batteries sont étiquetés conformément aux directives européennes 2006/66/EC, norme relative aux batteries et accumulateurs en usage et aux batteries et accumulateurs usés. Les directives déterminent la marche à suivre en vigueur dans l'Union Européenne pour le retour et le recyclage des batteries et accumulateurs usés. Cette étiquette est appliquée sur diverses batteries pour indiquer que la batterie ne doit pas être mise au rebut mais plutôt récupérée en fin de cycle de vie selon cette norme.

バッテリーあるいはバッテリー用のパッケージには、EU 諸国に対する廃電気電子機器指令 2006/66/EC のラベルが貼られています。この指令は、バッテリーと蓄電池、および廃棄バッテリーと蓄電池に関するものです。この指令は、使用済みバッテリーと蓄電池の回収とリサイクルの骨子を定めているもので、EU 諸国にわたって適用されます。このラベルは、使用済みになったときに指令に従って適正な処理をする必要があることを知らせるために種々のバッテリーに貼られています。

In accordance with the European Directive 2006/66/EC, batteries and accumulators are labeled to indicate that they are to be collected separately and recycled at end of life. The label on the battery may also include a chemical symbol for the metal concerned in the battery (Pb for lead, Hg for mercury and Cd for cadmium). Users of batteries and accumulators must not dispose of batteries and accumulators as unsorted municipal waste, but use the collection framework available to customers for the return, recycling and treatment of batteries and accumulators. Customer participation is important to minimize any potential effects of batteries and accumulators on the environment and human health due to the potential presence of hazardous substances. For proper collection and treatment, contact your local IBM representative.

Spain

This notice is provided in accordance with Royal Decree 106/2008 of Spain: The retail price of batteries, accumulators and power cells includes the cost of the environmental management of their waste.

Perchlorate Material - California

Special handling may apply. See <http://www.dtsc.ca.gov/hazardouswaste/perchlorate> for more information.

The foregoing notice is provided in accordance with California Code of Regulations Title 22, Division 4.5 Chapter 33. Best Management Practices for Perchlorate Materials. This product, part or both may include a lithium manganese dioxide battery which contains a perchlorate substance.

Installing the battery

The following procedure is for a Tier 1 customer replaceable unit (CRU). Replacement of Tier 1 CRUs is your responsibility. If IBM installs a Tier 1 CRU at your request, you will be charged for the installation. Service agreements can be purchased so that you can ask IBM to replace these units.

About this task

The following notes describe information that you must consider when you replace the battery in the file module.

- You must replace the battery with a lithium battery of the same type from the same manufacturer.
- After you replace the battery, you must reconfigure the file module and reset the system date and time.
- To avoid possible danger, read and follow the following safety statement.
- To order replacement batteries, call 1-800-IBM-SERV within the United States, and 1-800-465-7999 or 1-800-465-6666 within Canada. Outside the US and Canada, call your support center or IBM Business Partner.

Statement 2



CAUTION:

When you are replacing the lithium battery, use only IBM Part Number 33F8354 or an equivalent type battery that is recommended by the manufacturer. If your system has a module that contains a lithium battery, replace it only with the same module type made by the same manufacturer. The battery contains lithium and can explode if not properly used, handled, or disposed of.

Do not:

- Throw or immerse into water
- Heat to more than 100°C (212°F)
- Repair or disassemble

Dispose of the battery as required by local ordinances or regulations.

For more information, see the *IBM Environmental Notices and User's Guide* on the *IBM Documentation CD*.

To install the replacement battery, complete the following steps:

Procedure

1. Follow any special handling and installation instructions that come with the replacement battery.
2. Insert the new battery:
 - a. Tilt the battery so that you can insert it into the socket on the side opposite the battery clip.

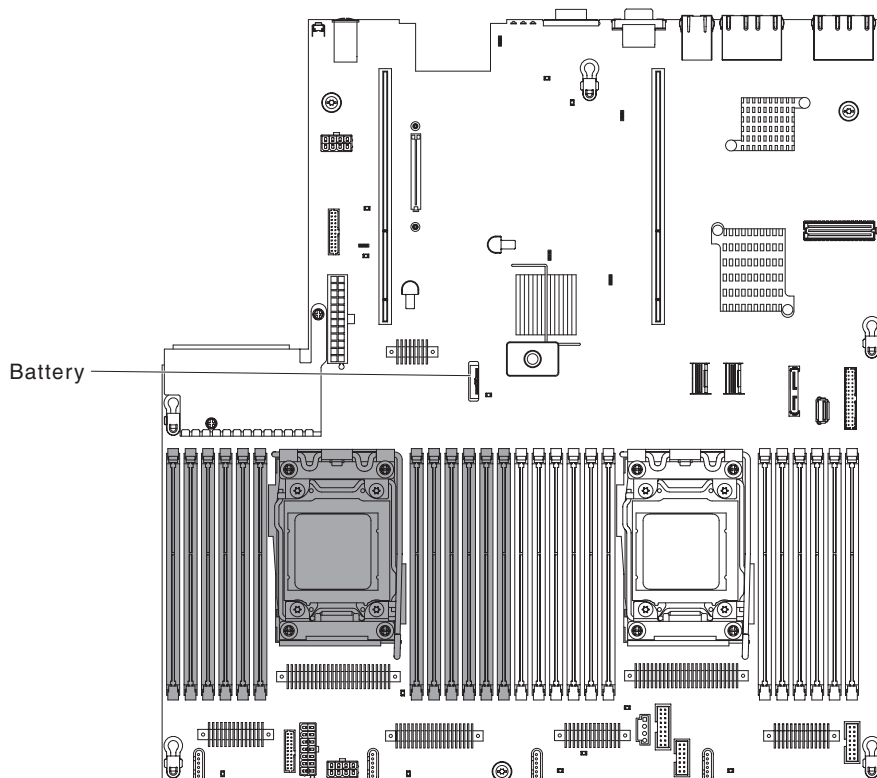


Figure 21. Installing the battery

- b. Press the battery down into the socket until it clicks into place. Make sure that the battery clip holds the battery securely.
 - c. If you removed a rubber cover from the battery holder, use your fingers to install the battery cover on top of the battery connector.
3. Reinstall any adapters that you removed.
 4. Reconnect the internal cables that you disconnected.
 5. Install the cover, as described in *Installing the cover*.
 6. Slide the file module into the rack.
 7. Follow the steps at the end of the procedure in "Removing a file module and disconnecting power" on page 58 to suspend the file module to reconnect the file module and resume its use in the cluster.

Note: You must wait approximately 2.5 minutes after you connect the power cord of the file module to an electrical outlet before the power-control button becomes active.

8. Start the Setup utility and reset the configuration.
 - Set the system date and time.
 - Set the power-on password.
 - Reconfigure the file module.

Removing the air baffle

The following procedure is for a Tier 1 customer replaceable unit (CRU). Replacement of Tier 1 CRUs is your responsibility. If IBM installs a Tier 1 CRU at your request, you will be charged for the installation. Service agreements can be purchased so that you can ask IBM to replace these units.

About this task

When you work with some replaceable devices, you must first remove the DIMM air baffle to access certain components or connectors on the system board.

To remove the DIMM air baffle, complete the following steps.

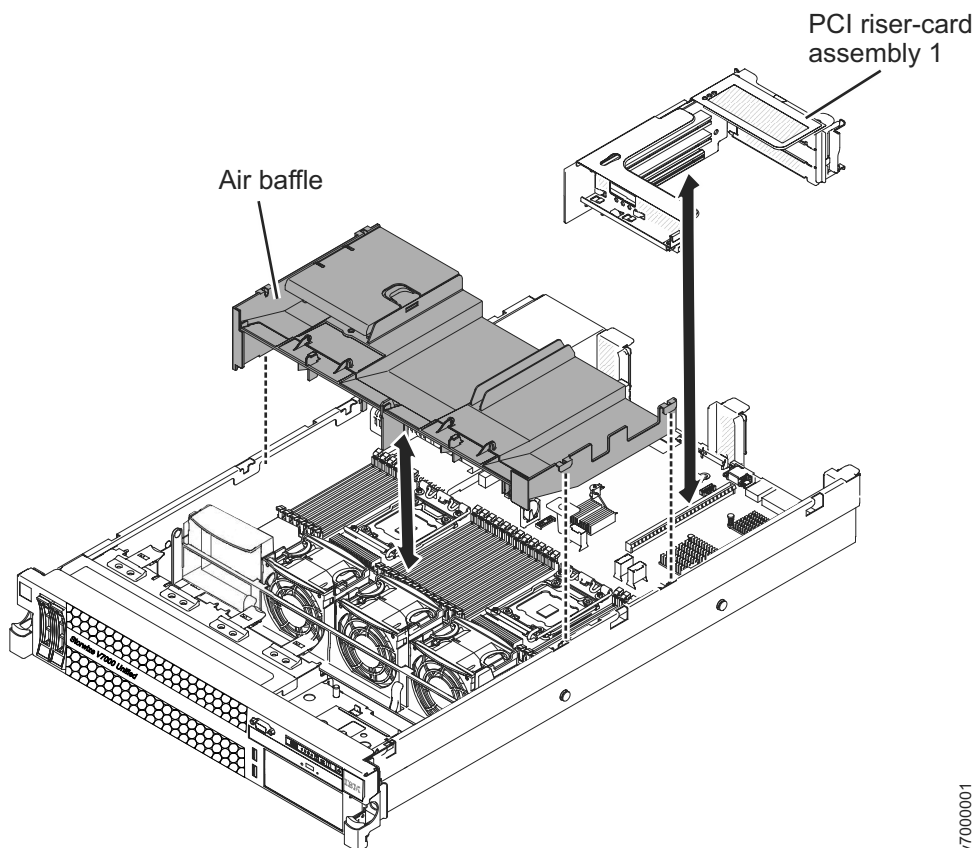


Figure 22. Removing the air baffle

Procedure

1. Read the safety information that begins on page Safety and "Installation guidelines" on page 60.

2. Follow the procedure in “Removing a file module and disconnecting power” on page 58 to suspend the file module from the cluster and shut it down and disconnect all power cords and external cables.
3. Remove the cover. For more information, see Removing the cover.
4. If there is any full-height, full-length card, remove riser-card assembly 1. For more information, see Removing a PCI riser-card assembly.
5. Place your fingers under the front and back of the top of the air baffle, and then lift the air baffle out of the file module.

Attention: For proper cooling and airflow, replace all the air baffles before you turn on the file module. If you operate the file module with any air baffle removed, it might cause damages to the file module components.

Installing the air baffle

The following procedure is for a Tier 1 customer replaceable unit (CRU). Replacement of Tier 1 CRUs is your responsibility. If IBM installs a Tier 1 CRU at your request, you will be charged for the installation. Service agreements can be purchased so that you can ask IBM to replace these units.

About this task

To install the DIMM air baffle, complete the following steps.

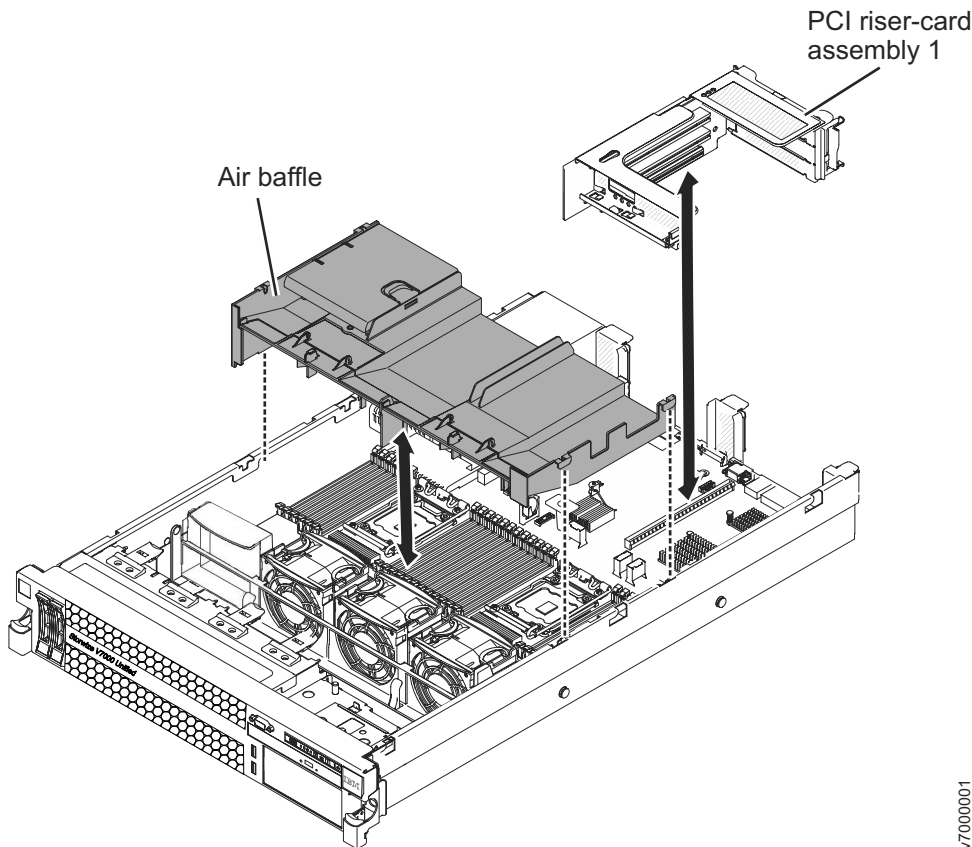


Figure 23. Installing the air baffle

Procedure

1. Read the safety information that begins on page Safety and “Installation guidelines” on page 60.

2. Align the air baffle pins with the two baffle pin slots on both sides of chassis.
3. Lower the air baffle into place, making sure that all cables are out of the way. Press the air baffle down until it is securely seated.

Note: Close the retaining clip on each end of the DIMM connector before you install the air baffle.

4. Install the cover. For more information, see *Installing the cover*.
5. Slide the file module into the rack.
6. Follow the steps at the end of the procedure in “Removing a file module and disconnecting power” on page 58 to suspend the file module to reconnect the file module and resume its use in the cluster.

Results

Attention: For proper cooling and airflow, replace all air baffles before you turn on the file module. Operating the file module with any air baffle removed might damage file module components.

Removing the fan bracket

The following procedure is for a Tier 1 customer replaceable unit (CRU). Replacement of Tier 1 CRUs is your responsibility. If IBM installs a Tier 1 CRU at your request, you will be charged for the installation. Service agreements can be purchased so that you can ask IBM to replace these units.

About this task

To replace some components or to create working room, you might have to remove the fan-bracket assembly.

Note: To remove or install a fan, it is not necessary to remove the fan bracket.

To remove the fan bracket, complete the following steps.

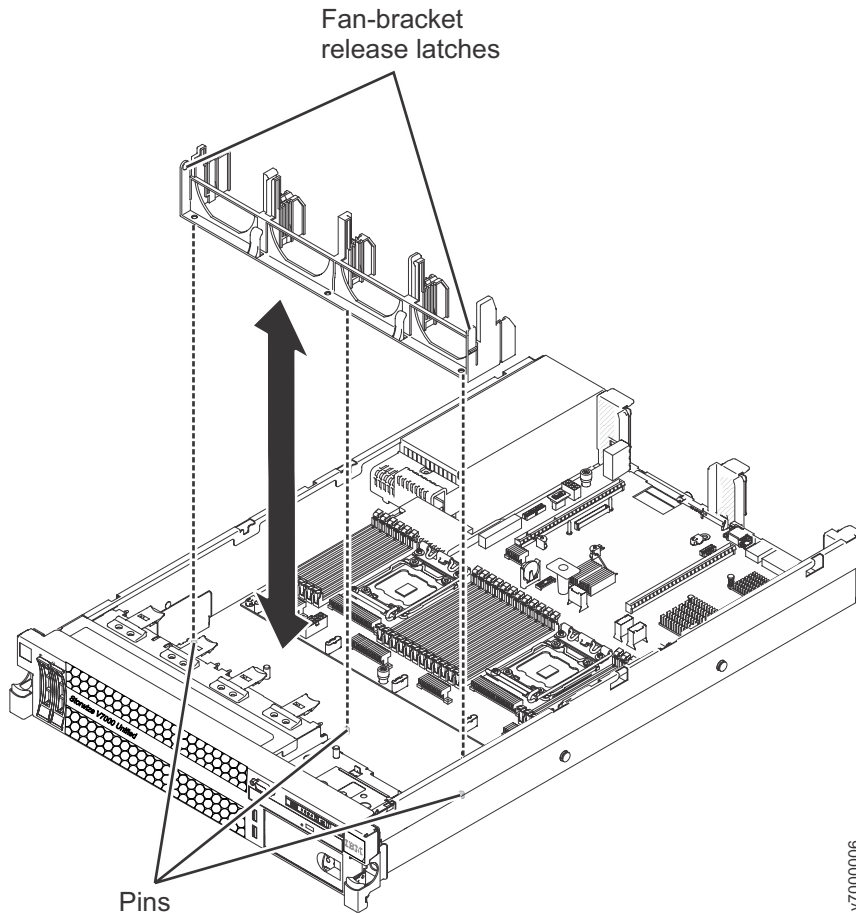


Figure 24. Removing the fan bracket

Procedure

1. Read the safety information that begins on page Safety and “Installation guidelines” on page 60.
2. Follow the procedure in “Removing a file module and disconnecting power” on page 58 to suspend the file module from the cluster and shut it down and disconnect all power cords and external cables.
3. Remove the cover. For more information, see Removing the cover.
4. Remove the fans.
5. Remove the PCI riser-card assemblies. For more information, see Removing a PCI riser-card assembly.
6. Press the fan-bracket release latches toward each other and lift the fan bracket out of the file module.

Installing the fan bracket

The following procedure is for a Tier 1 customer replaceable unit (CRU). Replacement of Tier 1 CRUs is your responsibility. If IBM installs a Tier 1 CRU at your request, you will be charged for the installation. Service agreements can be purchased so that you can ask IBM to replace these units.

About this task

To install the fan bracket, complete the following steps.

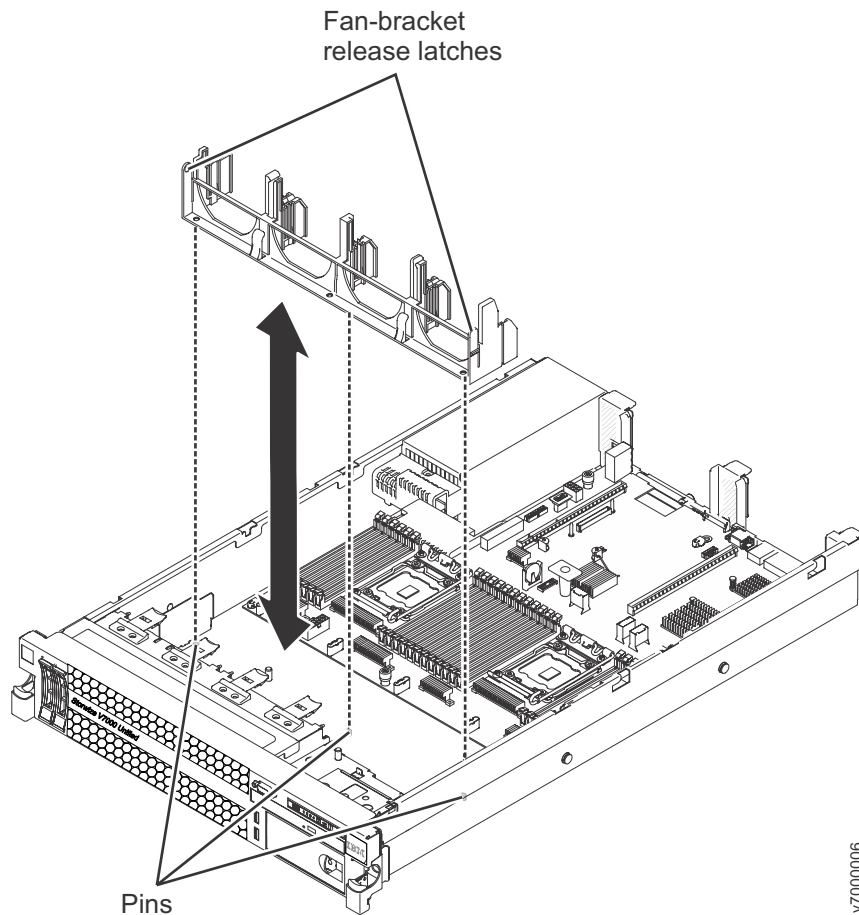


Figure 25. Installing the fan bracket

Procedure

1. Lower the fan bracket into the chassis.
2. Align the holes in the bottom of the bracket with the pins in the bottom of the chassis.
3. Press the bracket into position until the fan-bracket release levers click into place.
4. Replace the fans.
5. Replace the PCI riser-card assemblies. For more information, see *Installing a PCI riser-card assembly*.
6. Install the cover. For more information, see *Installing the cover*.
7. Slide the file module into the rack.
8. Follow the steps at the end of the procedure in “Removing a file module and disconnecting power” on page 58 to suspend the file module to reconnect the file module and resume its use in the cluster.

Removing a PCI riser-card assembly

The following procedure is for a Tier 1 customer replaceable unit (CRU). Replacement of Tier 1 CRUs is your responsibility. If IBM installs a Tier 1 CRU at your request, you will be charged for the installation. Service agreements can be purchased so that you can ask IBM to replace these units.

About this task

The file module comes with one riser-card assembly that contains two to three PCI slots. See <http://www.ibm.com/servers/eserver/serverproven/compat/us/> for a list of riser-card assemblies that you can use with the file module.

To remove a riser-card assembly, complete the following steps.

Procedure

1. Read the safety information that begins on page Safety and “Installation guidelines” on page 60.
2. Follow the procedure in “Removing a file module and disconnecting power” on page 58 to suspend the file module from the cluster and shut it down and disconnect all power cords and external cables.
3. Slide the file module out of the rack.
4. Remove the file module cover. For more information, see Removing the cover.
5. Grasp the riser-card assembly at the front tab and rear edge and lift it to remove it from the file module. Place the riser-card assembly on a flat, static-protective surface.

Installing a PCI riser-card assembly

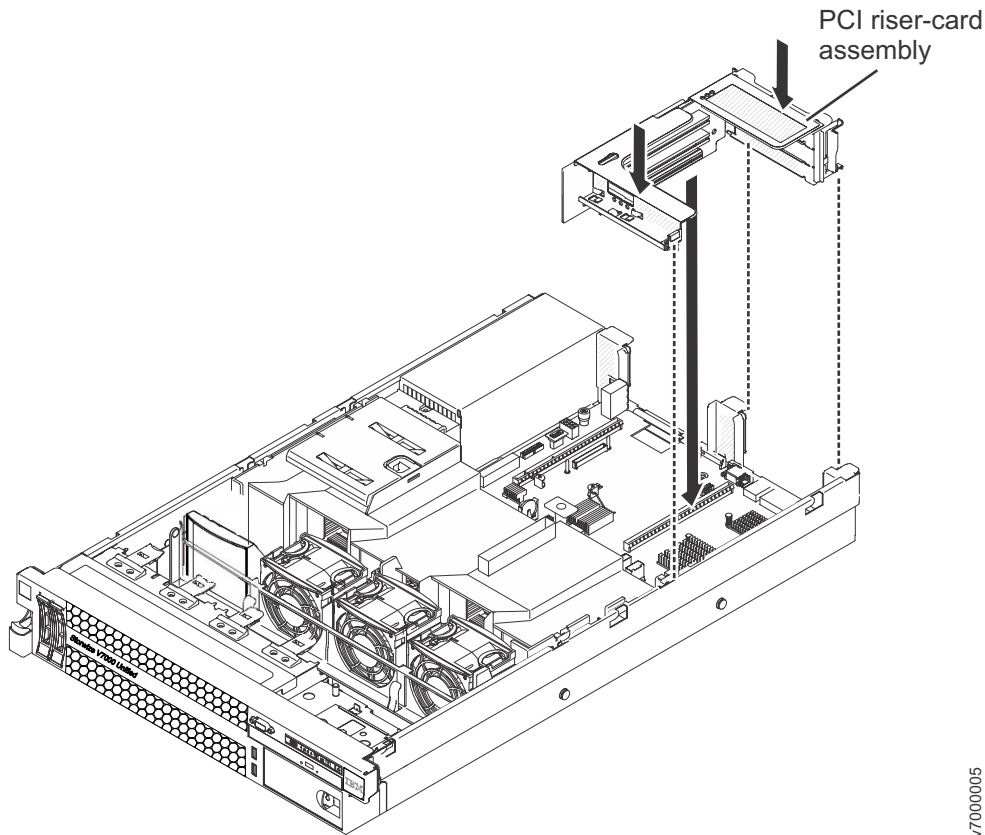
IBM authorized service providers can install a PCI riser-card assembly in the file module. The following procedure is for a Tier 1 customer replaceable unit (CRU). Replacement of Tier 1 CRUs is your responsibility. If IBM installs a Tier 1 CRU at your request, you will be charged for the installation. Service agreements can be purchased so that you can ask IBM to replace these units.

About this task

The file module provides two PCI riser-card slots on the system board. The following information indicates the riser-card slots:

- The file module come with one PCI Express® riser-card assembly installed.
- A PCI Express riser-card assembly has a black connector and supports PCI Express adapters.
- PCI riser slot 1 (the farthest slot from the power supplies). You must install a PCI riser-card assembly in slot 1.
- PCI riser slot 2 (the closest slot to the power supplies). You must not install a PCI riser-card assembly in slot 2.

To install a riser-card assembly, complete the following steps.



v7000005

Figure 26. Installing a PCI riser-card assembly

Procedure

1. Reinstall any adapters.
2. Align the PCI riser-card assembly with the selected PCI connector on the system board:

Note: The chassis might sag after you remove the riser assembly. In this case, lift the bottom of the chassis to line up the slots on the side of the assembly to the alignment brackets in the side of the chassis.

- **PCI connector 1:** Carefully fit the two alignment slots on the side of the assembly onto the two alignment brackets in the side of the chassis.
3. Press down on the assembly. Make sure that the riser-card assembly is fully seated in the riser-card connector on the system board.
 4. Install the file module cover. For more information, see *Installing the cover*.
 5. Slide the file module into the rack.
 6. Follow the steps at the end of the procedure in “Removing a file module and disconnecting power” on page 58 to suspend the file module to reconnect the file module and resume its use in the cluster.

Removing a PCI adapter from a PCI riser-card assembly

The following procedure is for a Tier 1 customer replaceable unit (CRU). Replacement of Tier 1 CRUs is your responsibility. If IBM installs a Tier 1 CRU at your request, you will be charged for the installation. Service agreements can be purchased so that you can ask IBM to replace these units.

About this task

This topic describes removing an adapter from a PCI expansion slot in a PCI riser-card assembly. These instructions apply to PCI adapters such as the Fibre Channel and the Ethernet network adapters.

To remove an adapter from a PCI expansion slot, complete the following steps.

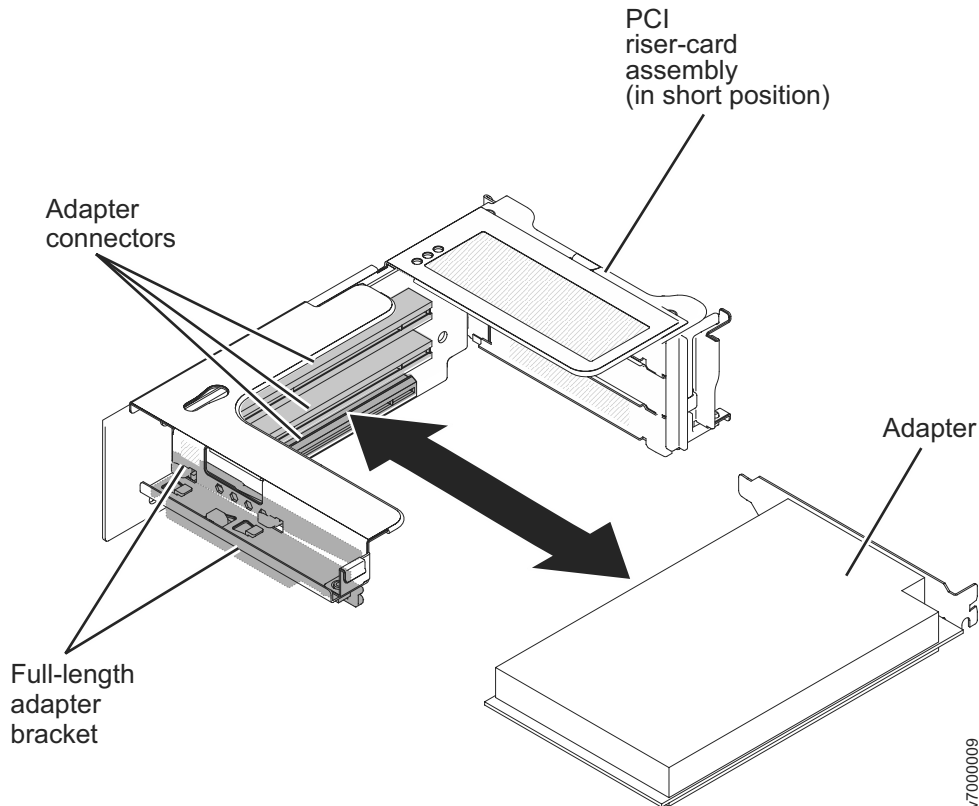


Figure 27. Removing a PCI adapter from a PCI riser-card assembly

Procedure

1. Read the safety information that begins on page Safety and “Installation guidelines” on page 60.
2. Follow the procedure in “Removing a file module and disconnecting power” on page 58 to suspend the file module from the cluster and shut it down and disconnect all power cords and external cables.
3. Press down on the left and right side latches and slide the file module out of the rack enclosure until both slide rails lock, and then remove the cover. For more information, see Removing the cover.
4. Remove the PCI riser-card assembly that contains the adapter, as described in Removing a PCI riser-card assembly.
5. Carefully grasp the adapter by its top edge or upper corners, and pull the adapter from the PCI expansion slot.
6. If you are instructed to return the adapter, follow all packaging instructions, and use any packaging materials for shipping that are supplied to you.

Installing a PCI adapter in a PCI riser-card assembly

The following procedure is for a Tier 1 customer replaceable unit (CRU). Replacement of Tier 1 CRUs is your responsibility. If IBM installs a Tier 1 CRU at your request, you will be charged for the installation. Service agreements can be purchased so that you can ask IBM to replace these units.

About this task

Important: Some cluster solutions require specific code levels or coordinated code updates. If the device is part of a cluster solution, verify that the latest level of code is supported for the cluster solution before you update the code.

To install an adapter, complete the following steps.

Procedure

1. Install the adapter in the expansion slot.
 - a. Align the adapter with the PCI connector on the riser card and the guide on the external end of the riser-card assembly.
 - b. Press the adapter firmly into the PCI connector on the riser card.

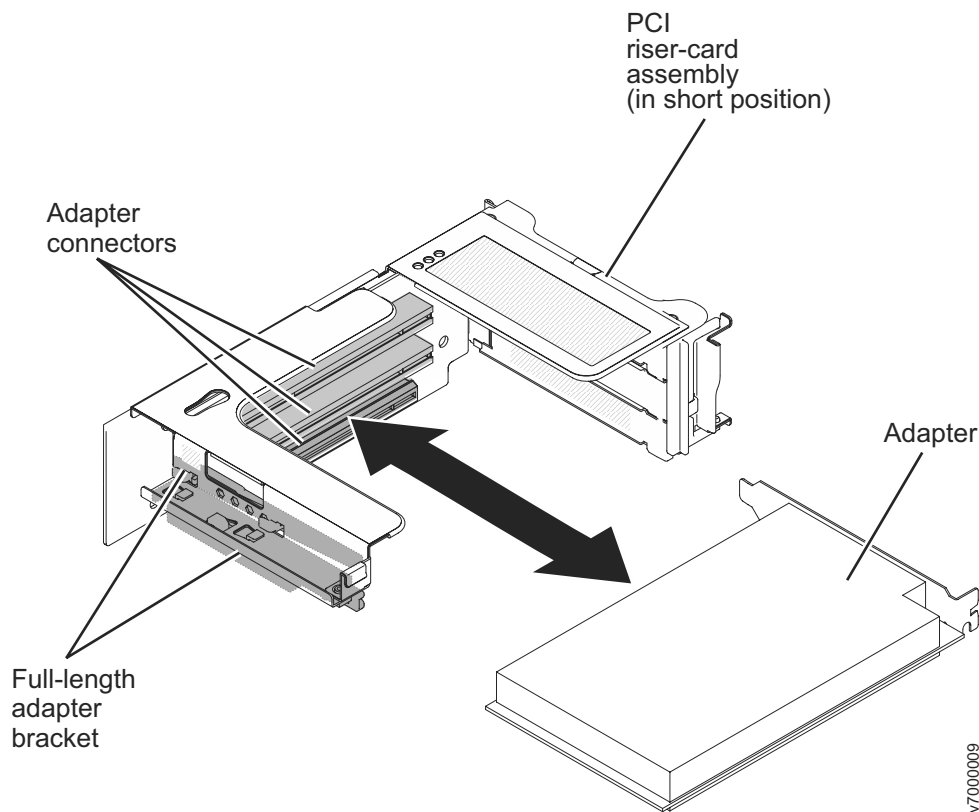


Figure 28. Inserting the adapter into the PCI connector

2. Align the PCI riser-card assembly with the selected PCI connector on the system board:
 - Carefully fit the two alignment slots on the side of the assembly onto the two alignment brackets on the side of the chassis; align the rear of the assembly with the guides on the rear of the file module.

3. Press down on the assembly. Make sure that the riser-card assembly is fully seated in the riser-card connector on the system board.
4. Install the file module cover. For more information, see *Installing the cover*.
5. Slide the file module into the rack.
6. Reconnect the external cables; then, reconnect the power cords and turn on the peripheral devices and the file module.

Removing a Fibre Channel PCI adapter

This removal instruction indicates the slot location for the Fibre Channel PCI adapter.

About this task

The Fibre Channel adapter is in PCI slot 2.

Refer to “Removing a PCI adapter from a PCI riser-card assembly” on page 109 for instructions.

Installing a Fibre Channel PCI adapter

This installation instruction indicates the slot location for the Fibre Channel PCI adapter.

About this task

The Fibre Channel adapter must go in PCI slot 2.

Refer to “Installing a PCI adapter in a PCI riser-card assembly” on page 111 for instructions.

Removing a 10-Gbps Ethernet adapter

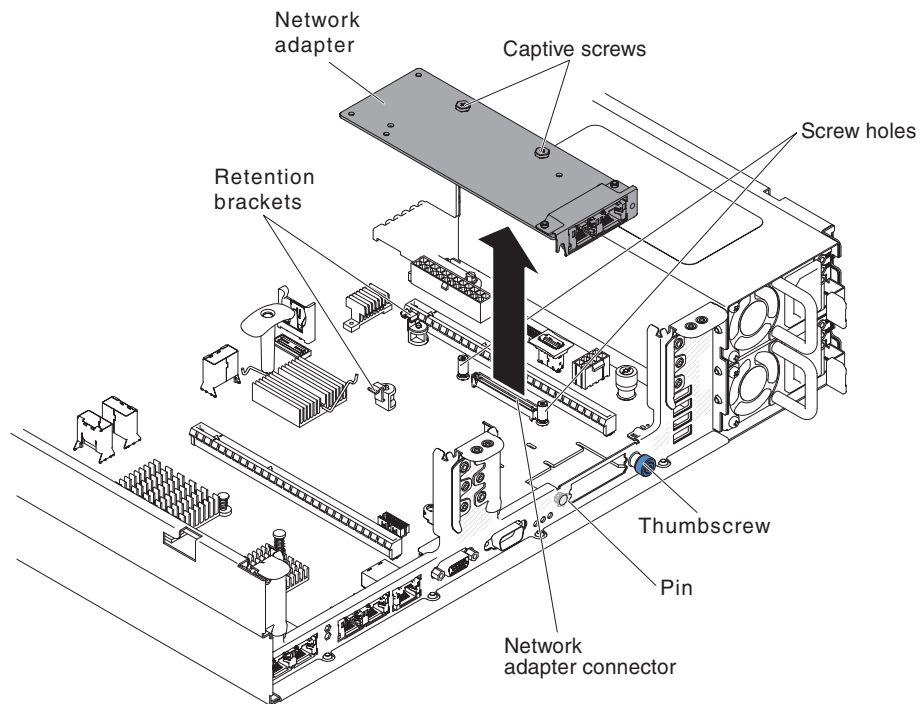
The following procedure is for a Tier 1 customer replaceable unit (CRU). Replacement of Tier 1 CRUs is your responsibility. If IBM installs a Tier 1 CRU at your request, you will be charged for the installation. Service agreements can be purchased so that you can ask IBM to replace these units.

About this task

To remove the network adapter, complete the following steps:

Procedure

1. Read the Safety information and “Installation guidelines” on page 60.
2. Follow the procedure in “Removing a file module and disconnecting power” on page 58 to suspend the file module from the cluster and shut it down, and then disconnect all power cords and external cables.
3. Remove the cover (see “Removing the cover” on page 89).
4. Loosen the thumbscrew on the rear of the chassis.



5. Grasp the network adapter and disengage it from the pin, standoffs, retention brackets, and the connector on the system board; then, lift the adapter out of the port openings on the rear of the chassis and remove it from the server.
6. If you are instructed to return the network adapter, follow all packaging instructions, and use any packaging materials for shipping that are supplied to you.

Installing a 10-Gbps Ethernet adapter

The following procedure is for a Tier 1 customer replaceable unit (CRU). Replacement of Tier 1 CRUs is your responsibility. If IBM installs a Tier 1 CRU at your request, you will be charged for the installation. Service agreements can be purchased so that you can ask IBM to replace these units.

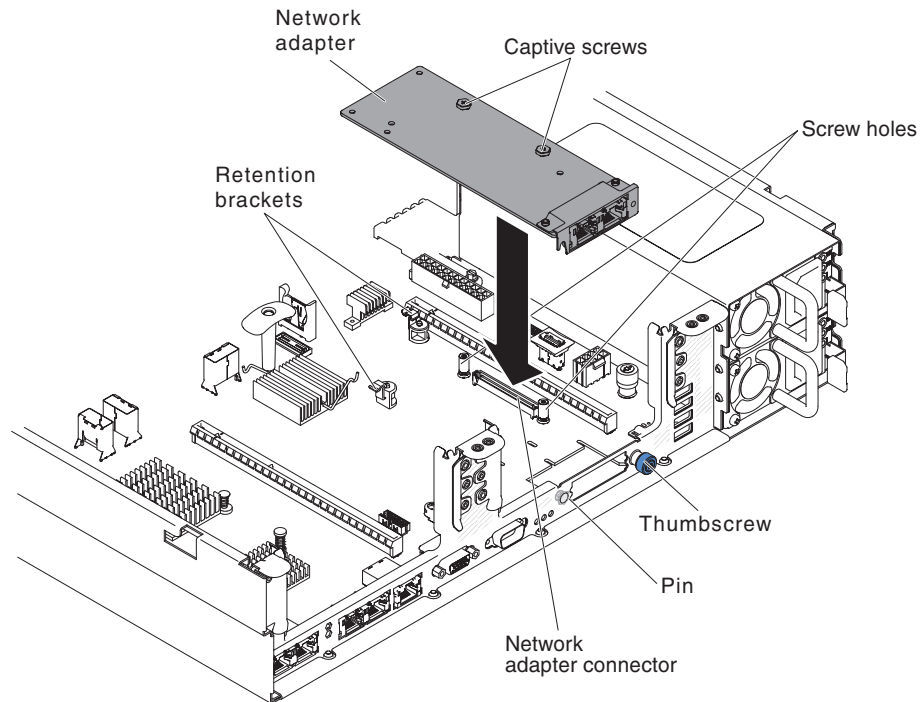
About this task

The file module has a Emulex dual port 10GbE SFP+ Embedded VFA III adapter.

To install the network adapter, complete the following steps:

Procedure

1. Read the Safety information and “Installation guidelines” on page 60.
2. Follow the procedure in “Removing a file module and disconnecting power” on page 58 to suspend the file module from the cluster and shut it down, and then disconnect all power cords and external cables.
3. Remove the cover (see “Removing the cover” on page 89).
4. Touch the static-protective package that contains the new adapter to any unpainted metal surface on the file module, and then remove the adapter from the package.
5. Align the adapter so that the port connectors on the adapter line up with the pin and thumbscrew on the chassis; then, align the connector of the adapter with the adapter connector on the system board.



6. Press the adapter firmly until the pin, standoffs, and retention brackets engage the adapter. Make sure the adapter is securely seated on the connector on the system board.

Attention: Make sure the port connectors on the adapter are aligned properly with the chassis on the rear of the server. An incorrectly seated adapter might cause damage to the system board or the adapter.

7. Fasten the thumbscrew.
8. Install the cover (see “Installing the cover” on page 90).
9. Slide the file module into the rack.
10. Follow the steps at the end of the procedure “Removing a file module and disconnecting power” on page 58 to reconnect the file module and resume its use in the cluster.

Removing a hot-swap hard disk drive

The following procedure is for a Tier 1 customer replaceable unit (CRU). Replacement of Tier 1 CRUs is your responsibility. If IBM installs a Tier 1 CRU at your request, you will be charged for the installation. Service agreements can be purchased so that you can ask IBM to replace these units.

About this task

To remove a hard disk drive from a hot-swap bay, complete the following steps.

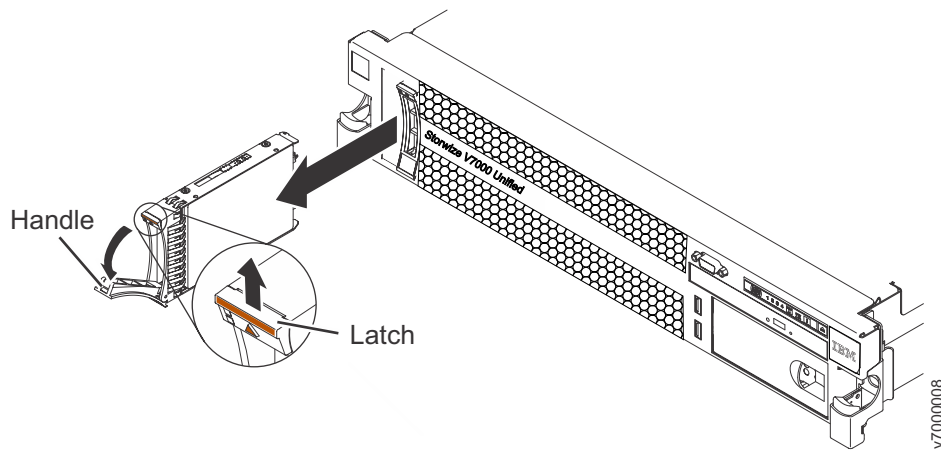


Figure 29. Removing a hot-swap hard disk drive

Attention: To maintain proper system cooling, do not operate the file module for more than 10 minutes without either a drive or a filler panel installed in each bay.

Procedure

1. Read the safety information that begins on page Safety, “Handling static-sensitive devices” on page 62, and “Installation guidelines” on page 60.
2. Press up on the release latch at the top of the drive front.
3. Rotate the handle on the drive downward to the open position.
4. Pull the hot-swap drive assembly out of the bay approximately 25 mm (1 inch). Wait approximately 45 seconds while the drive spins down before you remove the drive assembly completely from the bay.
5. If you are instructed to return the hot-swap drive, follow all packaging instructions, and use any packaging materials for shipping that are supplied to you.

Installing a hot-swap hard disk drive

The following procedure is for a Tier 1 customer replaceable unit (CRU). Replacement of Tier 1 CRUs is your responsibility. If IBM installs a Tier 1 CRU at your request, you will be charged for the installation. Service agreements can be purchased so that you can ask IBM to replace these units.

About this task

Locate the documentation that comes with the hard disk drive and follow those instructions in addition to the instructions in this section.

To install a drive in a hot-swap bay, complete the following steps.

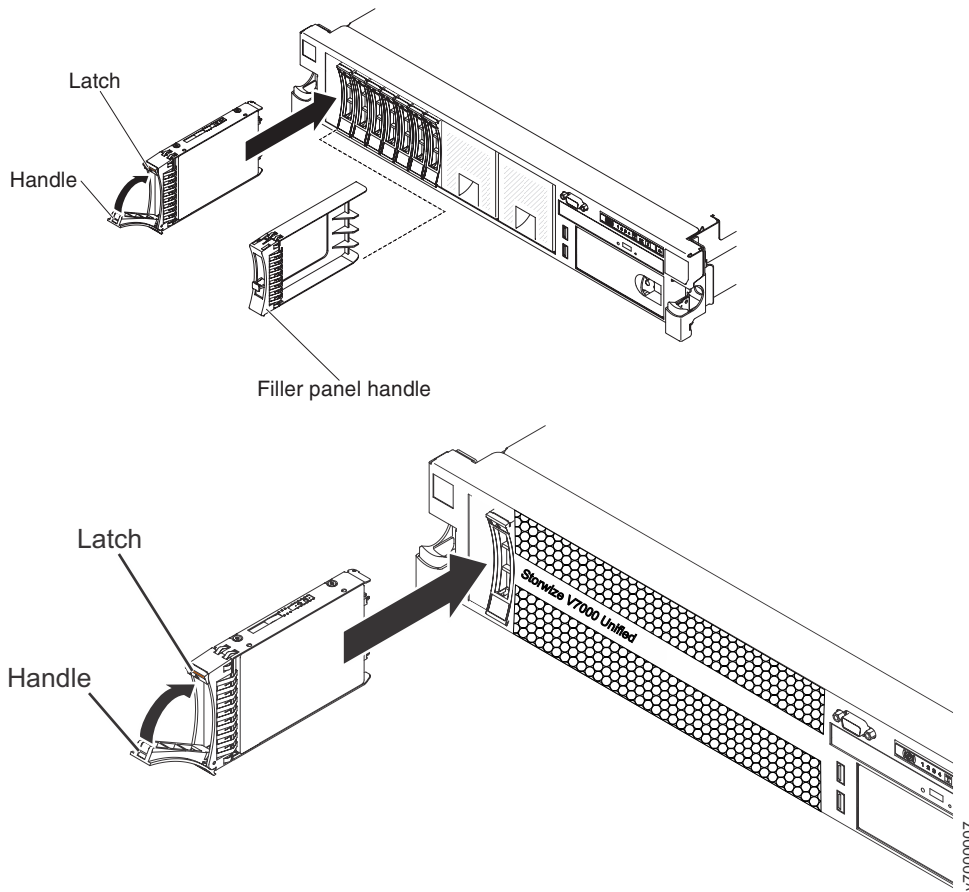


Figure 30. Installing a hot-swap hard disk drive

Attention: To maintain proper system cooling, do not operate the file module for more than 10 minutes without a drive that is installed in each bay.

Procedure

1. Orient the drive as shown in the illustration.
2. Make sure that the tray handle is open.
3. Align the drive assembly with the guide rails in the bay.
4. Gently push the drive assembly into the bay until the drive stops.
5. Push the tray handle to the closed (locked) position.
6. If the system is turned on, check the hard disk drive status LED to verify that the hard disk drive is operating correctly.

Results

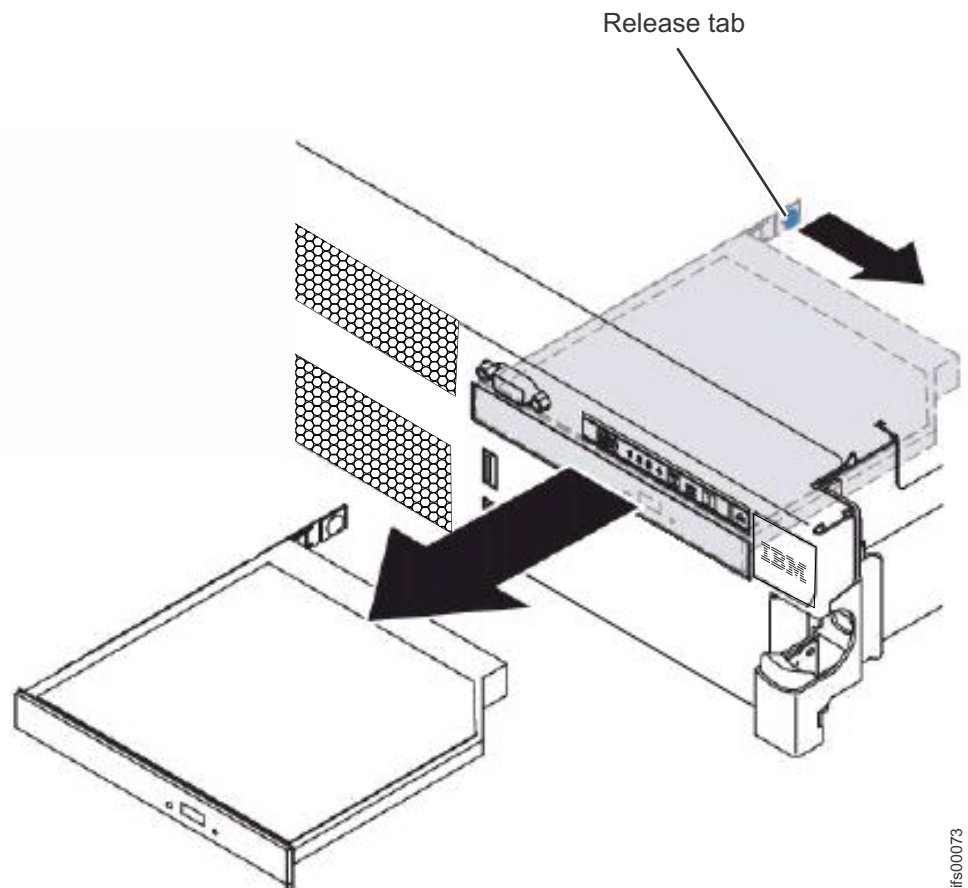
After you replace a failed hard disk drive, the green activity LED flashes as the disk spins up. The yellow LED turns off after approximately 1 minute. If the new drive starts to rebuild, the yellow LED flashes slowly, and the green activity LED remains lit during the rebuild process.

Removing the DVD drive

The following procedure is for a Tier 1 customer replaceable unit (CRU). Replacement of Tier 1 CRUs is your responsibility. If IBM installs a Tier 1 CRU at your request, you will be charged for the installation. Service agreements can be purchased so that you can ask IBM to replace these units.

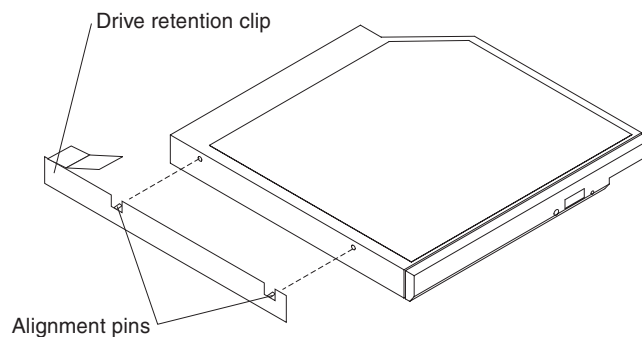
About this task

To remove the DVD drive, complete the following steps.



Procedure

1. Read the Safety information and “Installation guidelines” on page 60.
2. Follow the procedure in “Removing a file module and disconnecting power” on page 58 to suspend the file module from the cluster and shut it down, and then disconnect all power cords and external cables.
3. Slide the file module out of the rack, and then remove the cover (see “Removing the cover” on page 89).
4. Press the release tab down to release the drive; then, while you press the tab, push the drive toward the front of the file module.
5. From the front of the file module, pull the drive out of the bay.



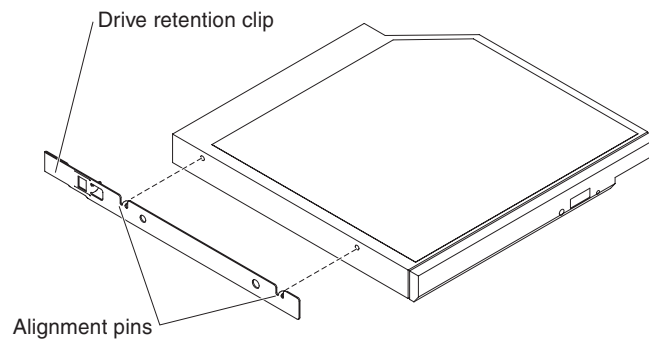
6. Remove the drive retention clip from the drive.
7. If you are instructed to return the DVD drive, follow all packaging instructions, and use any packaging materials for shipping that are supplied to you.

Installing the DVD drive

The following procedure is for a Tier 1 customer replaceable unit (CRU). Replacement of Tier 1 CRUs is your responsibility. If IBM installs a Tier 1 CRU at your request, you will be charged for the installation. Service agreements can be purchased so that you can ask IBM to replace these units.

About this task

To install the replacement DVD drive, complete the following steps.



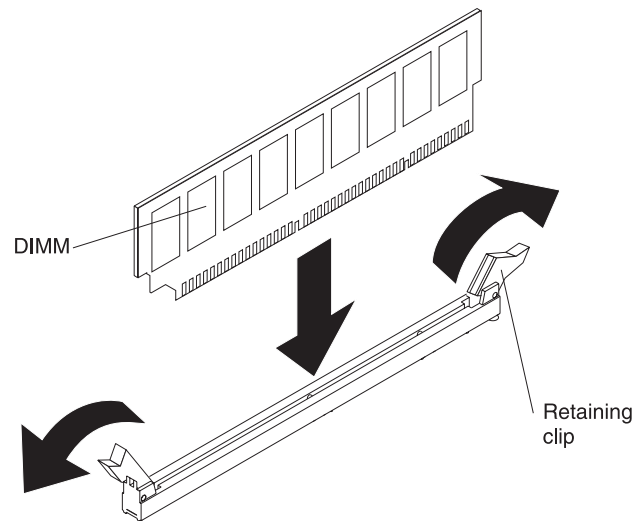
1. Attach the drive-retention clip to the side of the drive.
2. Slide the drive into the CD/DVD drive bay until the drive clicks into place.
3. Install the cover (see "Installing the cover" on page 90).
4. Slide the file module into the rack.
5. Follow the steps at the end of the procedure "Removing a file module and disconnecting power" on page 58 to reconnect the file module and resume its use in the cluster.

Removing a memory module

The following procedure is for a Tier 1 customer replaceable unit (CRU). Replacement of Tier 1 CRUs is your responsibility. If IBM installs a Tier 1 CRU at your request, you will be charged for the installation. Service agreements can be purchased so that you can ask IBM to replace these units.

About this task

To remove a DIMM, complete the following steps.



Procedure

1. Read the Safety information and “Installation guidelines” on page 60.
2. Follow the procedure in “Removing a file module and disconnecting power” on page 58 to suspend the file module from the cluster and shut it down, and then disconnect all power cords and external cables.
3. Slide the file module out of the rack.
4. Remove the cover (see “Removing the cover” on page 89).
5. Remove the air baffle over the DIMMs (see “Removing the air baffle” on page 103).
6. Open the retaining clip on each end of the DIMM connector and lift the DIMM from the connector.
Attention: To avoid breaking the retaining clips or damaging the DIMM connectors, open and close the clips gently.
7. If you are instructed to return the DIMM, follow all packaging instructions, and use any packaging materials for shipping that are supplied to you.

Installing a memory module

The following procedure is for a Tier 1 customer replaceable unit (CRU). Replacement of Tier 1 CRUs is your responsibility. If IBM installs a Tier 1 CRU at your request, you will be charged for the installation. Service agreements can be purchased so that you can ask IBM to replace these units.

About this task

See Figure 31 on page 120 for the locations of the DIMM connectors on the system board.

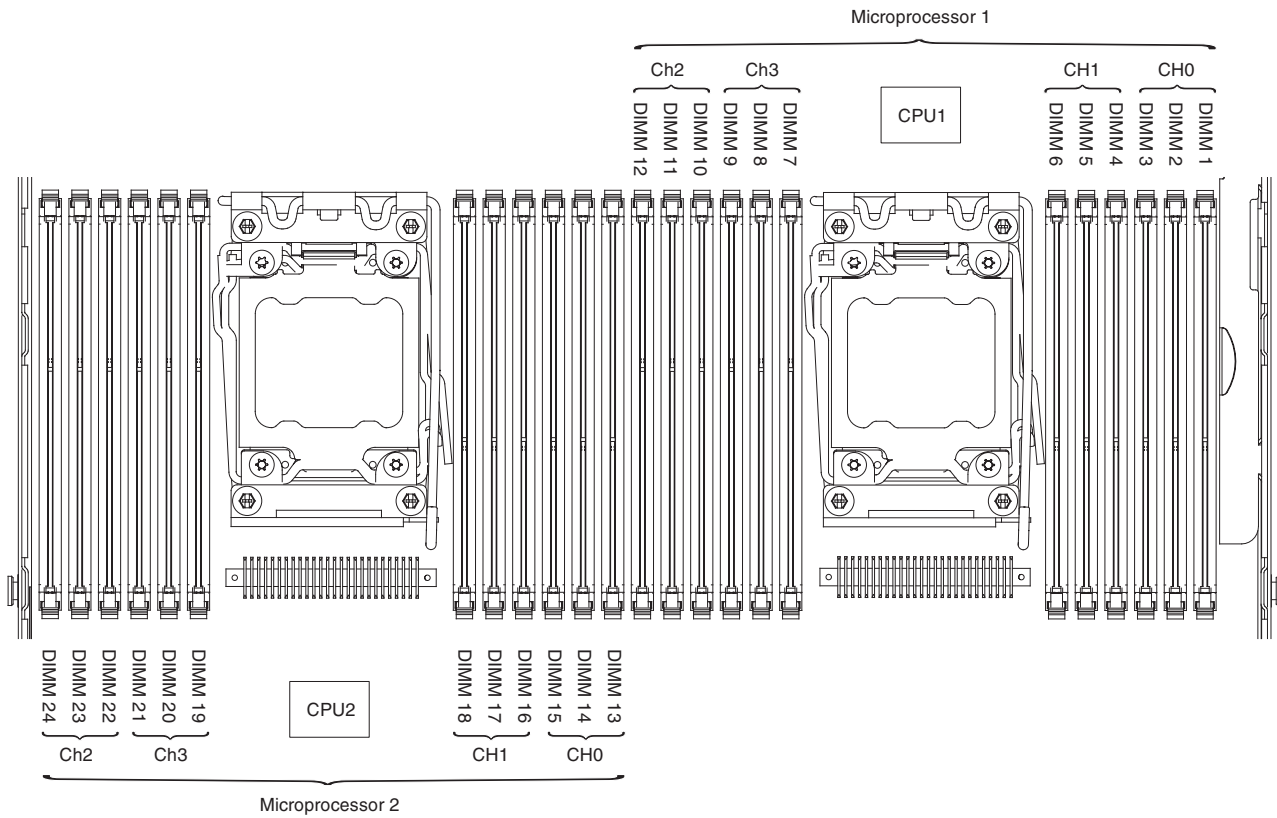
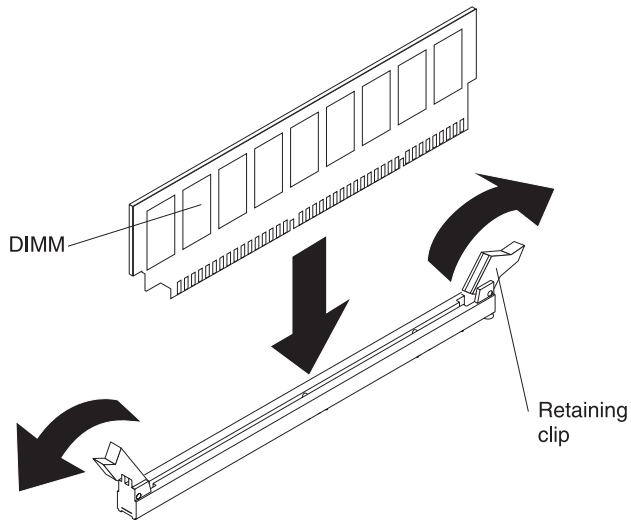


Figure 31. Locations of the DIMM connectors on the system board

To install a DIMM, complete the following procedure.



See Table 31 on page 121 for a listing of the eight DIMM slots populated with the memory RDIMM.

Table 31. DIMM slots populated with the memory RDIMM

| Processor | Memory Channel | DIMM Slot Number |
|-----------|----------------|------------------|
| 1 | 0 | 1 - 16GB RDIMM |
| | | 2 - 2GB RDIMM |
| | 1 | 4 - 16GB RDIMM |
| | | 5 - 2GB RDIMM |
| | 2 | 12 - 16GB RDIMM |
| | | 11 - 2GB RDIMM |
| | 3 | 9 - 16GB RDIMM |
| | | 8 - 2GB RDIMM |

Note: Do not put any DIMM into DIMM slots 3, 6, 7, 10, or slots 13 to 24.

Procedure

1. Remove the air baffle over the DIMMs (see “Removing the air baffle” on page 103).
2. Open the retaining clip on each end of the DIMM connector.
Attention: To avoid breaking the retaining clips or damaging the DIMM connectors, open and close the clips gently.
3. Touch the static-protective package that contains the DIMM to any unpainted metal surface on the file module, and then remove the DIMM from the package.
4. Turn the DIMM so that the DIMM keys align correctly with the connector.
5. Insert the DIMM into the connector by aligning the edges of the DIMM with the slots at the ends of the DIMM connector. Firmly press the DIMM straight down into the connector by applying pressure on both ends of the DIMM simultaneously. The retaining clips snap into the locked position when the DIMM is firmly seated in the connector.
Attention: If there is a gap between the DIMM and the retaining clips, the DIMM has not been correctly inserted; open the retaining clips, remove the DIMM, and then reinsert it.
6. Repeat steps 1 through 5 until all the new or replacement DIMMs are installed.
7. Replace the air baffle over the DIMMs (see “Installing the air baffle” on page 104), making sure all cables are out of the way.
8. Install the cover (see “Installing the cover” on page 90).
9. Slide the file module into the rack.
10. Follow the steps at the end of the procedure “Removing a file module and disconnecting power” on page 58 to reconnect the file module and resume its use in the cluster.
11. Go to the management GUI and look for any unfixed events related to DIMMs.

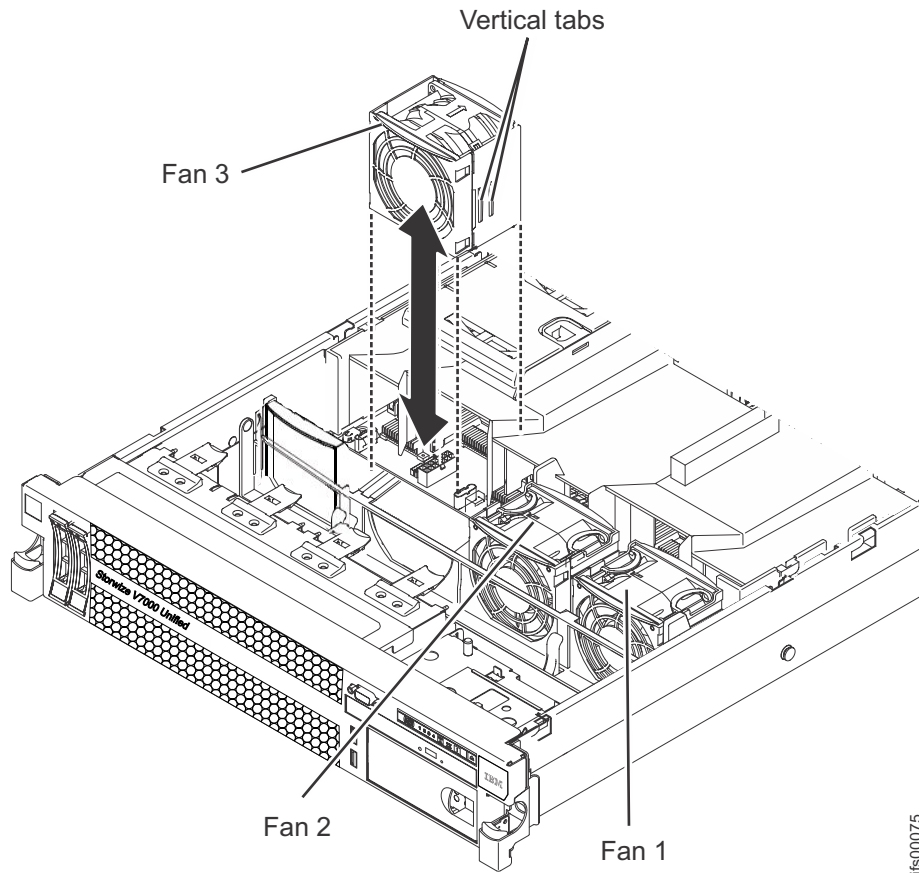
Removing a hot-swap fan

The following procedure is for a Tier 1 customer replaceable unit (CRU). Replacement of Tier 1 CRUs is your responsibility. If IBM installs a Tier 1 CRU at your request, you will be charged for the installation. Service agreements can be purchased so that you can ask IBM to replace these units.

About this task

Attention: To ensure proper file module operation and cooling, if you remove a dual-motor hot-swap fan with the system running, you must install a replacement dual-motor hot-swap fan within 30 seconds or the system will shut down.

To remove any of the three replaceable dual-motor hot-swap fans, complete the following steps.



Procedure

1. Read the Safety information and “Installation guidelines” on page 60.
2. Leave the file module connected to power.
3. Slide the file module out of the rack and remove the cover (see “Removing the cover” on page 89). The LED on the system board near the connector for the failing dual-motor hot-swap fan will be lit.

Attention: To ensure proper system cooling, do not remove the top cover for more than 30 minutes during this procedure.

4. Grasp the dual-motor hot-swap fan by the finger grips on the sides of the dual-motor hot-swap fan.
5. Rotate the air baffle up.
6. Lift the dual-motor hot-swap fan out of the file module.
7. Replace the dual-motor hot-swap fan within 30 seconds.

8. If you are instructed to return the dual-motor hot-swap fan, follow all packaging instructions, and use any packaging materials for shipping that are supplied to you.

Installing a hot-swap fan

The following procedure is for a Tier 1 customer replaceable unit (CRU). Replacement of Tier 1 CRUs is your responsibility. If IBM installs a Tier 1 CRU at your request, you will be charged for the installation. Service agreements can be purchased so that you can ask IBM to replace these units.

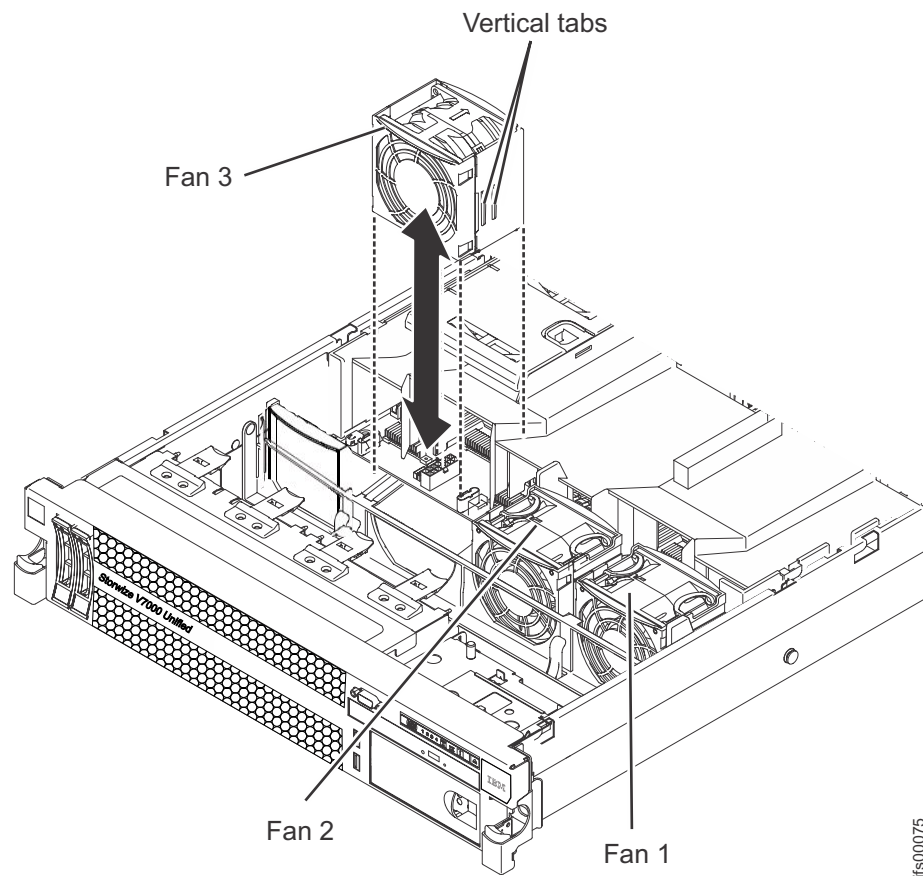
About this task

For proper cooling, the file module requires that all three dual-motor hot-swap fans be installed at all times.

Attention: To ensure proper file module operation, if a dual-motor hot-swap fan fails, replace it immediately. Have a replacement dual-motor hot-swap fan ready to install as soon as you remove the failed dual-motor hot-swap fan.

See System-board internal connectors for the locations of the dual-motor hot-swap fan connectors.

To install any of the three replaceable fans, complete the following steps.



Procedure

1. Rotate the air baffle up.

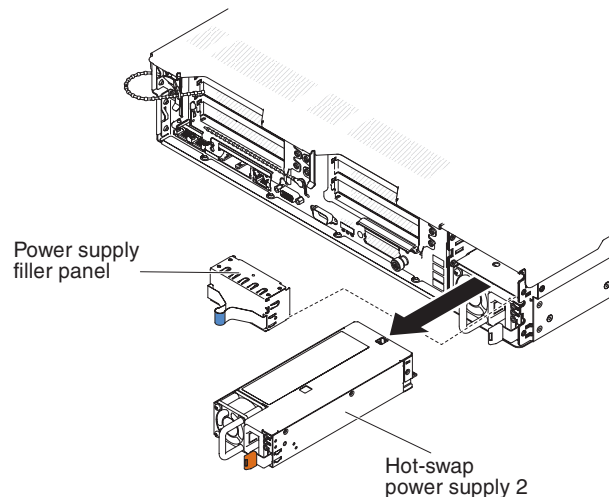
2. Orient the new dual-motor hot-swap fan over its position in the dual-motor hot-swap fan bracket so that the connector on the bottom aligns with the dual-motor hot-swap fan connector on the system board.
3. Align the vertical tabs on the dual-motor hot-swap fan with the slots on the dual-motor hot-swap fan cage bracket.
4. Push the new dual-motor hot-swap fan into the dual-motor hot-swap fan connector on the system board. Press down on the top surface of the dual-motor hot-swap fan to seat the dual-motor hot-swap fan fully. (Make sure that the LED has turned off.)
5. Repeat steps 1 through 3 until all the new or replacement dual-motor hot-swap fans are installed.
6. Install the cover (see “Installing the cover” on page 90).
7. Slide the file module into the rack.

Removing a hot-swap ac power supply

The following procedure is for a Tier 1 customer replaceable unit (CRU). Replacement of Tier 1 CRUs is your responsibility. If IBM installs a Tier 1 CRU at your request, you will be charged for the installation. Service agreements can be purchased so that you can ask IBM to replace these units.

About this task

To remove a power supply, complete the following steps.



1. Read the Safety information and “Installation guidelines” on page 60.
2. If only one power supply is installed, turn off the server and peripheral devices.
3. Disconnect the power cord from the power supply that you are removing.
4. Grasp the power-supply handle.
5. Press the orange release latch to the left and hold it in place.
6. Pull the power supply part of the way out of the bay, then release the latch and support the power supply as you pull it the rest of the way out of the bay.
7. If you are instructed to return the power supply, follow all packaging instructions, and use any packaging materials for shipping that are supplied to you.

Installing a hot-swap ac power supply

The following procedure is for a Tier 1 customer replaceable unit (CRU). Replacement of Tier 1 CRUs is your responsibility. If IBM installs a Tier 1 CRU at your request, you will be charged for the installation. Service agreements can be purchased so that you can ask IBM to replace these units.

About this task

The following notes describe the type of ac power supply that the server supports and other information that you must consider when you install a power supply:

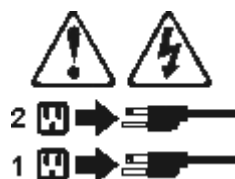
- Make sure that the devices that you are installing are supported. For a list of supported optional devices for the server, see <http://www.ibm.com/systems/info/x86servers/serverproven/compat/us/>.
- Before you install an additional power supply or replace a power supply with one of a different wattage, you may use the IBM Power Configurator utility to determine current system power consumption. For more information and to download the utility, go to <http://www-03.ibm.com/systems/bladecenter/resources/powerconfig.html>.
- The server comes with one hot-swap 12-volt output power supply that connects to power supply bay 1. The input voltage is 100-127 V ac or 200-240 V ac auto-sensing.
- Power supplies in the server must be with the same power rating or wattage to ensure that the server will operate correctly. For example, you cannot mix 750-watt and 900-watt power supplies in the server.
- Power supply 1 is the default/primary power supply. If power supply 1 fails, you must replace the power supply immediately.
- You can order an optional power supply for redundancy.
- These power supplies are designed for parallel operation. In the event of a power-supply failure, the redundant power supply continues to power the system. The server supports a maximum of two power supplies.

Statement 5



CAUTION:

The power control button on the device and the power switch on the power supply do not turn off the electrical current supplied to the device. The device also might have more than one power cord. To remove all electrical current from the device, ensure that all power cords are disconnected from the power source.



Statement 8

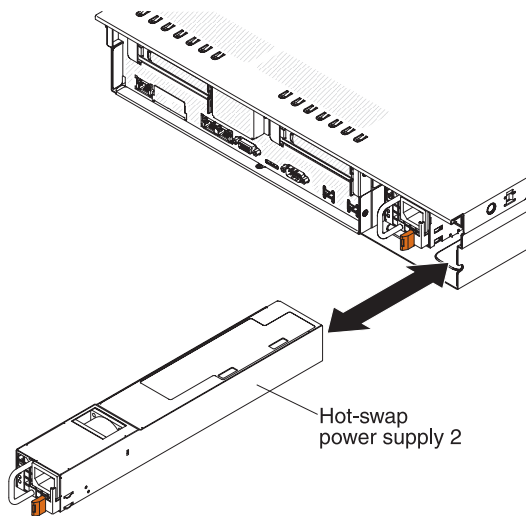


CAUTION:

Never remove the cover on a power supply or any part that has the following label attached.



Hazardous voltage, current, and energy levels are present inside any component that has this label attached. There are no serviceable parts inside these components. If you suspect a problem with one of these parts, contact a service technician.

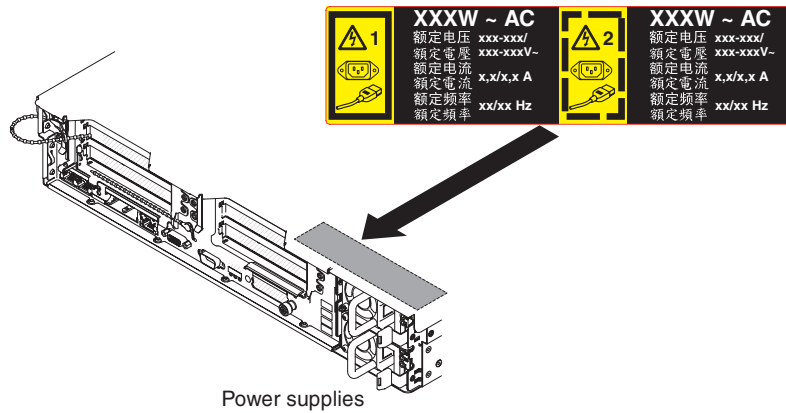


Attention: During normal operation, each power-supply bay must have either a power supply or power-supply filler installed for proper cooling.

To install a hot-swap ac power supply, complete the following steps:

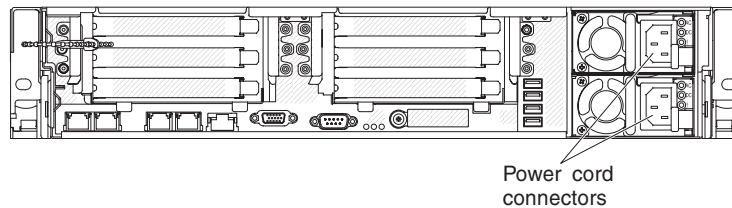
Procedure

1. Read the Safety information and “Installation guidelines” on page 60.
2. Touch the static-protective package that contains the hot-swap power supply to any unpainted metal surface on the server; then, remove the power supply from the package and place it on a static-protective surface.
3. If you are adding a power supply to the server, attach the redundant power information label that comes with this option on the server cover near the power supplies.



4. Slide the power supply into the bay until the retention latch clicks into place.
Attention: Do not install the different power rating or wattage of power supplies, high-efficiency and non-high-efficiency power supplies in the server.
5. Connect the power cord for the new power supply to the power-cord connector on the power supply.

The following illustration shows the power-cord connectors on the back of the server.



6. Route the power cord through the clip next to power-supply and through any cable clamps on the rear of the server, to prevent the power cord from being accidentally pulled out when you slide the server in and out of the rack.
7. Connect the power cord to a properly grounded electrical outlet.
8. Make sure that the error LED on the power supply is not lit, and that the ac power LED on the power supply are lit, indicating that the power supply is operating correctly.
9. If you are replacing a power supply with one of a different wattage, apply the power information label provided with the new power supply over the existing power information label on the server.

| | | | |
|------|-----------------|------|--|
| 额定电压 | xxx-xxx/xxx-xxx | 额定電壓 | |
| 额定电流 | x,x/x,x | 额定電流 | |
| 额定频率 | xx/xx Hz | 额定頻率 | |

Product certified in Shenzhen, China
Made in China V 中国制造

Manufacturer: IBM Corporation
©Copyright IBM Corp. 2010 All Rights Reserved.
Canada ICES/NMB-003 Class/Classe A

この装置は、クラスA 情報技術装置です。この装置を家庭環境で使用すると電波妨害を引き起こすことがあります。この場合には使用者が適切な対策を講ずるよう要求されることがあります。VCCI-A

Apparaten skall anslutas till jordat uttag
Apparatet må tilkoples jordnet stikkontakt
Laitte on liitettävä suojamaadoituskoskettimilla varustettuun pistorasiaan

This device complies with part 15 of FCC rules. Operation is subject to the following two conditions: (1) this device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

警告使用者:
這是甲類的資訊產品，在居住的環境中使用時，可能會造成射頻干擾，在這種情況下，使用者會被要求採取某些適當的對象。

廢電池請回收

EU Only

30

100% Product Safety

UL US LISTED I.T.E. Equip. 167G

CE PCPT MED1

CCC

RSS3026 伺服器 服务器 型号 MT: XXXX

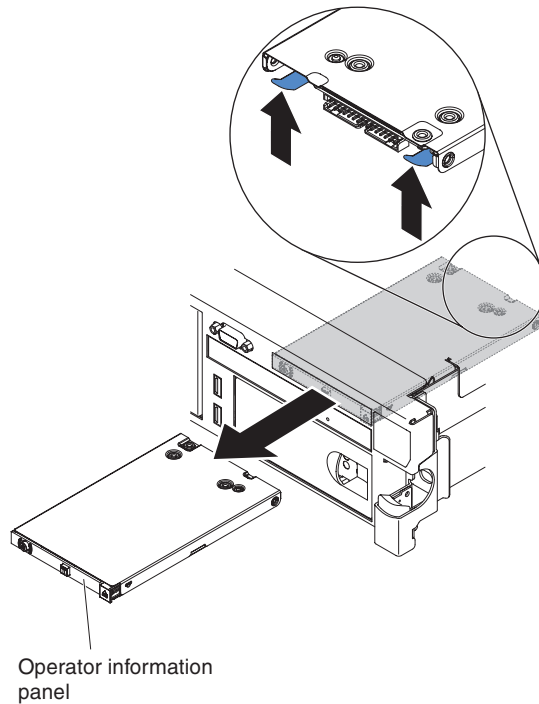
Model: xxx
SN: SSSSSSS
MFG date: YYYYMMDD
Product ID:
PN:

Removing the operator information panel assembly

The following procedure is for a Tier 1 customer replaceable unit (CRU). Replacement of Tier 1 CRUs is your responsibility. If IBM installs a Tier 1 CRU at your request, you will be charged for the installation. Service agreements can be purchased so that you can ask IBM to replace these units.

About this task

To remove the operator information panel assembly, complete the following steps.



Procedure

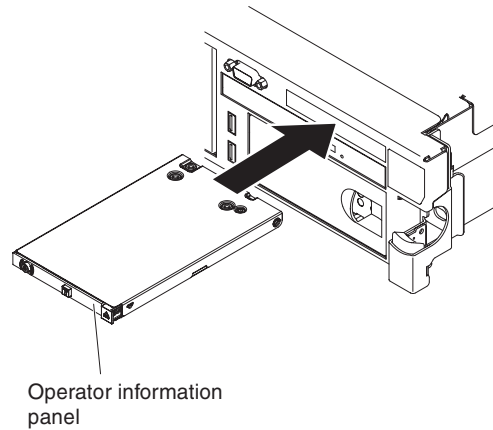
1. Read the Safety information and “Installation guidelines” on page 60.
2. Follow the procedure in “Removing a file module and disconnecting power” on page 58 to suspend the file module from the cluster and shut it down, and then disconnect all power cords and external cables.
3. Remove the cover (see “Removing the cover” on page 89).
4. Disconnect the cable from the back of the operator information panel assembly.
5. Reach inside the file module and press the release tab; then, while you hold the release tab down, push the assembly toward the front of the file module.
6. From the front of the file module, carefully pull the operator information panel assembly out of the file module.
7. If you are instructed to return the operator information panel assembly, follow all packaging instructions, and use any packaging materials for shipping that are supplied to you.

Installing the operator information panel assembly

The following procedure is for a Tier 1 customer replaceable unit (CRU). Replacement of Tier 1 CRUs is your responsibility. If IBM installs a Tier 1 CRU at your request, you will be charged for the installation. Service agreements can be purchased so that you can ask IBM to replace these units.

About this task

To install the replacement operator information panel assembly, complete the following steps.



Procedure

1. Read the Safety information and “Installation guidelines” on page 60.
2. Position the operator information panel assembly so that the tabs face upward and slide it into the file module until it clicks into place.
3. Inside the file module, connect the cable to the rear of the operator information panel assembly.
4. Install the cover (see “Installing the cover” on page 90).
5. Slide the file module into the rack.
6. Follow the steps at the end of the procedure “Removing a file module and disconnecting power” on page 58 to reconnect the file module and resume its use in the cluster.

Removing the hot-swap drive backplane

The following procedure is for a Tier 1 customer replaceable unit (CRU). Replacement of Tier 1 CRUs is your responsibility. If IBM installs a Tier 1 CRU at your request, you will be charged for the installation. Service agreements can be purchased so that you can ask IBM to replace these units.

About this task

To remove the hot-swap drive backplane, complete the following steps.

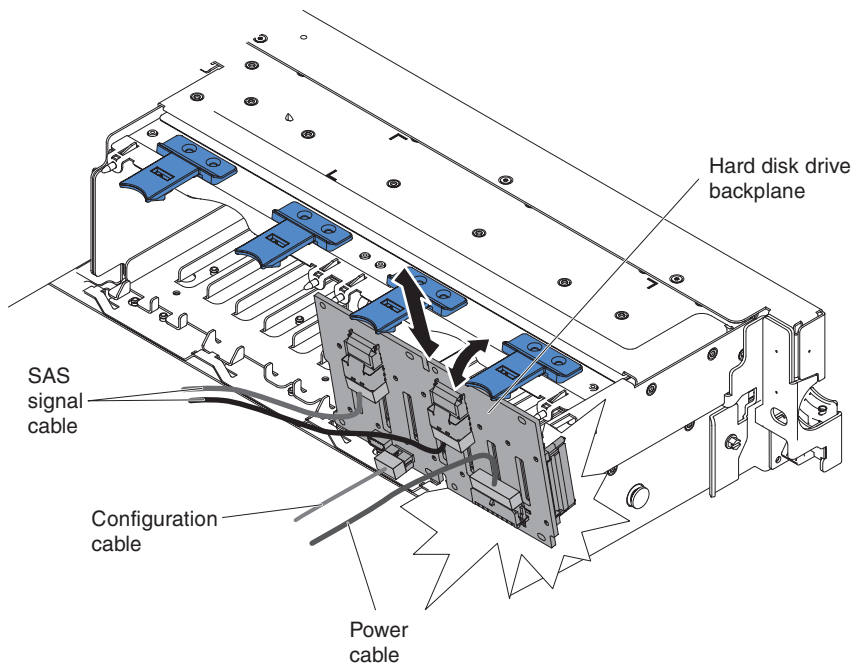


Figure 32. Removing the hot-swap drive backplane

Procedure

1. Read the safety information that begins on page Safety and “Installation guidelines” on page 60.
2. Follow the procedure in “Removing a file module and disconnecting power” on page 58 to suspend the file module from the cluster and shut it down and disconnect all power cords and external cables.
3. Slide the file module out of the rack.
4. Remove the cover. For more information, see Removing the cover.
5. Pull the hard disk drives or fillers out of the file module slightly to disengage them from the backplane.
6. To obtain more working room, remove the fans.
7. Lift the backplane out of the file module by pulling it toward the rear of the file module and then lifting it up.
8. Disconnect the backplane power cable, SAS signal cable, and configuration cable.
9. If you are instructed to return the backplane, follow all packaging instructions, and use any packaging materials for shipping that are supplied to you.

Installing the hot-swap drive backplane

The following procedure is for a Tier 1 customer replaceable unit (CRU). Replacement of Tier 1 CRUs is your responsibility. If IBM installs a Tier 1 CRU at your request, you will be charged for the installation. Service agreements can be purchased so that you can ask IBM to replace these units.

About this task

To install the replacement hot-swap drive backplane, complete the following steps.

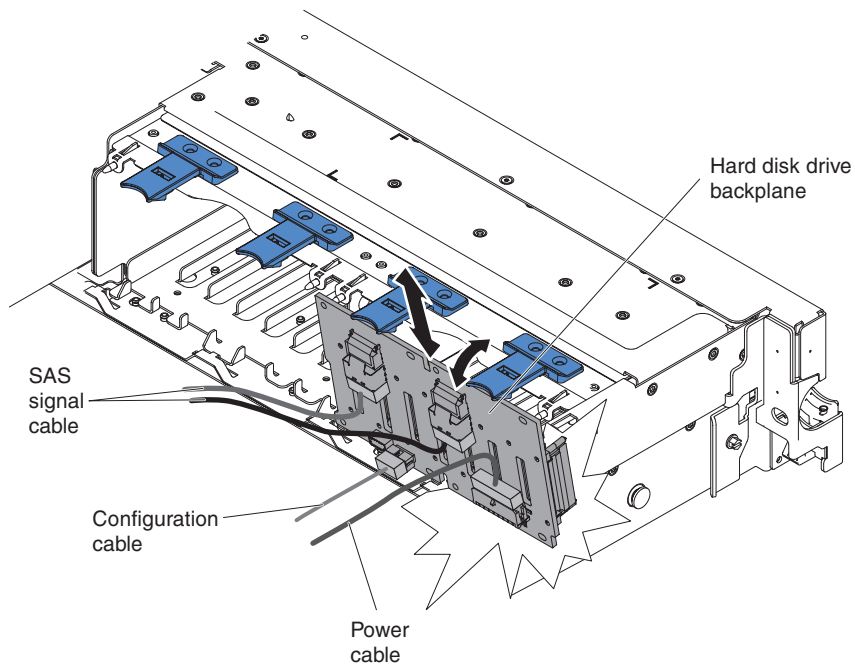


Figure 33. Installing the hot-swap drive backplane

Procedure

1. Connect the power and signal cables to the replacement backplane.
2. Align the backplane with the backplane slot in the chassis and the small slots on top of the hard disk drive cage.
3. Lower the backplane into the slots on the chassis.
4. Rotate the top of the backplane until the front tab clicks into place into the latches on the chassis.
5. Insert the hard disk drives and the fillers the rest of the way into the bays.
6. Replace the fan bracket and fans if you removed them.
7. Install the cover. For more information, see *Installing the cover*.
8. Slide the file module into the rack.
9. Follow the steps at the end of the procedure in “Removing a file module and disconnecting power” on page 58 to suspend the file module to reconnect the file module and resume its use in the cluster.

Removing a microprocessor and heat sink

IBM authorized service providers can remove and replace a microprocessor and heat sink in the file module. The following procedure is for a field replaceable unit (FRU). FRUs must be installed only by trained service technicians.

About this task

Attention:

- Always use the microprocessor installation tool to remove a microprocessor. Failing to use the microprocessor installation tool may damage the microprocessor sockets on the system board. Any damage to the microprocessor sockets may require replacing the system board.
- Microprocessors are to be removed only by trained service technicians.
- Do not allow the thermal grease on the microprocessor and heat sink to come in contact with anything. Contact with any surface can compromise the thermal grease and the microprocessor socket.
- Dropping the microprocessor during installation or removal can damage the contacts.
- Do not touch the microprocessor contacts; handle the microprocessor by the edges only. Contaminants on the microprocessor contacts, such as oil from your skin, can cause connection failures between the contacts and the socket.

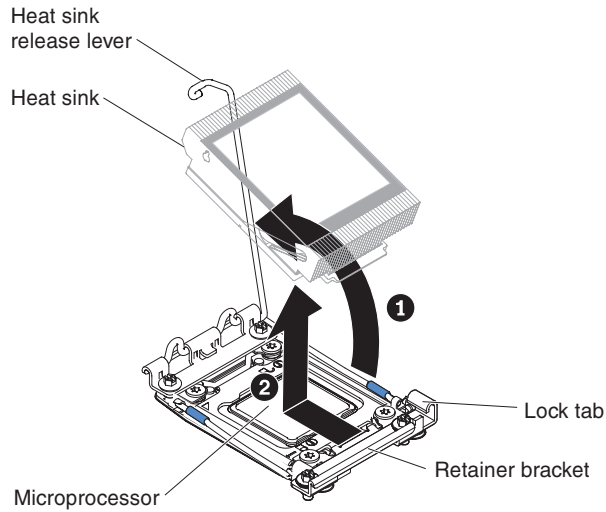
To remove a microprocessor and heat sink, complete the following steps:

Procedure

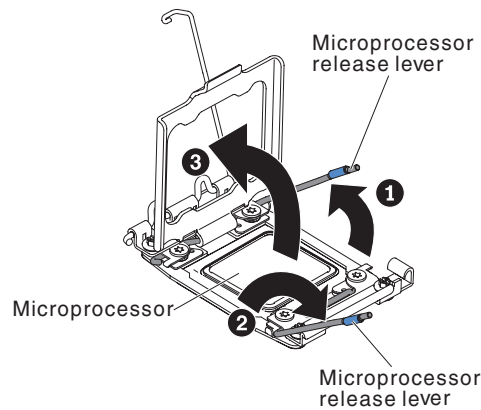
1. Read the Safety information, “Handling static-sensitive devices” on page 62, and “Installation guidelines” on page 60.
2. Follow the procedure in “Removing a file module and disconnecting power” on page 58 to suspend the file module from the cluster and shut it down, and then disconnect all power cords and external cables.
3. Remove the cover (see “Removing the cover” on page 89).
4. Remove the following components, if necessary:
 - PCI riser-card assembly 1 (see “Removing a PCI riser-card assembly” on page 107)
 - DIMM air baffle (see “Removing the air baffle” on page 103)
5. Disconnect any cables that impede access to the heat sink and the microprocessor.
6. Locate the microprocessor to be removed (see System-board internal connectors).
7. Remove the heat sink.

Attention: Do not touch the thermal material on the bottom of the heat sink. Touching the thermal material will contaminate it. If the thermal material on the microprocessor or heat sink becomes contaminated, you must wipe off the contaminated thermal material on the microprocessor or heat sink with the alcohol wipes and reapply clean thermal grease to the heat sink.

- a. Open the heat sink release lever to the fully open position.
- b. Lift the heat sink out of the file module. After removal, place the heat sink (with the thermal grease side up) on a clean, flat surface.



8. Open the microprocessor socket release levers and retainer:



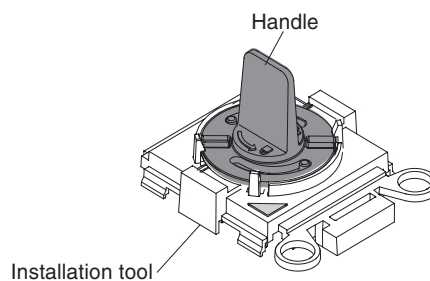
- a. Identify which release lever is labeled as the first release lever to open and open it.
- b. Open the second release lever on the microprocessor socket.
- c. Open the microprocessor retainer.

Attention: Do not touch the connectors on the microprocessor and the microprocessor socket.

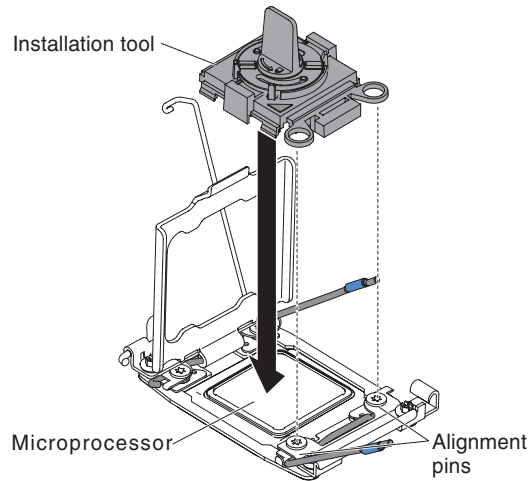
9. Install the microprocessor on the microprocessor installation tool.

Note: If you are replacing a microprocessor, use the empty installation tool that comes with the CRU to remove the microprocessor.

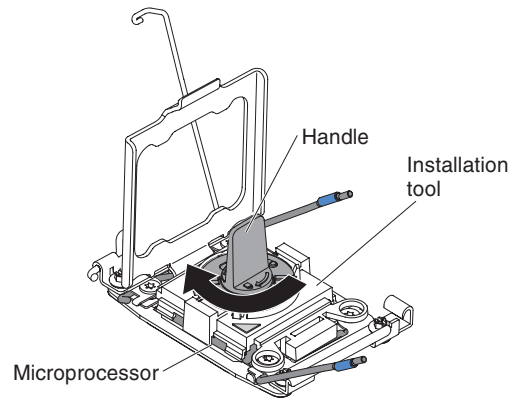
- a. Twist the handle on the microprocessor tool counterclockwise so that it is in the open position.



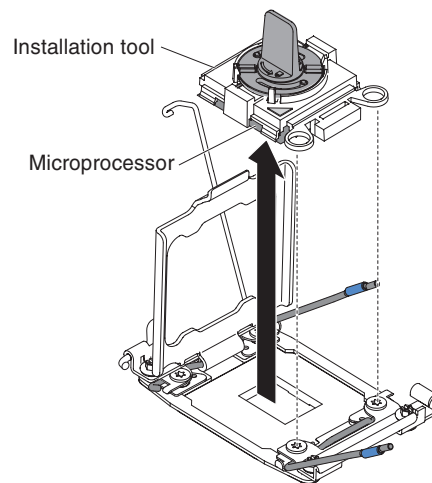
- b. Align the installation tool with the alignment pins on the microprocessor socket and lower the tool on the microprocessor. The installation tool rests flush on the socket only if aligned correctly.



- c. Twist the handle on the installation tool clockwise.



- d. Lift the microprocessor out of the socket.



10. If you do not intend to install a microprocessor on the socket, install the socket cover that you removed in step 8 on page 138 of "Installing a microprocessor and heat sink" on page 135 on the microprocessor socket.

Attention: The pins on the socket are fragile. Any damage to the pins may require replacing the system board.

11. If you are instructed to return the microprocessor, follow all packaging instructions, and use any packaging materials for shipping that are supplied to you.

Installing a microprocessor and heat sink

IBM authorized service providers can remove and replace a microprocessor and heat sink in the file module. The following procedure is for a field replaceable unit (FRU). FRUs must be installed only by trained service technicians.

About this task

The following notes describe the type of microprocessor that the file module supports and other information that you must consider when you install a microprocessor and heat sink:

- Microprocessors are to be installed only by trained service technicians.
- A 2073-720 file module supports one (1) microprocessor. See Parts listing for 2073-720 file modules.
- The microprocessor must always be installed in microprocessor socket 1 on the system board.
- The air baffle must be installed to provide proper system cooling.
- If you have to replace the microprocessor, call IBM Remote Technical Support for service.
- If the thermal-grease protective cover (for example, a plastic cap or tape liner) is removed from the heat sink, do not touch the thermal grease on the bottom of the heat sink or set down the heat sink. For more information about applying or working with thermal grease, see “Removing and replacing the thermal grease” on page 139.

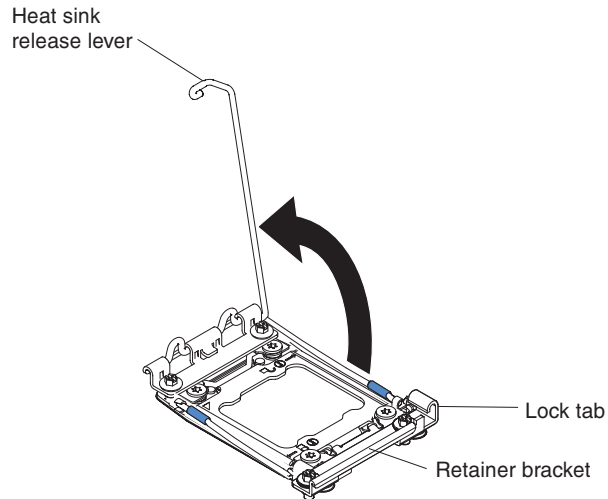
Note: Removing the heat sink from the microprocessor destroys the even distribution of the thermal grease and requires replacing the thermal grease.

To install an additional microprocessor and heat sink, complete the following steps:

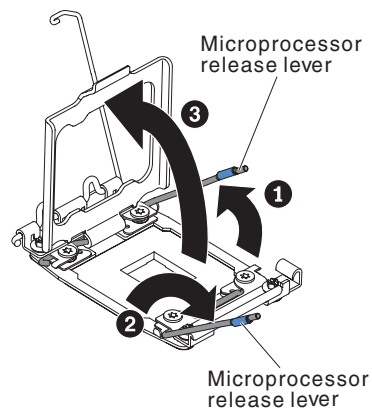
Procedure

1. Read the Safety information and “Installation guidelines” on page 60.
2. Follow the procedure in “Removing a file module and disconnecting power” on page 58 to suspend the file module from the cluster and shut it down, and then disconnect all power cords and external cables.

Attention: When you handle static-sensitive devices, take precautions to avoid damage from static electricity. For details about handling these devices, see “Handling static-sensitive devices” on page 62.
3. Remove the cover (see “Removing the cover” on page 89).
4. Remove the following components, if necessary:
 - PCI riser-card assembly 1 (see “Removing a PCI riser-card assembly” on page 107)
 - DIMM air baffle (see “Removing the air baffle” on page 103)
5. Rotate the heat sink release lever to the open position.



6. Open the microprocessor socket release levers and retainer:

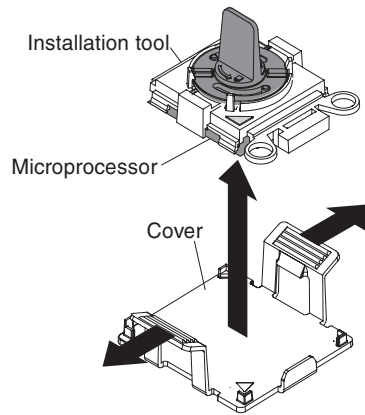


- a. Identify which release lever is labeled as the first release lever to open and open it.
- b. Open the second release lever on the microprocessor socket.
- c. Open the microprocessor retainer.

Attention: Do not touch the connectors on the microprocessor and the microprocessor socket.

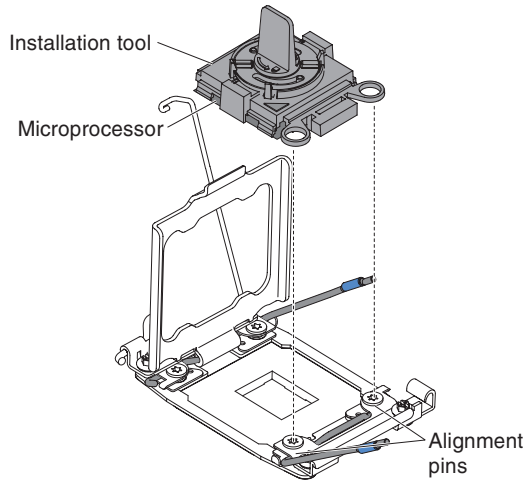
7. Install the microprocessor on the microprocessor socket:

- a. Touch the static-protective package that contains the new microprocessor to any *unpainted* on the chassis or any *unpainted* metal surface on any other grounded rack component; then, carefully remove the microprocessor from the package.
- b. Release the sides of the cover and remove the cover from the installation tool. The microprocessor is preinstalled on the installation tool.

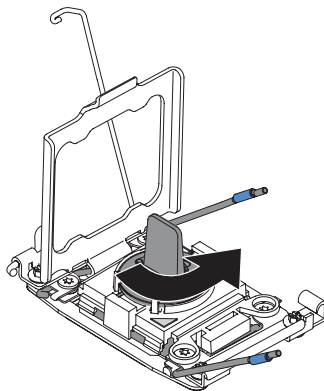


Note: Do not touch the microprocessor contacts. Contaminants on the microprocessor contacts, such as oil from your skin, can cause connection failures between the contacts and the socket.

- c. Align the installation tool with the microprocessor socket. The installation tool rests flush on the socket only if properly aligned.



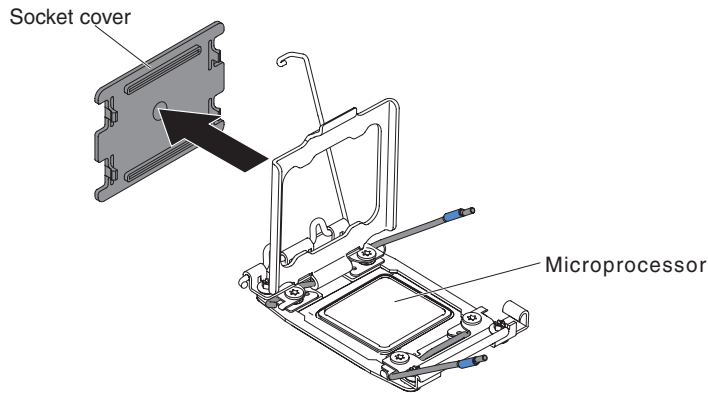
- d. Twist the handle on the microprocessor tool counterclockwise to insert the microprocessor into the socket. The microprocessor is keyed to ensure that the microprocessor is installed correctly. The microprocessor rests flush on the socket only if properly installed.



Attention:

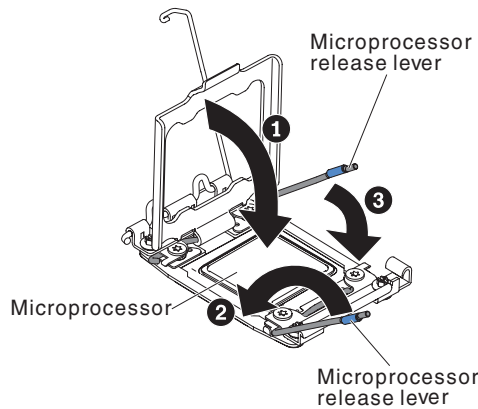
- Do not press the microprocessor into the socket.
- Make sure that the microprocessor is oriented and aligned correctly in the socket before you try to close the microprocessor retainer.
- Do not touch the thermal material on the bottom of the heat sink or on top of the microprocessor. Touching the thermal material will contaminate it.

8. Remove the microprocessor socket cover, tape, or label from the surface of the microprocessor socket, if one is present. Store the socket cover in a safe place.



Attention: When you handle static-sensitive devices, take precautions to avoid damage from static electricity. For details about handling these devices, see “Handling static-sensitive devices” on page 62.

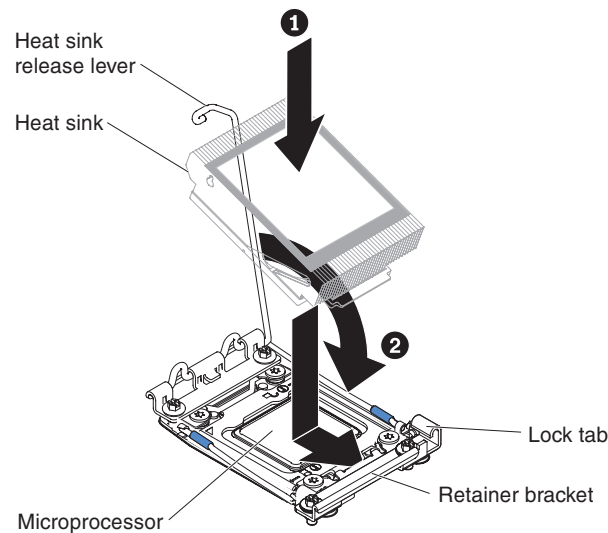
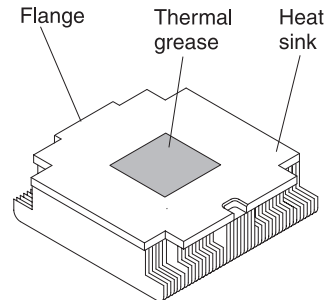
9. Close the microprocessor socket release levers and retainer:



- a. Close the microprocessor retainer on the microprocessor socket.
 - b. Identify which release lever is labeled as the first release lever to close and close it.
 - c. Close the second release lever on the microprocessor socket.
10. Install the heat sink.

Attention:

- Do not set down the heat sink after you remove the plastic cover.
- Do not touch the thermal grease on the bottom of the heat sink after you remove the plastic cover. Touching the thermal grease will contaminate it. See “Removing and replacing the thermal grease” for more information.



- a. Remove the plastic protective cover from the bottom of the heat sink.
 - b. Position the heat sink over the microprocessor. The heat sink is keyed to assist with proper alignment.
 - c. Align and place the heat sink on top of the microprocessor in the retention bracket, thermal material side down.
 - d. Press firmly on the heat sink.
 - e. Rotate the heat sink release lever to the closed position and hook it underneath the lock tab.
11. Reinstall the air baffle (see “Installing the air baffle” on page 104).
 12. Install the cover (see “Installing the cover” on page 90).
 13. Slide the file module into the rack.
 14. Follow the steps at the end of the procedure “Removing a file module and disconnecting power” on page 58 to reconnect the file module and resume its use in the cluster.

Removing and replacing the thermal grease

IBM authorized service providers must replace the thermal grease when the heat sink has been removed from the top of a microprocessor in the file module and the

heat sink is going to be reused or when debris is found in the grease. The following procedure is for a field replaceable unit (FRU). FRUs must be installed only by trained service technicians.

About this task

The thermal grease must be replaced whenever the heat sink has been removed from the top of the microprocessor and is going to be reused or when debris is found in the grease.

When you are installing the heat sink on the same microprocessor that it was removed from, make sure that the following requirements are met:

- The thermal grease on the heat sink and microprocessor is not contaminated.
- Additional thermal grease is not added to the existing thermal grease on the heat sink and microprocessor.

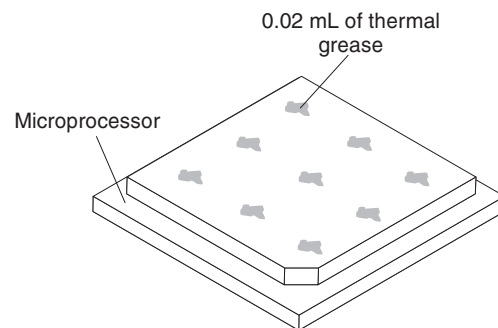
To replace damaged or contaminated thermal grease on the microprocessor and heat exchanger, complete the following steps:

Procedure

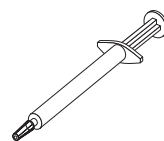
1. Read the Safety information, "Handling static-sensitive devices" on page 62, and "Installation guidelines" on page 60.
2. Place the heat-sink assembly on a clean work surface.
3. Remove the cleaning pad from its package and unfold it completely.
4. Use the cleaning pad to wipe the thermal grease from the bottom of the heat exchanger.

Note: Make sure that all of the thermal grease is removed.

5. Use a clean area of the cleaning pad to wipe the thermal grease from the microprocessor, and then dispose of the cleaning pad after all of the thermal grease is removed.



6. Use the thermal-grease syringe to place 9 uniformly spaced dots of 0.02 mL each on the top of the microprocessor. The outermost dots must be within approximately 5 mm of the edge of the microprocessor; this is to ensure uniform distribution of the grease.



Note: If the grease is properly applied, approximately half of the grease will remain in the syringe.

7. Install the heat sink onto the microprocessor as described in Install the heat sink.

Removing a heat-sink retention module

IBM authorized service providers can remove and replace a heat-sink retention module in the file module. The following procedure is for a field replaceable unit (FRU). FRUs must be installed only by trained service technicians.

About this task

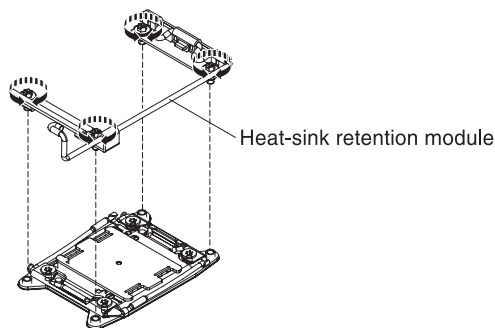
To remove a heat-sink retention module, complete the following steps:

Procedure

1. Read the Safety information and “Installation guidelines” on page 60.
2. Follow the procedure in “Removing a file module and disconnecting power” on page 58 to suspend the file module from the cluster and shut it down, and then disconnect all power cords and external cables.
3. Remove the cover (see “Removing the cover” on page 89).
4. Remove the applicable air baffle, and then remove the heat sink and microprocessor. See “Removing a microprocessor and heat sink” on page 131 for instructions, and then continue with step 5.

Attention: When you remove a microprocessor and heat sink, be sure to keep each heat sink with its microprocessor for reinstallation.

5. Use a screwdriver and remove the four screws that secure the retention module to the system board; then, lift the retention module from the system board.



6. If you are instructed to return the heat-sink retention module, follow all packaging instructions, and use any packaging materials for shipping that are supplied to you.

Installing a heat-sink retention module

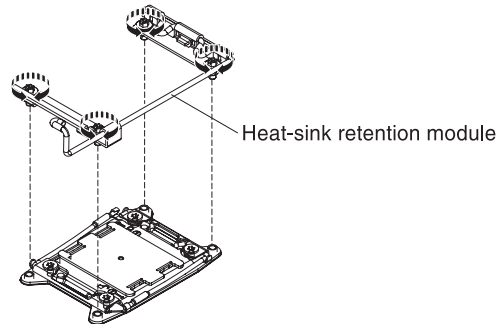
IBM authorized service providers can remove and replace a heat-sink retention module in the file module. The following procedure is for a field replaceable unit (FRU). FRUs must be installed only by trained service technicians.

About this task

To install a heat-sink retention module, complete the following steps:

Procedure

1. Read the Safety information and “Installation guidelines” on page 60.
2. Align the retention module with the holes on the system board.
3. Use a screwdriver to reinstall the four screws.



4. Reinstall the microprocessor and heat sink (see “Installing a microprocessor and heat sink” on page 135).
5. Reinstall the air baffle (see “Installing the air baffle” on page 104).
6. Install the cover (see “Installing the cover” on page 90).
7. Slide the file module into the rack.
8. Follow the steps at the end of the procedure “Removing a file module and disconnecting power” on page 58 to reconnect the file module and resume its use in the cluster.

Removing the system board

IBM authorized service providers can remove and replace the system board in the file module. The following procedure is for a field replaceable unit (FRU). FRUs must be installed only by trained service technicians.

About this task

To remove the system board, complete the following steps.

Procedure

1. Read the Safety information and “Installation guidelines” on page 60.
2. Follow the procedure in “Removing a file module and disconnecting power” on page 58 to suspend the file module from the cluster and shut it down, and then disconnect all power cords and external cables.
3. Pull the power supplies out of the rear of the file module, just enough to disengage them from the file module.
4. Remove the file module cover (see “Removing the cover” on page 89).
5. Remove the riser-card assemblies with adapters (see “Removing a PCI riser-card assembly” on page 107).

Attention: Place all removed components on a static-protective surface for reinstallation.

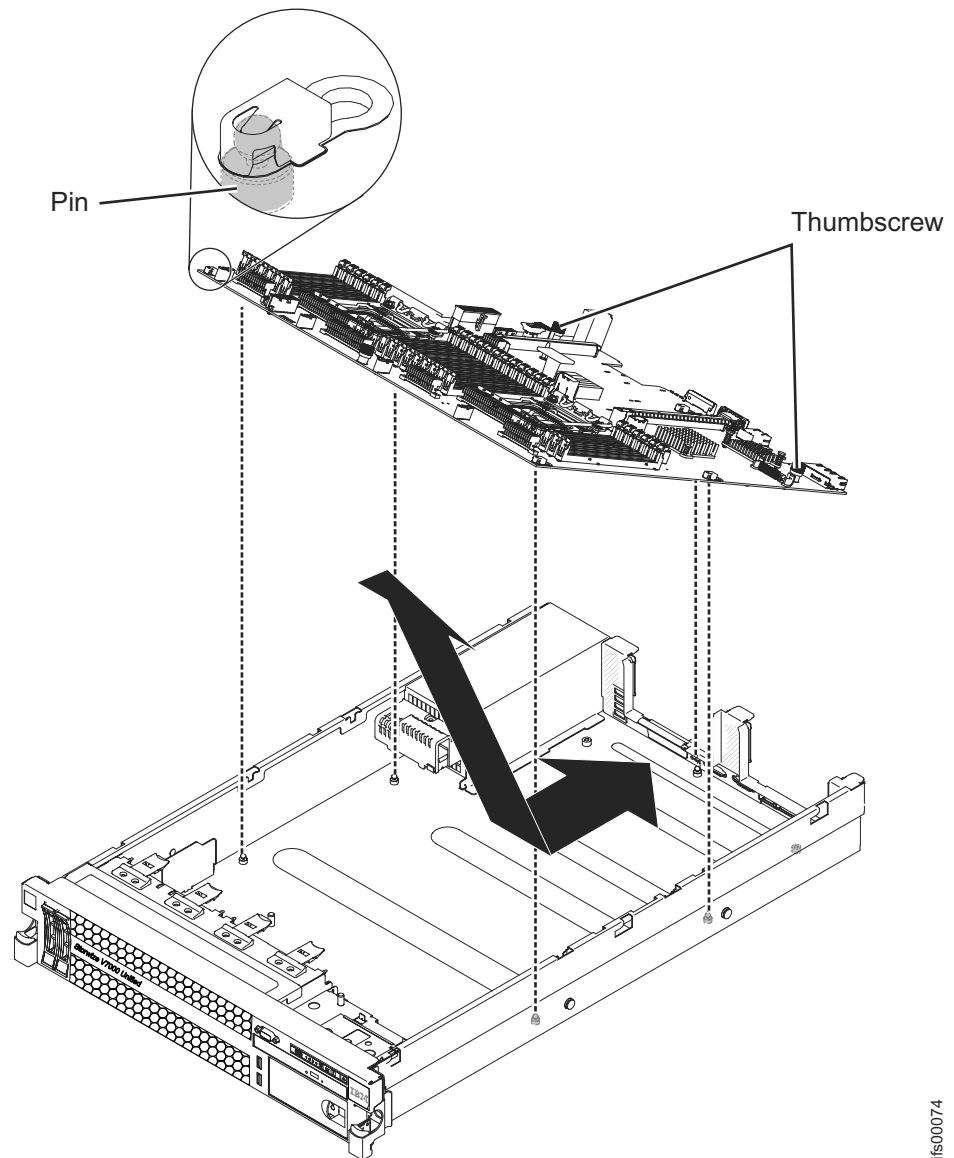
6. Remove the 10 Gbps Ethernet adapter (see Removing a 10-Gbps Ethernet adapter).
7. Remove the air baffle (see “Removing the air baffle” on page 103).
8. Remove all DIMMs, and place them on a static-protective surface for reinstallation (see “Removing a memory module” on page 118).

Important: Before you remove the DIMMs, note which DIMMs are in which connectors. You must install them in the same configuration on the replacement system board.

9. Remove the fans (see “Removing a hot-swap fan” on page 121).
10. Disconnect all cables from the system board.

Attention:

- In the following step, do not allow the thermal grease to come in contact with anything, and keep each heat sink paired with its microprocessor for reinstallation. Contact with any surface can compromise the thermal grease and the microprocessor socket; a mismatch between the microprocessor and its original heat sink can require the installation of a new heat sink.
 - Disengage all latches, release tabs or locks on cable connectors when you disconnect all cables from the system board. Failing to release them before removing the cables will damage the cable sockets on the system board. The cable sockets on the system board are fragile. Any damage to the cable sockets may require replacing the system board.
11. Remove the microprocessor heat sink and microprocessor, and then place them on a static-protective surface for reinstallation (see “Removing a microprocessor and heat sink” on page 131).
 12. Pull out and lift up the pin and the thumbscrews on each side of the system board.



ifs00074

13. Slide the system board forward and tilt it away from the power supplies. Using the two lift handles on the system board, pull the system board out of the file module.
14. If you are instructed to return the system board, follow all packaging instructions, and use any packaging materials for shipping that are supplied to you.
15. Remove the socket covers from the microprocessor sockets on the new system board and place them on the microprocessor sockets of the system board you are removing.

Attention: Make sure to place the socket covers for the microprocessor sockets on the system board before you return the old system board.

Installing the system board

IBM authorized service providers can remove and replace the system board in the file module. The following procedure is for a field replaceable unit (FRU). FRUs must be installed only by trained service technicians.

Before you begin

Notes:

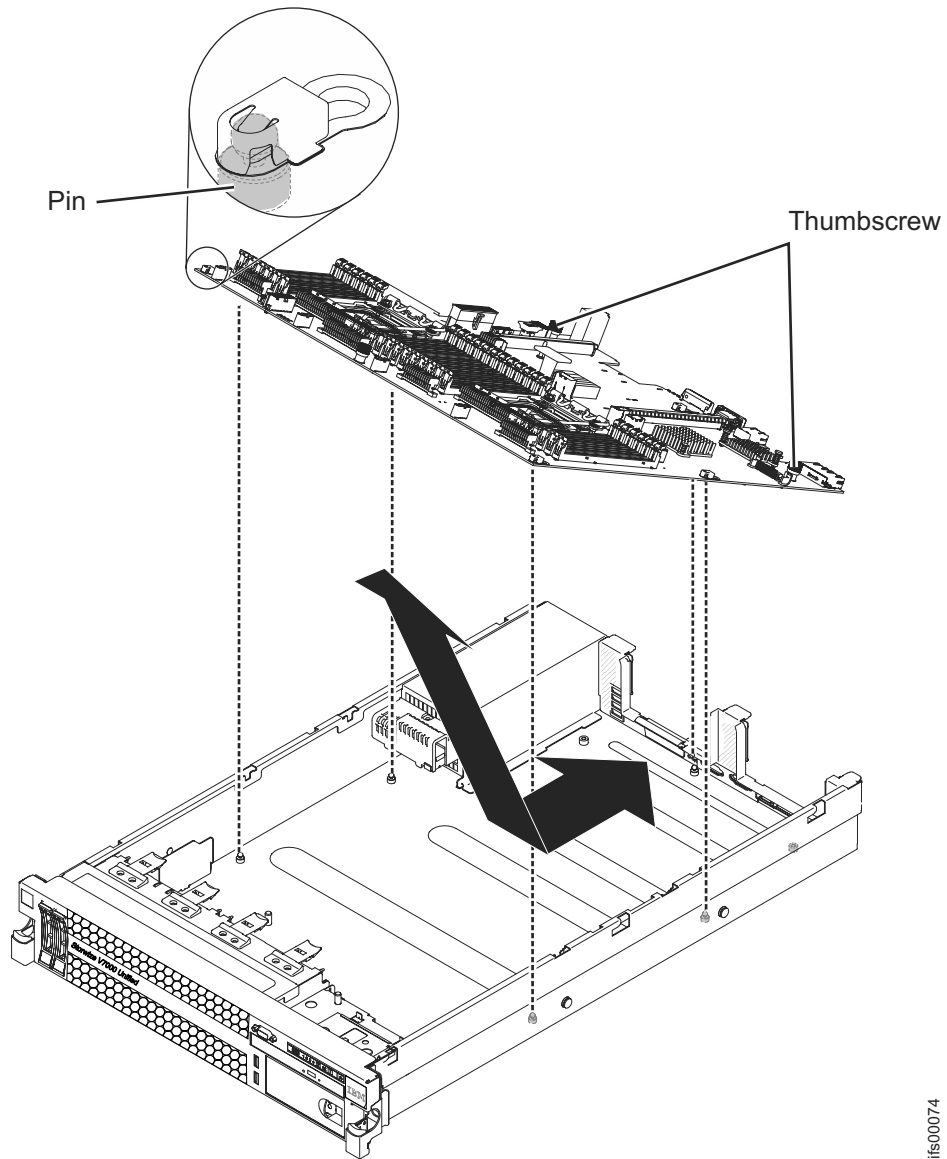
1. When you reassemble the components in the file module, be sure to route all cables carefully so that they are not exposed to excessive pressure.
2. When you replace the system board, you must either update the file module with the latest firmware or restore the pre-existing firmware that the customer provides on a diskette or CD image. Make sure that you have the latest firmware or a copy of the pre-existing firmware before you proceed.

Important: Some cluster solutions require specific code levels or coordinated code updates. If the device is part of a cluster solution, verify that the latest level of code is supported for the cluster solution before you update the code.

3. Update the vital product data (VPD) through the file module firmware update procedure.
4. If you see the error message *Non-compatible/non-supported CPU, see PDSG for more information* appears, the microprocessor that you installed is not supported. See Parts listing for 2073-720 file modules for a list of supported microprocessors.

About this task

To reinstall the system board, complete the following steps.



ifs00074

Procedure

1. Align the system board at an angle, as shown in the illustration; then, rotate and lower it flat and slide it back toward the rear of the file module. Make sure that the rear connectors extend through the rear of the chassis.
2. Reconnect to the system board the cables that you disconnected in step 10 on page 143 of "Removing the system board" on page 142.
3. Rotate the system-board thumbscrews toward the rear of the file module until the latch clicks into place.
4. Install the fans.
5. Install each microprocessor with its matching heat sink (see "Installing a microprocessor and heat sink" on page 135).
6. Install the DIMMs (see "Installing a memory module" on page 119).

7. Install the air baffle (see “Installing the air baffle” on page 104), making sure that all cables are out of the way.
8. If necessary, install the Ethernet adapter.
9. If necessary, install the virtual media key.
10. Install the PCI riser-card assemblies and all adapters (see “Installing a PCI riser-card assembly” on page 108).
11. Install the cover (see “Installing the cover” on page 90).
12. Push the power supplies back into the file module.
13. Slide the file module into the rack.
14. Follow the steps at the end of the procedure “Removing a file module and disconnecting power” on page 58 to reconnect the file module and resume its use in the cluster.

Results

Important: Perform the following updates:

- Start the Setup utility and reset the configuration.
 - Set the system date and time.
 - Set the power-on password.
 - Reconfigure the file module.
- Either update the file module with the latest RAID firmware or restore the pre-existing firmware from a diskette or CD image.
- Update the UUID.
- Update the DMI/SMBIOS.

Important: Some cluster solutions require specific code levels or coordinated code updates. If the device is part of a cluster solution, verify that the latest level of code is supported for the cluster solution before you update the code.

Setting the machine type, model, and serial number

This procedure is for IBM authorized service providers who, after replacing a system board in one of the file modules, must reset the machine type, model, and serial number vital product data using the Advanced Settings Utility (ASU). The following procedure is for a field replaceable unit (FRU). FRUs must be installed only by trained service technicians.

About this task

The ASU package is part of the Storwize V7000 Unified code. ASU is available to authorized service personnel from the command-line interface (CLI) on the file module. Use ASU to modify selected settings in the integrated-management-module (IMM)-based Storwize V7000 Unified file modules.

You can use the ASU remotely from your laptop (if allowed) or from a file module that has Storwize V7000 Unified installed.

Procedure

1. Access and log in to the Storwize V7000 Unified system from the CLI.
2. Issue the following command to view the current settings for the machine type and model:

```
asu show SYSTEM_PROD_DATA.SysInfoProdName
```

3. Issue the ASU command on the Storwize V7000 Unified file module to set the machine type and model:
asu set SYSTEM_PROD_DATA.SysInfoProdName 2073-720
4. Issue the following command to verify that you set the machine type and model number correctly:
`asu show SYSTEM_PROD_DATA.SysInfoProdName`
5. Issue the following command to view the current setting of the serial number:
`asu show SYSTEM_PROD_DATA.SysInfoSerialNum`
6. Issue the following ASU command on the Storwize V7000 Unified file module to set the serial number:
`asu set SYSTEM_PROD_DATA.SysInfoSerialNum xxxxx`
 The variable `xxxxx` in the command stands for the serial number.
7. Issue the following command to verify that you set the serial number correctly:
`asu show SYSTEM_PROD_DATA.SysInfoSerialNum`

How to reset/reboot server IMM interface

About this task

Use this procedure to initiate a reset/reboot of the iMM interface located on the file module. This action is not disruptive to the system operations and should only be used when directed to clear out fault conditions.

Note: This procedure requires root access to the file module node.

Procedure

1. Log into the active management file module using root.
2. If this is the file module requiring action, then continue with step 3. If this is not the file module to reset:
 - a. Type `ssh <node name>` and press **Enter**. For example: `ssh mgmt002st001`
3. Type `asu rebootimm --kcs` and press **Enter**.

Note: If you are using a telnet connection, you can reboot using `resetsp`.

- a. Wait for the IMM reboot to complete (typically about 3 minutes). If the reboot is successful, the output of the previous command will be similar to the following:

```
IBM Advanced Settings Utility version 3.62.71B
Licensed Materials - Property of IBM
(C) Copyright IBM Corp. 2007-2010 All Rights Reserved
```

```
Try to connect to the primary node to get nodes number.
Connected via IPMI device driver (KCS interface)
Connected to primary node.
Nodes number is 1
Unable to locate a script required to set up LAN-over-USB device,
  tried location cdc_interface.sh
```

```
Connect to imm to reboot.
Issuing reset command to imm.
Checking if the imm has reset yet. (attempt 0)
imm has started the reset.
Disconnect from imm
```

- b. Wait for about 2 minutes to allow the iMM to completely reboot.

File module software problems

This section helps you to identify and resolve file module software problems.

About this task

Logical devices and physical port locations for a 2073-720 file module

Use this table to help identify logical devices, file module roles used, and physical locations on a 2073-720 file module.

Table 32. Default logical devices and physical port locations for a 2073-720 file module

| Logical Ethernet device name | Device description | Physical location information |
|------------------------------|--|---|
| mgmtsl0_0 | Internal connection between the file modules | Port 1 - Built-In xSeries Ethernet Port |
| mgmtsl0_1 | Internal connection between the file modules | Port 2 - Built-In xSeries Ethernet Port |
| ethXsl0_0 | 1-Gbps Public Network | Port 3 - Built-In xSeries Ethernet Port |
| ethXsl0_1 | 1-Gbps Public Network | Port 4 - Built-In xSeries Ethernet Port |
| ethXsl1_0 | 1-Gbps Public Network | Port 7 - Quad Port 1-GB Ethernet adapter in PCI slot 2 |
| ethXsl1_1 | 1-Gbps Public Network | Port 8 - Quad Port 1-GB Ethernet adapter in PCI slot 2 |
| ethXsl1_2 | 1-Gbps Public Network | Port 9 - Quad Port 1-GB Ethernet adapter in PCI slot 2 |
| ethXsl1_3 | 1-Gbps Public Network | Port 10 - Quad Port 1-GB Ethernet adapter in PCI slot 2 |
| ethXsl2_0 | 10-Gbps Public network | Port 5 / 10-Gbps Ethernet adapter |
| ethXsl2_1 | 10-Gbps Public network | Port 6 / 10-Gbps Ethernet adapter |

Note: The physical port locations on your system might differ from the port locations that are given in the preceding table if the port bonding has been changed.

Management node role failover procedures

The following procedures either restart the management service or initiate a management service failover from the file module hosting the active management node role to the file module hosting the passive management node role.

Once complete, the file module that previously hosted the active management node role now hosts the passive management node role. The file module that previously hosted the passive management node role now hosts the active management node role.

Note: All of these tasks require a user that is configured as a CLI admin. Other users cannot perform these tasks.

Determining the service IP for the management node roles

Use this procedure to identify the service IP addresses for the file modules that host the management node roles.

About this task

You need the service IP address of a file module that hosts a management node role to perform a management failover from the file module that hosts the active management node role to the file module that hosts the passive management node role, when the active management node fails and the current management IP does not respond.

Procedure

1. Attempt to open an SSH connection to the root IP of one of the file modules hosting a management node role.

Note: Run the CLI command **lsnode**.

- If you get output from **lsnode** that shows the system configuration (as in Example 1), proceed to step 2.
- If you get a message that the management service is stopped or is not running (as in Example 2), attempt to log out and log in to the other file module hosting a management node role. If the other file module is not responding, refer to “Performing management node role failover procedures for failure conditions” on page 151.

Example 1: System configuration output from **lsnode** displays similar to the following example:

```
[root@kq186wx.mgmt001st001 ~]# lsnode
Hostname IP Description Role
mgmt001st001 172.31.8.2 active management node management,interface,storage
mgmt002st001 172.31.8.3 passive management node management,interface,storage

Product version Connection status GPFS status CTDB status Last updated
1.3.0.0-50a OK active active 8/30/11 8:36 PM
1.3.0.0-50a OK active active 8/30/11 8:36 PM

EFSSG1000I The command completed successfully.
[root@kq186wx.mgmt001st001 ~]#
```

Example 2: Output for **lsnode** for a management service that is not running is similar to the following example:

```
[root@kq186wx.mgmt002st001 ~]# lsnode
EFSSG0026I Cannot execute commands because Management Service is stopped.
Use startmgtsrv to restart the service.
```

2. Determine the service IP addresses for the file modules hosting a management node role by running the CLI command **lsnwmgt**. Output that is similar to the following example is displayed:

```
[root@kq186wx.mgmt001st001 ~]# lsnwmgt
Interface Service IP Node1 Service IP Node2
ethX0 9.11.137.128 9.11.137.129

Management IP Network Gateway VLAN ID
9.11.137.127 255.255.254.0 9.11.136.1
EFSSG1000I The command completed successfully.
```

The following table describes the nodes that are identified by the command:

Table 33. Hostname and service IP reference

| Host name | Corresponding Service IP reference |
|--------------|------------------------------------|
| mgmt001st001 | Service IP Node1 |
| mgmt002st001 | Service IP Node2 |

Performing management node role failover on a “good” system

Use this procedure to complete a failover process when both file modules appear to be operating correctly.

About this task

If both file modules are operating correctly with regard to management services, perform the following procedure to failover the active management node to the passive management node.

Procedure

1. Open an SSH connection to the service IP of the file module hosting the passive management node role.
Refer to “Determining the service IP for the management node roles” on page 149, if necessary.
2. To initiate the management services on the passive node and perform the switchover from the active management node, run the **startmgtsrv** command.

Note: If you run the **startmgtsrv** command from the node that is becoming active, you first need to run the **setcluster** command to set the cluster environment variable. If you see the following error message when running the command, wait until the initialization has completed before running **setcluster** again:

```
IBM SONAS management service is starting up
EFSSG0654I The Management Service is starting up.
```

After you run the **startmgtsrv** command, the system displays information that is similar to the following example:

```
[yourlogon@yourmachine.mgmt002st001 ~]# startmgtsrv
Other node is reachable and its management state is active.
Are you sure? (Y/N)Y
EFSSG0717I Takeover initiated by root - this may take a few minutes
EFSSG0544I Takeover of the management functions from the active
node was successful
```

Results

Once complete, the file module that previously hosted the active management node role now hosts the passive management node role. The file module that previously hosted the passive management node role now hosts the active management node role.

Performing management node role failover procedures for failure conditions

Use this topic to isolate and perform file module failover for failed conditions.

About this task

“Failed conditions” exist when the active management node has failed and is not responding. This failure is exposed by the inability to access the file module, run CLI commands, and/or access the GUI.

Note: If the management IP is accessible and you can establish an SSH connection and run CLI tasks, do not perform a management failover. Refer to .

Complete the following procedure to address this issue.

Important: Performing this procedure does not repair a problem that caused the current system condition. This procedure provides for system access and troubleshooting to restart the management services or to failover the management service from a failed file module to the passive management node on the other file module. Once you complete this procedure, follow the appropriate troubleshooting documentation to isolate and repair the core problem that caused this condition.

Procedure

1. Attempt to open an SSH connection to the service IP of the file module with the active management node role. Refer to . Was the connection successful?
 - **Yes** - proceed to step 2
 - **No** - proceed to step 5
2. If the connection is successful, verify that the management service is not running by executing the CLI command **lsnode** and then reviewing the output.
 - If the system responds with output for the **lsnode** command, then the management services are already running. If you still cannot access the GUI, refer to . If the GUI is accessible, then the management services are properly running on the active management node and no failover is needed. If you want to initiate a failover, refer to “Performing management node role failover on a “good” system” on page 150.
 - If the system responds that the management service is not running, proceed to the next step.

Note: For a management service that is not running, the system displays information similar to the following example:

```
[yourlogon@yourmachine.mgmt002st001 ~]# lsnode
EFSSG0026I Cannot execute commands because Management Service is stopped.
Use startmgtsrv to restart the service.
```

3. Attempt to stop and restart the management services. Wait for the commands to complete.
 - a. Run the CLI command **stopmgtsrv**.
 - b. Run the CLI command **startmgtsrv**. This restarts the management services.
4. Once command execution is complete:
 - a. Verify that the management service is running by again executing the CLI command **lsnode**. If the system responds that the management service is not running, proceed to step 5.
 - b. If the **lsnode** output provides system configuration information, verify that you can access and log in to the GUI. If you still have trouble with accessing the GUI, refer to .
 - c. If the problem appears to be resolved, DO NOT perform steps 5-9. Instead, using the GUI event log, follow the troubleshooting documentation to isolate the software or hardware problem that might have caused this issue.

Attention: Perform the following steps only if the active management node is not responding properly. These steps initiate a startup and failover of the management services on the file module hosting the passive management node role.

5. Open an SSH connection to the service IP and port of the file module with the passive management node role. Refer to “Determining the service IP for the management node roles” on page 149.
6. Verify the management service status by running the CLI command **lsnode**. If the file file module responds that the management service is not running, proceed to the next step.
7. Run the CLI command **startmgtsrv**. This starts the management services on the passive node.
8. Once command execution is complete:
 - a. Verify that the management service is running by again executing the CLI command **lsnode**.

- b. If the **1snode** output provides system configuration information, verify that you can access and log in to the GUI. If you still have trouble with accessing the GUI, refer to .
 - c. If the **1snode** output reports that the management service is still not running, contact IBM support.
9. Using the GUI event log, follow the troubleshooting documentation against the file module with the failed management node role to isolate the software or hardware problem that might have caused this issue.

Checking CTDB health

Use this information for checking the health of the clustered trivial database (CTDB) on each file module.

About this task

CTDB checks the health status of the Storwize V7000 Unified file modules, scanning elements such as storage access, General Parallel File System (GPFS), networking, Common Internet File System (CIFS) shares, and Network File System (NFS) exports.

An unhealthy file module cannot serve public Internet Protocol (IP) addresses and must be fixed. However, the high availability features of the Storwize V7000 Unified system can mask the unhealthy status from its clients by failing over IP addresses from an unhealthy file module to a healthy file module.

In the management graphical user interface (GUI), select **Monitoring > System** and check the health status for errors and degraded events.

Procedure

To check the status using either the GUI or the command-line interface (CLI), complete this procedure:

1. To check the CTDB status:
 - With the Storwize V7000 Unified GUI, use the following method:
 - Select **Monitoring > System Details > Interface Nodes > mgmt001st001 > NAS Services**. In the **CTDB state** row, a healthy status is displayed as "Active" and an unhealthy status is displayed as "unhealthy".
 - A "disconnected" status is displayed when this CTDB node could not be reached through the network and is currently not participating in the cluster.

Review the status of both file modules, **1** mgmt001st001 and **2** mgmt002st001, as shown in Figure 34 on page 154.

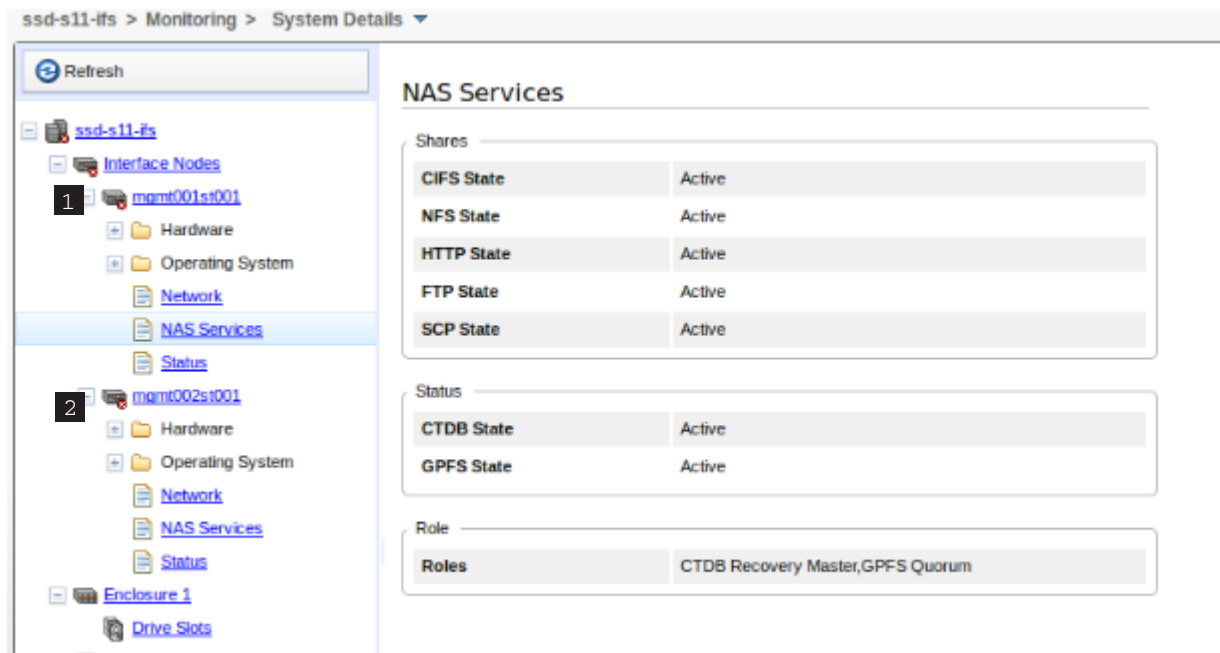


Figure 34. Management GUI showing CTDB status for both file modules

- With the CLI, log in as an admin user, then open the CLI and issue the **lsmode -r** command to determine whether CTDB is active on all nodes.

The system displays information similar to the following:

```
[yourlogin@yourmachine]$ lsmode -r
EFSSG0015I Refreshing data.
Hostname      IP           Description          Role
mgmt001st001 10.254.8.2  active management node management,interface,storage
mgmt002st001 10.254.8.3  passive management node management,interface,storage

Product version Connection status GPFS status CTDB status Last updated
1.3.0.0-55c    OK           active   active
1.3.0.0-55c    OK           active   unhealthy
EFSSG1000I The command completed successfully.
```

In the CTDB Status column, “active” indicates a healthy status and “unhealthy” indicates an error status. A “disconnected” status is displayed when this CTDB node could not be reached through the network and is currently not participating in the cluster.

2. If the CTDB status for a file module is not “active”, perform one or more of the following procedures:
 - Review the health status for any potential network problems. A network failure between a file module and the customer can result in an “UNHEALTHY” CTDB status. Follow the appropriate error code action plans to resolve the network problems. Refer to “Checking network interface availability” on page 160.
 - If the network has been examined without any problems being identified, perform the procedures in “Checking the GPFS file system mount on each file module” on page 155.
 - Refer to the information in “Troubleshooting the System x3650 server” topic in the *IBM Storwize V7000 Unified Information Center* to determine if any additional hardware problems might be causing the “unhealthy” CTDB status.

- Perform a reboot of the unhealthy file module. Refer to “Resuming services on a suspended file module” in the *IBM Storwize V7000 Unified Information Center*.
- If none of the above actions resolves the problem, contact IBM Remote Technical Support.

Checking the GPFS file system mount on each file module

Use this information to identify and resolve problems with General Parallel File System (GPFS) file system mounts on IBM Storwize V7000 Unified file modules.

About this task

A GPFS file system that is not mounted on an Storwize V7000 Unified file module can cause the clustered trivial database (CTDB) status to be 'UNHEALTHY'." The GPFS file system must be mounted on both file modules in the Storwize V7000 Unified product to support dual redundancy and to allow file input/output through all public IP addresses.

Note: You cannot change the cluster and file system configuration, when one of the nodes hosting the GPFS primary or secondary configuration server is not present in the cluster. You can identify the nodes hosting the primary or secondary configuration server in the output of the **lscluster** CLI command. This also applies to disk management operations such as creating or deleting a file system, adding or removing a disk using the CLI commands such as **mkfs**, **rmfs**, **chfs**, and **rp1disk**. It also includes the changes to the cluster configuration such as **addnode** and **delnode**. These CLI commands report an error and fail the operations when this condition is detected in the cluster.

Use the following procedure to get a file system that is not mounted on a file module to be mounted. Contact IBM Remote Technical Support if this procedure does not work.

Procedure

- To identify all of the currently created file systems on the Storwize V7000 Unified system, or on each file module, perform the procedure in “Identifying created and mounted file system mounts.”
- To resolve problems with mounted file systems that are missing, perform the procedure in “Resolving problems with missing mounted file systems” on page 156.
- To resolve problems with stale NFS file systems, perform the procedure in “Resolving stale NFS file systems” on page 157.
- To resolve problems that are not covered by the information that is presented in the previous topics, perform the procedure in “Recovering a GPFS file system” on page 161.

Identifying created and mounted file system mounts

You can identify and resolve problems in GPFS file system mounts on the Storwize V7000 Unified system and file modules.

About this task

Procedure

To identify and resolve problems in file system mounts, perform this procedure:

1. To identify all the currently created file systems on the Storwize V7000 Unified system, log in as the admin user, then enter the **lsfs -r** command from the command-line interface (CLI), as shown in the following example:

```
# lsfs -r
EFSSG0015I Refreshing data.
Cluster   Device name Quota           Def. quota Block size Inodes
kd18pz5.ibm gpfs1       user;group;fileset 256 kB     11373

Replication Dmapi Block allocation type Last update
none        yes  scatter                10/3/11 2:08 PM

EFSSG1000I The command completed successfully.
```

2. To identify the currently created file systems on each Storwize V7000 Unified file module, log in as the root user on the active management node, then enter the **onnode -n mgmt001st001 df | grep ibm** command from the CLI, as shown in the following example:

```
# onnode -n mgmt001st001 df | grep ibm
/dev/gpfs1          3221225472 4590080 3216635392 1% /ibm/gpfs1
```

Repeat the command for another file module by using the **onnode -n mgmt002st001 df | grep ibm** command, for example:

```
# onnode -n mgmt002st001 df | grep ibm
/dev/gpfs1          3221225472 4590080 3216635392 1% /ibm/gpfs1
```

Resolving problems with missing mounted file systems

You can resolve problems with mounted file systems that are missing on Storwize V7000 Unified file modules.

About this task

Display the file system by using the **lsfs -r** command. The **lsmount -r -v** command shows which file modules mount the file system. The Mounted status means that both file modules mount the file system. All other states, Partially, Internally, or Not mounted mean that a file system is not properly mounted.

Procedure

To resolve the problem with the missing mounted file system, perform the following procedure:

1. Log in to the Storwize V7000 Unified CLI as admin.
2. Identify on which file module the file system is missing, for example, mgmt001st001.
3. Mount the missing file system on the file module by using the **mountfs** command.

```
mountfs gpfs0
```
4. Issue the **lsmount** command to verify that all file systems are now mounted on file modules 0 and 1.
5. If the mounted file systems are not consistent across the file modules, reboot the file module on which a file system is missing, and then issue the **lsmount** command.

Reboot the file module by using the management GUI.

If they are not mounted on either file module, then reboot each file module.

6. Use the **lsnode** command to determine when the file modules are back up and when GPFS and CTDB are both active.

The file systems might take several minutes to get mounted after GPFS becomes active on both file modules. More than one reboot might be required to bring the file system back up. Allow time between reboots because the file system might take some time before it comes back up after a reboot.

7. Ensure that the CTDB status is now shown as **active** on both file modules, as described in “Checking CTDB health” on page 153.
8. If a GPFS file system fails to mount, complete the following steps:
 - a. Check the output log of the **lslog** command and look for the latest messages about mounting the file system.

If you find input/output errors and messages about a failure to read the super block, the problem is with the DMAPI clients of the TSM/HSM system.

Check for disk-related problems, such as errors reading from a disk or errors showing a non-existent disk. For these errors, check whether the path to the storage system is working. If it is, verify that the system itself is in working order.

- b. For additional information, refer to the “Diagnostics: Troubleshooting tables” information in “Troubleshooting the System x3650” in the *IBM Storwize V7000 Unified Information Center*.
- c. If file systems remain unmounted, contact IBM support.

Resolving stale NFS file systems

You can resolve problems with stale NFS file systems on Storwize V7000 Unified file modules. A file module might have the file system mounted, but the file system remains inaccessible due to a stale NFS file handle.

About this task

Procedure

To identify and resolve stale file handle problems, complete this procedure:

1. To identify stale NFS file handle problems, log in to the active management node as root user and enter the **onnode all df | grep NFS** command:

```
# onnode all df | grep NFS
```

```
df: `/ibm/gpfs0': Stale NFS file handle
```

2. If the command reports a stale NFS file handle on a particular file system, see “Working with file modules that report a stale NFS file handle” on page 264 for instructions on file system recovery.

Checking user and server authentication issues

If you cannot log in or if a connection cannot be established between servers, such issues could occur as a result of authentication failure.

About this task

If you are sure that you have used the correct user ID and password, your user account might have been deleted or corrupted.

Refer to these topics in the *IBM Storwize V7000 Unified Information Center* “Planning for user authentication”, “Verifying the authentication configuration”, “Establishing user and group mapping for client access”, and “chkauth”.

If you cannot resolve the issue, contact the authentication server administrator to validate or reestablish your account.

Refer to “Managing authentication server integration” for more information about authentication and server configuration.

Resolving the “Missing SRV record in DNS” error

About this task

If the “Missing SRV record in DNS” error displays when you configure the active directory (AD) using the **cfgad** command, similar to the following example, verify that entries for DNS Domain Name, DNS Server, and DNS Search Domains are correct. Also, verify that the DNS server has valid SRV records for that domain.

```
$ cfgad -s 9.9.9.9 -u admin -p ****
(1/9) Fetching the list of cluster file modules.
(2/9) Check if cfgcluster has done the basic configuration successfully.
(3/9) Check whether file modules are
reachable from management file module.
(4/9) Detection of AD server and fetching domain information from AD server.
Missing SRV record in DNS : _ldap._tcp.xxxxx.COM
Missing SRV record in DNS : _ldap._tcp.dc._msdcs.xxxxx.COM
Missing SRV record in DNS : _kerberos._tcp.xxxxx.COM
Missing SRV record in DNS : _kerberos._tcp.dc._msdcs.xxxxx.COM
Necessary DNS entries are missing, the domain join step might fail.
(5/9) Check whether AD server is reachable
from file modules.
(6/9) Joining the domain of the specified ADS.
EFSSG0110C Configure AD failed on cluster. Cause: Error encountered while
executing netjoinAD.sh. Output till failure is :Join to Active Directory
domain with user Administrator
Failed to join domain: failed to find DC for domain SONAS
Error occurred due to reason : Join to Active Directory domain failed
```

If “netgroup” functionality with NIS or LDAP is not working

About this task

If “netgroup” functionality with Network Information Service (NIS) or Lightweight Directory Access Protocol (LDAP) is not working, ensure that you have included a “@” in front of the netgroup name, as shown in the following example:

```
$ mkexport testnetgrp5 /ibm/gpfs0/netgroup5 --nfs "@ng1(rw,no_root_squash)"
```

Do not create a netgroup with an IP address; instead, use a host name. The host name that is defined in a netgroup should resolve to a valid IP address that points back to the same host name when you query for it.

Possible client misconfiguration

About this task

Authentication problems might be caused by a client-side NAS misconfiguration. To verify, issue the **lookupname** command on the active management file module, as shown in the following example, to verify that the file module can authenticate with the authentication server.

```
$ lookupname --user SONAS\userr
USER          GROUP
SONAS\userr  SONAS\domain users
EFSSG1000I The command completed successfully.
```

```
$ chkauth -i -u SONAS\userr
Command_Output_Data  UID      GID      Home_Directory      Template_Shell
FETCH USER INFO SUCCEED 12004360 12000513 /var/opt/IBM/sofs/scproot /usr/bin/rsch
EFSSG1000I The command completed successfully.
```

When the system is unable to authenticate against an external authentication server, you must ensure that it can obtain user information from the authentication server. For this user information, query commands can be run from the file modules. For example, in the case of the LDAP authentication server, you can issue a command as shown in the following example:

```
$ chkauth -a -u SONAS\userr -p *****
AUTHENTICATE USER SUCCEED
EFSSG1000I The command completed successfully.
```

Trouble accessing exports when server and client configurations are correct

About this task

If you cannot access an export and the server and client configurations are correct, it could be because of the following reasons.

- If Storwize V7000 Unified authentication is configured against an LDAP server, the user entries are case-sensitive when you access exports. If the server and client configurations are correct, ensure that the user entries have the correct case.
- If Storwize V7000 Unified authentication is configured against an Active Directory server, user entries are not case-sensitive when you access exports. When you access CIFS exports, ensure that you use the domain name and user name, separated by a backslash (\), for example, w2k3dom01\test1.

Checking client access

Verify that your client workstation can successfully ping the full host name of the cluster and all of the IP addresses that are associated with it.

About this task

The following example shows how to ping an cluster. When the client connects to the host name of the cluster, the DNS server responds with IP addresses. You must then ping each IP address from the client machine.

If clients cannot successfully ping the IP addresses, then they are not able to access Storwize V7000 Unified whenever the DNS returns the IP address on name resolution requests. This can cause some clients have access while others do not.

Procedure

1. To obtain the IP addresses of your Storwize V7000 Unified cluster, issue the **nslookup** command; this non-disruptive command requires “root” access and your domain name. .

Information similar to the following example is displayed:

```
# nslookup yourdomainname
Server:          9.11.136.116
Address:         9.11.136.116#53
```

Non-authoritative answer:

```
Name:   yourdomainname
Address: 129.42.16.103
Name:   yourdomainname
Address: 129.42.17.103
Name:   yourdomainname
Address: 129.42.18.103
```

The **nslookup** command returns the IP addresses (129.42.18.103 in the example above) that are configured on the DNS server for Storwize V7000 Unified. Ideally, these IP addresses should be the same as the addresses that are configured on the Storwize V7000 Unified cluster itself. To check this, issue the **lsnw** CLI command.

2. Ping each IP address that is listed in the output by issuing the **ping returned IP Address** command. A successful return indicates a working connection. The response Request timed out indicates a failed connection.

Note: If clients cannot ping the IP addresses, refer to “Checking network interface availability.”

3. If you have a failed connection, contact the system administrator or IBM Remote Technical Support.

Checking network interface availability

You have several options for checking network availability by using the Storwize V7000 Unified GUI or the CLI.

Procedure

1. In the GUI, select **Monitoring > System Details > mgmt00xst001 > Operating System > Network**.
2. In the CLI, check the status of the interface “ethX0” (the interface of file modules to the customer net).
 - a. Open the CLI.
 - b. Issue the **lsnwinterface** command to display the status for the desired IP addresses.

```
# lsnwinterface
```

The system displays information similar to the following example:

| Node | Interface | MAC | Master/Subordinate | Bonding mode |
|--------------|-----------|-------------------|--------------------|-------------------|
| mgmt001st001 | ethX0 | e4:1f:13:d6:ae:ac | MASTER | balance-alb (6) |
| mgmt001st001 | ethX1 | 00:c0:dd:17:bc:ac | MASTER | active-backup (1) |
| mgmt002st001 | ethX0 | e4:1f:13:d6:ae:94 | MASTER | balance-alb (6) |
| mgmt002st001 | ethX1 | 00:c0:dd:17:c5:50 | MASTER | active-backup (1) |

```
Up/Down Speed IP-Addresses      MTU
UP      1000
UP      10000 9.11.84.84,9.11.84.85 1500
UP      1000
UP      10000 9.11.84.82,9.11.84.83 1500
EFSSG1000I The command completed successfully.
```

In the **Up/Down** column, the value UP indicates a connection.

3. If the network interface is not available, check the cables and ensure that the cables are plugged in. For instance, if you have no machine connectivity between file modules and switches, check the external Ethernet cabling. If all cables are correctly connected, check intranet and external Internet availability. If none of these checks indicate a problem, contact the next level of support.

Recovering a GPFS file system

Use this procedure to recover a GPFS file system after a storage system failure has been fully addressed. You should use this procedure only under the supervision of IBM support.

Before you begin

Prerequisites:

- You are running this procedure on a file module.
- You are logged into the file module, which is the active file module, as root. See “Accessing a file module as root” on page 261.
- GPFS and CTDB must both be in a healthy state to run some of the commands that follow.

For storage system recovery, see the procedure for recovering a storage system.

About this task

This procedure provides steps to recover a GPFS file system after a failure of the block storage system. The file volumes were offline and are now back online after a repair or recovery action. The disks referred to in this procedure are the volumes that are provided by the block storage system.

Note: Because no I/O can be done by GPFS, it is assumed for these procedures that the storage unit failure caused the GPFS file system to unmount. After satisfying the prerequisites above, take the following steps:

Procedure

1. Verify that GPFS is running on both file modules by using the **lsnode -r** command.
The column **GPFS status** shows active.
2. In the **lsnode -r** command output, verify that the CTDB status is also active. If the CTDB status shows the value *unhealthy*, see “Checking CTDB health” on page 153 for steps to resolve the CTDB status.
3. With GPFS functioning normally on both file modules, ensure that all disks in the file system are available by running the **lsdisk -r** command. The **Availability** column shows Up.
4. Issue the **chkfs file_system_name -v | tee /ftdc/chkfs_fs_name.log1** command to capture the output to a file.
Review the output file for errors and save it for IBM support to investigate any problems.
If the file contains a TSM ERROR message, perform the following steps:
 - a. Issue the **stopbackup -d file_system_name** command and the **stoprestore -d file_system_name** command to stop any backup or restore operation.
 - b. Validate that no error occurred while stopping any Tivoli Storage Manager service.

- c. Issue the **chkfs** *file_system_name* -v | tee /ftdc/chkfs_fs_name.log2 command to recapture the output to a file.
- d. Issue the **startrestore** command and the **startbackup** command to enable Tivoli Storage Manager.

If you receive an error message (the number of mounted or used file modules does not matter) at step 5 of the command internal execution steps like the following,

```
(5/9) Performing mmfsck call for the file system check stderr:
Cannot check. "gpfs0" is mounted on 1 node(s) and in use on 1 node(s).
mmfsck: Command failed.
Examine previous error messages to determine cause.
```

perform the following steps:

- a. Monitor the **lsmount -r** command until the mount status changes to not mounted.
- b. Issue the **chkfs** *file_system_name* command again.

Review the new output file for errors and save it for IBM support to investigate any problems. It is expected that the file contains Lost blocks were found messages. It is normal to have some missing file system blocks. If the only errors that are reported are missing blocks, no further repair is needed. However, if the **chkfs** command reports more severe errors, contact IBM support to assist with repairing the file system.

Resolving an ANS1267E error

An ANS1267E error might indicate an incorrect setting in the Tivoli® Storage Manager server configuration.

About this task

An ANS1267E error can result from the Tivoli Storage Manager server not being set up to handle hierarchical storage management (HSM) migrated files and that the management class is not accepting files from HSM.

To correct this error, set the **spacemgtech** value to "auto".

Resolving issues reported by lshelth

Use this information to resolve **lshelth** reported issues, specifically for "MGMTNODE_REPL_STATE ERROR DATABASE_REPLICATION_FAILED" and "The mount state of the file system /ibm/FileSystem_Name changed to error level" errors.

About this task

These errors might be transient and can clear automatically at any time.

Error for "MGMTNODE_REPL_STATE ERROR DATABASE_REPLICATION_FAILED"

About this task

To resolve the "MGMTNODE_REPL_STATE ERROR DATABASE_REPLICATION_FAILED" error, complete the following steps.

Procedure

1. Verify that the other file module role displays Host State OK. Repair the host state if necessary.
2. Allow fifteen minutes for the error to disappear. If the error does not disappear, attempt to reboot the passive management node. The issue should be resolved after the reboot and within five minutes after the file module displays Host State OK again.

Error for “The mount state of the file system `/ibm/FileSystem_Name` changed to error level”

About this task

If the command `lshealth -i gpfs_fs -r` returns “The mount state of the file system `/ibm/FileSystem_Name` changed to error level”, complete the following steps to resolve the issue.

Procedure

1. Verify that the other file module role displays Host State OK. Repair the host state if necessary.
2. Issue the command `mountfs fileSystem`.
3. Issue the command `lsfs -r`.
4. Issue the command `lshealth -i gpfs_fs -r`.
The command output should display The mount state of the file system `/ibm/gpfs1` was set back to normal level.
5. If the error persists, refer to the GPFS documentation to debug or repair the error.

Resolving network errors

Use the following information and examples to resolve network errors that are identified by the health system.

If a network is not attached to an interface, the health center monitors all ports and logs and displays any port failures.

To stop monitoring an unused port, use the `attachnw` command to attach the interface that corresponds to that port. After this command is issued, you must manually mark the displayed error events for the unused port as *resolved*. You can use the GUI system details panel to manually mark the events.

Whether a port is monitored depends on the attached network configuration and the interface that is used for the management network. If an interface is not in use by an attached network, the interface is monitored if it is used by the management network.

Important:

It is highly recommended, that for a given VLAN subnet definition, you must also consistently provide the same VLAN ID (tag) for that subnet on any network definition that you create within a common interface bond on the clustered system. If you define a VLAN on your management network, and you have the same VLAN subnet on the same interface bond for data connectivity, ensure that you provide the exact same VLAN ID. Additionally, the switch configurations supporting this VLAN should be same for all connections that the VLAN uses.

Ensure that you use trunk, access link, or native VLAN consistently on the switch ports that are connected to all ports on the clustered system. The clustered system shares the same VLAN subnet. Avoid defining the same VLAN with a tag ID either different or missing, when providing the VLAN ID to a management network bond, as well as to a shared data network bond.

Unless you have intentionally configured your switching network to support this unique case, where the VLAN ID for the management network and data network are not the same and you are confident on how this will be routed from the clustered system to your switch, you might incur unpredictable routing path behavior and even network connectivity loss.

See the following examples.

Scenario 1

```
lsnwgroupp returns:
[root@kd66t4v.mgmt001st001 ~]# lsnwgroupp
Network Group Nodes          Interfaces
DEFAULT      mgmt001st001,mgmt002st001
EFSSG1000I The command completed successfully.
and lsnwmgtp returns:
[root@kd52v6k.mgmt001st001 ~]# lsnwmgtp
Interface Service IP Node1 Service IP Node2 Management IP Network Gateway VLAN ID
ethX0          . . .          . . .          . . .          . . .          . . .
EFSSG1000I The command completed successfully.
```

None of the interfaces is attached and the management network uses interface ethX0. If any ethX1 port cable is unplugged, the health center displays a failure because no network is attached to an interface, which causes the system to monitor all ports.

Scenario 2

```
lsnwgroupp returns:
[root@kd52v6k.mgmt001st001 ~]# lsnwgroupp
Network Group Nodes          Interfaces
DEFAULT      mgmt001st001,mgmt002st001 ethX0
EFSSG1000I The command completed successfully.
and lsnwmgtp returns:
[root@kd52v6k.mgmt001st001 ~]# lsnwmgtp
Interface Service IP Node1 Service IP Node2 Management IP Network Gateway VLAN ID
ethX0          . . .          . . .          . . .          . . .          . . .
EFSSG1000I The command completed successfully.
```

The interface ethX0 is attached to a network and the management network uses ethX0. If any ethX1 port cable is unplugged, the health center does not display a failure, because ethX1 is not used by either an attached network or the management network.

Scenario 3

```
lsnwgroupp returns:
[root@kd52v6k.mgmt001st001 ~]# lsnwgroupp
Network Group Nodes          Interfaces
DEFAULT      mgmt001st001,mgmt002st001 ethX0
EFSSG1000I The command completed successfully.
and lsnwmgtp returns:
[root@kd52v6k.mgmt001st001 ~]# lsnwmgtp
Interface Service IP Node1 Service IP Node2 Management IP Network Gateway VLAN ID
ethX1          . . .          . . .          . . .          . . .          . . .
EFSSG1000I The command completed successfully.
```


If any ethX1 port cable is unplugged, the health center displays a failure because ethX1 is used by the management network.

Resolving full condition for GPFS file system

Use this procedure when the management GUI reports a critical error when a file system is 100% full.

About this task

You must have root access to perform this procedure.

Note: If you use GPFS snapshots, the file system locks when it reaches 100% utilization.

Procedure

To resolve the full condition for the file system, perform the following steps:

1. Review the contents of the GPFS file system.
 - If the file system has snapshots, remove the oldest snapshot after verifying that it is no longer needed. Continue to remove the snapshots from oldest to newest until the level of free space that you want is achieved.
 - If no snapshots exist, perform the following steps:
 - a. Run the **mmdf** command to determine what storage pool is out of space.
 - b. Remove files to free up storage.
 - c. If the **mmdf** command output shows that there is space in free fragments, run the **mmdefragfs** command to combine the fragments into full blocks.

Note: You can run the GPFS **defrag** command while the file systems are mounted. However, for better results, unmount the GPFS file system before performing the defragmentation operation.

2. If there is no space in fragments or if the **mmdefragfs** command does not free up space, add disks (NSDs) to the file system to create space.
 - a. Add disks to the file system.

Note: If free space exists in the **mdiskgroup** then you can modify the file system by editing it in the GUI or simply running the command: **mkdisk filesystem size mdiskgroup**

For example:

```
[root@kd01gln.mgmt002st001 ~]# mkdisk gpfs0 10GB 0
(1/4) Creating Storage System volumes
(2/4) Scanning for new devices
(3/4) Creating NSDs
(4/4) Adding disks to filesystem
Successfully created disk
```

- b. If there is no storage space available, contact IBM support.

Analyzing GPFS logs

Use this procedure when reviewing GPFS log entries.

About this task

Note: Contact IBM support if you want to analyze GPFS log entries.

Procedure

1. Log in to the appropriate file module using root privileges.
2. Review the log file `/var/adm/ras/mmfs.log.latest`. The details in the log are listed from oldest to newest, so you can find the latest GPFS information at the end.

Note: The GPFS log is a complex raw log file for GPFS. If you do not understand the conditions listed in the log, contact IBM support for assistance.

Synchronizing time on the file modules

Use this information to synchronize the time on all Storwize V7000 Unified file module.

About this task

Synchronizing the time on all the file module can help as you start troubleshooting because the timestamps on the logs then indicate whether you have concurrent, legitimate results.

You can ensure that the Storwize V7000 Unified, Active Directory (AD), Kerberos, and other servers are synchronized with a valid Network Time Protocol (NTP) source. This is important both for log checking and because if the cluster falls behind the correct time, Kerberos tickets, for example, can expire and then no one can access the cluster. For the Storwize V7000 Unified file module, the `ntpq -p` command shows you which server is used for synchronization and any peers and a set of data about their status. The * in the first column indicates that the local clock is used for synchronization.

```
# ntpq -p
      remote           refid      st t when poll reach  delay  offset  jitter
=====
*machine.domain.i 9.19.0.220  2 u  269 1024  377   0.659  -0.115  0.164
+machine.domain.i 9.19.0.220  2 u  992 1024  377   1.380   0.337  0.564
LOCAL(0)          .LOCL.        10 l   50   64  377   0.000   0.000  0.001
```

As NTP is drift based, large time differences can prevent NTP from synchronizing, or cause synchronization to take a long time. It can be helpful to synchronize time manually once and to verify that the time is picked up correctly afterward. Use the separate commands of `service ntpd stop`, `ntpdate your IP`, and `service ntpd start`. The following example shows the sequence:

```
[root@domain.node ~]# service ntpd stop
Shutting down ntpd: [ OK ]
[root@domain.node ~]# ntpdate 9.19.0.220
14 Jan 12:06:46 ntpdate[25360]: adjust time server 9.19.0.220 offset 0.003277 sec
[root@domain.node ~]# service ntpd start
Starting ntpd: [ OK ]
[root@domain.node ~]#
```

After the time on all of the servers is synchronized, you can verify that the logs apply to your troubleshooting situation.

Chapter 5. Control enclosure

Find out how to troubleshoot the control enclosure, which includes the use of error codes, problem scenarios, software, and removal and replacement instructions.

About this task

Storwize V7000 system interfaces

The Storwize V7000 system provides a number of user interfaces to troubleshoot, recover, or maintain your system. The interfaces provide various sets of facilities to help resolve situations that you might encounter. The interfaces for servicing your system connect through the 1 Gbps Ethernet ports that are accessible from port 1 of each canister. You cannot manage a system by using the 10 Gbps Ethernet ports.

You can perform almost all of the configuration, troubleshooting, recovery, and maintenance of the storage system from within the Storwize V7000 Unified management GUI or the CLI commands that are running on the Storwize V7000 file modules.

Attention: Do not use the Storwize V7000 system interfaces directly unless you are directed to do so by a service procedure.

Use the initialization tool to do the initial setup of your system. Use the Storwize V7000 Unified management GUI or the Storwize V7000 system management GUI to monitor and maintain the configuration of storage that is associated with your systems. Perform service procedures from the service assistant. Use the command-line interface (CLI) to manage your system.

Service assistant interface

The service assistant interface is a browser-based GUI that is used to service individual node canisters in the control enclosures.

You connect to the service assistant on one node canister through the service IP address. If there is a working communications path between the node canisters, you can view status information and perform service tasks on the other node canister by making the other node canister the current node. You do not have to reconnect to the other node.

When to use the service assistant

The primary use of the service assistant is when a node canister in the control enclosure is in service state. The node canister cannot be active as part of a system while it is in service state.

Attention: Perform service actions on node canisters only when directed to do so by the fix procedures. If used inappropriately, the service actions that are available through the service assistant can cause loss of access to data or even data loss.

The node canister might be in service state because it has a hardware issue, has corrupted data, or has lost its configuration data.

Use the service assistant in the following situations:

- When you cannot access the system from the management GUI and you cannot access the storage Storwize V7000 Unified to run the recommended actions
- When the recommended action directs you to use the service assistant.

The storage system management GUI operates only when there is an online system. Use the service assistant if you are unable to create a system or if both node canisters in a control enclosure are in service state.

The service assistant does not provide any facilities to help you service expansion enclosures. Always service the expansion enclosures by using the management GUI.

The service assistant provides detailed status and error summaries, and the ability to modify the World Wide Node Name (WWN) for each node.

You can also perform the following service-related actions:

- Collect logs to create and download a package of files to send to support personnel.
- Remove the data for the system from a node.
- Recover a system if it fails.
- Install a code package from the support inh_site or rescue the code from another node.
- Upgrade code on node canisters manually versus performing a standard upgrade procedure.
- Configure a control enclosure chassis after replacement.
- Change the service IP address that is assigned to Ethernet port 1 for the current node canister.
- Install a temporary SSH key if a key is not installed and CLI access is required.
- Restart the services used by the system.

A number of tasks that are performed by the service assistant cause the node canister to restart. It is not possible to maintain the service assistant connection to the node canister when it restarts. If the current node canister on which the tasks are performed is also the node canister that the browser is connected to and you lose your connection, reconnect and log on to the service assistant again after running the tasks.

Accessing the service assistant

The service assistant is a web application that helps troubleshoot and resolve problems on a node canister in a control enclosure.

About this task

You must use a supported web browser. Verify that you are using a supported and an appropriately configured web browser from the following website:

www.ibm.com/storage/support/storwize/v7000/unified

To start the application, perform the following steps:

Procedure

1. Start a supported web browser and point your web browser to `<serviceaddress>/service` for the node canister that you want to work on.

For example, if you set a service address of 11.22.33.44 for a node canister, point your browser to 11.22.33.44/service. If you are unable to connect to the service assistant, see “Problem: Cannot connect to the service assistant” on page 193.

2. Log on to the service assistant using the superuser password.

If you are accessing a new node canister, the default password is `passwd`. If the node canister is a member of a system or has been a member of a system, use the password for the superuser password.

If you do not know the current superuser password, reset the password. Go to “Procedure: Resetting superuser password” on page 197.

Results

Perform the service assistant actions on the correct node canister. If you did not connect to the node canister that you wanted to work on, access the **Change Node** panel from the home page to select a different current node.

Commands are run on the current node. The current node might not be the node canister that you connected to. The current node identification is shown on the left at the top of the service assistant screen. The identification includes the enclosure serial number, the slot location, and if it has one, the node name of the current node.

Storage system command-line interface

Use the storage system command-line interface (CLI) to manage a storage system by using the task commands and information commands.

You can also access most of the storage system CLI commands from the Storwize V7000 Unified CLI that runs in the file system on one of the file modules.

For a full description of the storage system commands and how to start an SSH command-line session, see the “Command-line interface” topic in the “Reference” section of the Storwize V7000 Unified Information Center.

When to use the storage system CLI

The storage system CLI is intended for use by advanced users who are confident at using a command-line interface.

Nearly all of the flexibility that is offered by the CLI is available through the management GUI. However, the CLI does not provide the fix procedures that are available in the management GUI. Therefore, use the fix procedures in the management GUI to resolve the problems. Use the CLI when you require a configuration setting that is unavailable in the management GUI.

You might also find it useful to create command scripts by using the CLI commands to monitor for certain conditions or to automate configuration changes that you make on a regular basis.

Accessing the storage system CLI

Follow the steps that are described in the “Command-line interface” topic in the “Reference” section of the Storwize V7000 Unified Information Center to initialize and use a CLI session.

Service command-line interface

Use the service command-line interface (CLI) to manage a node canister in a control enclosure using the task commands and information commands.

For a full description of the commands and how to start an SSH command-line session, see the “Command-line interface” topic in the “Reference” section of the Storwize V7000 Unified Information Center.

When to use the service CLI

The service CLI is intended for use by advanced users who are confident at using a command-line interface.

To access a node canister directly, it is normally easier to use the service assistant with its graphical interface and extensive help facilities.

Accessing the service CLI

Follow the steps that are described in the “Command-line interface” topic in the “Reference” section of the Storwize V7000 Unified Information Center to initialize and use a CLI session.

USB flash drive and Initialization tool interface

Use a USB flash drive to initialize a system and also to help service the node canisters in a control enclosure.

The initialization tool is a Windows application. Use the initialization tool to set up the USB flash drive to perform the most common tasks.

When a USB flash drive is inserted into one of the USB ports on a node canister in a control enclosure, the node canister searches for a control file on the USB flash drive and runs the command that is specified in the file. When the command completes, the command results and node status information are written to the USB flash drive.

When to use the USB flash drive

The USB flash drive is normally used to initialize the configuration after installing a new system.

Using the USB flash drive is required in the following situations:

- When you cannot connect to a nodecanister in a control enclosure using the service assistant and you want to see the status of the node.
- When you do not know, or cannot use, the service IP address for the node canister in the control enclosure and must set the address.
- When you have forgotten the superuser password and must reset the password.

Using a USB flash drive

Use any USB flash drive that is formatted with a FAT32 file system on its first partition.

About this task

When a USB flash drive is plugged into a node canister, the node canister code searches for a text file named `satask.txt` in the root directory. If the code finds the file, it attempts to run a command that is specified in the file. When the command completes, a file called `satask_result.html` is written to the root directory of the USB flash drive. If this file does not exist, it is created. If it exists, the data is

inserted at the start of the file. The file contains the details and results of the command that was run and the status and the configuration information from the node canister. The status and configuration information matches the detail that is shown on the service assistant home page panels.

The `satask.txt` file can be created on any workstation by using a text editor. If a Microsoft Windows workstation is being used, the initialization tool can be used to create the commands that are most often used.

The fault LED on the node canister flashes when the USB service action is being performed. When the fault LED stops flashing, it is safe to remove the USB flash drive.

Results

The USB flash drive can then be plugged into a workstation and the `satask_result.html` file viewed in a web browser.

To protect from accidentally running the same command again, the `satask.txt` file is deleted after it has been read.

If no `satask.txt` file is found on the USB flash drive, the result file is still created, if necessary, and the status and configuration data is written to it.

Using the initialization tool

The initialization tool is a graphical user interface (GUI) application that is used to create the `satask.txt` file on a USB flash drive.

Before you begin

Verify that you are using a supported operating system. The initialization tool is valid for the following operating systems.

- Microsoft Windows 7 (64-bit) or XP (32-bit)
- Apple MacOS X 10.7
- Red Hat Enterprise Server 5 or Ubuntu desktop 11.04

About this task

By using the initialization tool, you can set the USB flash drive to run one of the following tasks:

- Initialize a new system.
- Reset the superuser password.
- Set or reset the service assistant IP address on a node canister on the control enclosure.
- Set the management IP addresses.

For any other tasks that you want to perform on a node canister on the control enclosure, you must create the `satask.txt` file using a text editor.

The initialization tool is available on the USB flash drive that is shipped with the control enclosures. The name of the application file is `InitTool.exe`. If you cannot locate the USB flash drive, you can download the application from the support website (search for initialization tool):

Procedure

To use the initialization tool, complete the following steps.

1. If you downloaded the initialization tool, copy the file onto the USB flash drive that you are going to use.
2. To start the initialization tool, insert the USB flash drive that contains the program into a USB slot on a suitable personal computer.
3. Run the `InitTool.exe` program from the USB drive.
 - **Windows:** Open the USB flash drive and double-click `InitTool.bat`.
 - **Apple Macintosh:** Locate the root directory of the USB flash drive (usually located in the `/Volumes/` directory). Type `sh InitTool.sh`.
 - **Linux:** Locate the root directory of the USB flash drive. (It is usually located in the `/media/` directory. If an automatic mount system is used, the root directory can be located by typing the mount command.) Type `sh InitTool.sh`.

The initialization tool prompts you for the task that you want to perform and for the parameters that are relevant to that task. It prompts you when to put it in the node canister on the control enclosure.

4. After the `satask.txt` file is created, follow the instructions in “Using a USB flash drive” on page 170 to run the commands on the node.
5. When the commands have run, return the USB flash drive to your personal computer and start the tool again to see the results.

USB memory key has incorrect gateway address information

If the link on the `InitTool` panel to the management GUI does not work, the USB key may have an incorrect gateway address.

About this task

The `InitTool.exe` may indicate that the initial setup was successful, however, the link on the `InitTool` panel to the management GUI may not work. Given this scenario, it is possible that you have entered a management gateway IP address that is in the same subnet as the management IP address but is not the IP address of the gateway for this subnet. To check this, look inside the `satask.exe` file on the USB flash drive and note the IP address after the `-gw` switch. Make sure this IP address is the gateway for this subnet. If an IP address is needed then check this with your 1 Gbps Ethernet administrator.

If you did enter the wrong IP address for the gateway of this subnet and you have the correct gateway IP address ready, then it is possible to re-configure the control enclosure and file module to use the correct management gateway IP address.

If you have access to a computer that is plugged into the same Ethernet switch as the 1 Gbps Ethernet port 3 of each file module and the 1 Gbps Ethernet port 1 of each node canister in the control enclosure, then you may be able to ssh from it to the management IP address and log on as admin.

In this example, the default password is **admin**:

```
ssh admin@<management IP address>
```


Use the **lssystemip** CLI command to show you the current management IP address setting on the control enclosure:

```
[kd52v6h.ibm]$ lssystemip
cluster_id cluster_name location port_id IP_address subnet_mask gateway
IP_address_6 prefix_6 gateway_6
00000200A9E0089E ifsc1uster-svt2 local 1 9.71.16.208 255.255.255.0 9.71.16.2
00000200A9E0089E ifsc1uster-svt2 local 2
```

If this command fails because the file module could not ssh to the control enclosure then refer to **Troubleshooting > Getting started troubleshooting > Installation troubleshooting > Problems with initial configuration** from the Problem Determination Guide.

Use the **chsystemip** CLI command to change the managed gateway IP address setting on the control enclosure. (This must be done first before you change the management gateway IP address setting on the file modules):

```
[kd52v6h.ibm]$ chsystemip -gw 9.71.16.1 -port 1
```

The active management node on the file module is not able to ssh CLI commands to the control enclosure until you change the management gateway setting to match the setting on the control enclosure. Use the **lsnwmgt** CLI command to show you the current management IP address setting on the file modules.

```
[kd52v6h.ibm]$ lsnwmgt
Interface Service IP Node1 Service IP Node2 Management IP Network Gateway LAN ID
ethX0 9.71.16.204 9.71.16.205 9.71.16.216 255.255.255.0 9.71.16.2
EFSSG1000I The command completed successfully
```

Use the **chnwmgt** CLI command to change the managed gateway IP address setting on the file modules.

```
[kd52v6h.ibm]$ chnwmgt --gateway 9.71.16.1
EFSSG0015I Refreshing data.
EFSSG1000I The command completed successfully
```

The active management node on the file module should now be able to ssh CLI commands to the control enclosure again. You should be able to access the management GUI or CLI from a computer, which is on a different subnet or different Ethernet switch to the Storwize V7000 Unified system. The link to the management GUI from the InitTool.exe panel should now work.

satask.txt commands

This topic identifies the commands that can be run from a USB flash drive.

If you are creating the **satask.txt** command file by using a text editor, the file must contain a single command on a single line in the file. The commands that you use are the same as the service CLI commands except where noted. Not all service CLI commands can be run from the USB flash drive. The **satask.txt** commands always run on the node that the USB flash drive is plugged into.

Reset service IP address and superuser password command:

Use this command to obtain service assistant access to a node canister even if the current state of the node canister is unknown. The physical access to the node canister is required and is used to authenticate the action.

Syntax

```
▶▶▶ satask — chserviceip — --serviceip—ipv4— [—gw—ipv4] [—mask—ipv4] [—resetpassword]
▶▶▶ satask — chserviceip — --serviceip_6—ipv6— [—gw_6—ipv6] [—prefix_6—int]
▶▶▶ satask — chserviceip — --default— [—resetpassword]
```

Parameters

-serviceip

(Optional) The IPv4 address for the service assistant.

-gw

(Optional) The IPv4 gateway for the service assistant.

-mask

(Optional) The IPv4 subnet for the service assistant.

-serviceip_6

(Optional) The IPv6 address for the service assistant.

-gw_6

(Optional) The IPv6 gateway for the service assistant.

-default

(Optional) Resets to the default IPv4 address.

-prefix_6

(Optional) The IPv6 prefix for the service assistant.

-resetpassword

(Optional) Sets the service assistant password to the default value.

Description

This command resets the service assistant IP address to the default value. If the command is run on the upper canister, the default value is 192.168.70.121 subnet mask: 255.255.255.0. If the command is run on the lower canister, the default value is 192.168.70.122 subnet mask: 255.255.255.0. If the node canister is active in a system, the superuser password for the system is reset; otherwise, the superuser password is reset on the node canister.

If the node canister becomes active in a system, the superuser password is reset to that of the system. You can configure the system to disable resetting the superuser password. If you disable that function, this action fails.

This action calls the **satask chserviceip** command and the **satask resetpassword** command.

Reset service assistant password command:

Use this command when you are unable to logon to the system because you have forgotten the superuser password, and you wish to reset it.

Attention: Run this command only when instructed by IBM support. Running this command directly on a Storwize V7000 can affect your I/O operations on the file modules.

Syntax

```
▶▶ satask — resetpassword —————▶▶
```

Parameters

None.

Description

This command resets the service assistant password to the default value `passw0rd`. If the node canister is active in a system, the superuser password for the system is reset; otherwise, the superuser password is reset on the node canister.

If the node canister becomes active in a system, the superuser password is reset to that of the system. You can configure the system to disable resetting the superuser password. If you disable that function, this action fails.

This command calls the **satask resetpassword** command.

Snap command:

Use this command to collect diagnostic information from the node canister and to write the output to a USB flash drive.

Attention: Run this command only when instructed by IBM support. Running this command directly on a Storwize V7000 can affect your I/O operations on the file modules.

Syntax

```
▶▶ satask — snap — --options————▶▶
```

Parameters

-options

(Optional) Specifies which diagnostic information to collect.

Description

This command moves a snap file to a USB flash drive.

This command calls the **satask snap** command.

Apply software command:

Use this command to install a specific upgrade package on the node canister.

Attention: Run this command only when instructed by IBM support. Running this command directly on a Storwize V7000 can affect your I/O operations on the file modules.

Syntax

```
▶▶ satask — installsoftware — — -file filename —————▶▶  
└── -ignore ─┘
```

Parameters

-file

(Required) The file name of upgrade package .

-ignore

(Optional) Overrides prerequisite checking and forces installation of the upgrade package.

Description

This command copies the file from the USB flash drive to the upgrade directory on the node canister and then installs the upgrade package.

This command calls the **satask installsoftware** command.

Create system command:

Use this command to create a storage system.

Note: The reference to cluster is not the same as the file system cluster on the Storwize V7000 file modules.

Attention: Run this command only when instructed by IBM support. Running this command directly on a Storwize V7000 can affect your I/O operations on the file modules.

Syntax

```
▶▶ satask — mkcluster — — -clusterip ipv4 —————▶▶  
└── -gw ipv4 ─┘ └── -mask ipv4 ─┘  
└── -name cluster_name ─┘
```

```
▶▶ satask — mkcluster — — -clusterip_6 ipv6 —————▶▶  
└── -gw_6 ipv6 ─┘ └── -prefix_6 int ─┘  
└── -name cluster_name ─┘
```

Parameters

-clusterip

(Optional) The IPv4 address for Ethernet port 1 on the system.

-gw

(Optional) The IPv4 gateway for Ethernet port 1 on the system.

-mask

(Optional) The IPv4 subnet for Ethernet port 1 on the system.

-clusterip_6

(Optional) The IPv6 address for Ethernet port 1 on the system.

-gw_6

(Optional) The IPv6 gateway for Ethernet port 1 on the system.

-prefix_6

(Optional) The IPv6 prefix for Ethernet port 1 on the system.

-name

(Optional) The name of the new system.

Description

This command creates a storage system.

This command calls the **satask mkcluster** command.

Change system IP address:

Use this command to change the system IP address of the storage system.

It is best to use the initialization tool to create this command in `satask.txt` together with the associated `clitask.txt` file that changes the file modules management IP addresses.

Syntax

```
▶▶▶ satask — setsystemip — — -systemip —ipv4 — — -gw —ipv4 — — -mask —ipv4 — —————▶  
▶▶ -consoleip — ipv4————▶▶▶
```

Parameters

-systemip

The IPv4 address for Ethernet port 1 on the system.

-gw

The IPv4 gateway for Ethernet port 1 on the system.

-mask

The IPv4 subnet for Ethernet port 1 on the system.

-consoleip

The management IPv4 address of Storwize V7000 Unified system.

Description

This command is only supported in the `satask.txt` file on a USB flash drive.

It calls the `svctask chsystemip` command if the USB flash drive is inserted in the configuration node canister, Otherwise it will blink the amber identify LED of the node canister that is the configuration node.

If the amber identify LED for a different node canister starts to blink then move the USB flash drive over to that node canister because it is the configuration node.

When the amber LED turns off you can move the USB flash drive to one of the file modules so that it will use the `clitask.txt` file to change the file module management IP addresses.

Leave the USB flash drive in the file module for at least two minutes before you remove it. Use a workstation to check the `clitask_results.txt` and `satask.txt` results files on the USB flash drive.

If the IP address change was successful then you must run the `startmgtsrv -r` command to restart the management service so that it will not continue to ssh commands to the old system IP address of the volume storage system.

For example, on a Linux workstation with network access to the new management IP address:

```
satask setsystemip -systemip 123.123.123.20 -gw 123.123.123.1 -mask 255.255.255.0 -consoleip 123.123.123.10
```

You should now be able to access the management GUI which you can use to change any other IP address that need to be changed.

Here is an example of what could be in the `clitask.txt` file:

```
chnwmgmt --serviceip1 123.123.123.11 --serviceip2 123.123.123.12 --mgtip 123.123.123.10 --gateway 123.123.123.1 --netmask 255.255.255.0 --force  
chstoragesystem --ip1 123.123.123.20
```

Here is an example of what could be in the `satak.txt` file:

```
satask setsystemip -systemip 123.123.123.20 -gw 123.123.123.1 -mask 255.255.255.0 -consoleip 123.123.123.10
```

Query status command:

Use this command to determine the current service state of the node canister.

Syntax

▶— `sainfo` — `getstatus` — 

Parameters

None.

Description

This command writes the output from each node canister to the USB flash drive.

This command calls the `sainfo lsservicenodes` command, the `sainfo lsservicestatus` command, and the `sainfo lsservicerecommendation` command.

Event reporting

Events that are detected are saved in an event log. As soon as an entry is made in this event log, the condition is analyzed. If any service activity is required, a notification is sent.

Event reporting process

The following methods are used to notify you and the IBM Support Center of a new event:

- If you enabled Simple Network Management Protocol (SNMP), an SNMP trap is sent to an SNMP manager that is configured by the customer.
- If enabled, log messages can be forwarded on an IP network by using the syslog protocol.
- If enabled, event notifications can be forwarded by email by using Simple Mail Transfer Protocol (SMTP).
- Call Home can be enabled so that critical faults generate a problem management record (PMR) that is then sent directly to the appropriate IBM Support Center by using email.

Understanding events

When a significant change in status is detected, an event is logged in the event log.

Error data

Events are classified as either alerts or messages:

- An alert is logged when the event requires some action. Some alerts have an associated error code that defines the service action that is required. The service actions are automated through the fix procedures. If the alert does not have an error code, the alert represents an unexpected change in state. This situation must be investigated to see if it is expected or represents a failure. Investigate an alert and resolve it as soon as it is reported.
- A message is logged when a change that is expected is reported, for instance, an IBM FlashCopy[®] operation completes.

Viewing the event log

You can view the event log by using the management GUI or the command-line interface (CLI).

About this task

You can view the event log by using the **Monitoring > Events** options in the management GUI. The event log contains many entries. You can, however, select only the type of information that you need.

You can also view the event log by using the command-line interface (**lseventlog**). See the “Command-line interface” topic for the command details.

Managing the event log

The event log has a limited size. After it is full, newer entries replace entries that are no longer required.

To avoid having a repeated event that fills the event log, some records in the event log refer to multiple occurrences of the same event. When event log entries are

coalesced in this way, the time stamp of the first occurrence and the last occurrence of the problem is saved in the log entry. A count of the number of times that the error condition has occurred is also saved in the log entry. Other data refers to the last occurrence of the event.

Describing the fields in the event log

The event log includes fields with information that you can use to diagnose problems.

Table 34 describes some of the fields that are available to assist you in diagnosing problems.

Table 34. Description of data fields for the event log

| Data field | Description |
|----------------------|--|
| Event ID | This number precisely identifies why the event was logged. |
| Error code | This number describes the service action that should be followed to resolve an error condition. Not all events have error codes that are associated with them. Many event IDs can have the same error code because the service action is the same for all the events. |
| Sequence number | A number that identifies the event. |
| Event count | The number of events coalesced into this event log record. |
| Object type | The object type to which the event log relates. |
| Object ID | A number that uniquely identifies the instance of the object. |
| Fixed | When an alert is shown for an error condition, it indicates if the reason for the event was resolved. In many cases, the system automatically marks the events fixed when appropriate. There are some events that must be manually marked as fixed. If the event is a message, this field indicates that you have read and performed the action. The message must be marked as read. |
| First time | The time when this error event was reported. If events of a similar type are being coalesced together, so that one event log record represents more than one event, this field is the time the first error event was logged. |
| Last time | The time when the last instance of this error event was recorded in the log. |
| Root sequence number | If set, this number is the sequence number of an event that represents an error that probably caused this event to be reported. Resolve the root event first. |
| Sense data | Additional data that gives the details of the condition that caused the event to be logged. |

Event notifications

The Storwize V7000 product can use Simple Network Management Protocol (SNMP) traps, syslog messages, emails and Call Homes to notify you and IBM(r) Remote Technical Support when significant events are detected. Any combination of these notification methods can be used simultaneously. Notifications are normally sent immediately after an event is raised. However, there are some events that might occur because of service actions that are being performed. If a recommended service action is active, these events are notified only if they are still unfixed when the service action completes.

Only events recorded in the event log can be notified. Most CLI messages in response to some CLI commands are not recorded in the event log so do not cause an event notification.

Table 35 describes the levels of event notifications.

Table 35. Notification levels

| Notification level | Description |
|--------------------|---|
| Error | <p>Error notification is sent to indicate a problem that must be corrected as soon as possible.</p> <p>This notification indicates a serious problem with the system. For example, the event that is being reported could indicate a loss of redundancy in the system, and it is possible that another failure could result in loss of access to data. The most typical reason that this type of notification is sent is because of a hardware failure, but some configuration errors or fabric errors also are included in this notification level. Error notifications can be configured to be sent as a Call Home to the IBM Remote Technical Support.</p> |
| Warning | <p>A warning notification is sent to indicate a problem or unexpected condition with the system. Always immediately investigate this type of notification to determine the effect that it might have on your operation, and make any necessary corrections.</p> <p>A warning notification does not require any replacement parts and therefore should not require IBM Support Center involvement. The allocation of notification type Warning does not imply that the event is less serious than one that has notification level Error.</p> |
| Information | <p>An informational notification is sent to indicate that an expected event has occurred: for example, a FlashCopy operation has completed. No remedial action is required when these notifications are sent.</p> |

Power-on self-test

When you turn on the system, the file modules and the control enclosure node canisters perform self-tests.

A series of tests is performed to check the operation of components and some of the options that have been installed when the units are first turned on. This series of tests is called the power-on self-test (POST).

If a critical failure is detected during the POST, the software is not loaded and the fault LED is illuminated. To determine if there is a POST error on a file module or a node canister, go to “Procedure: Understanding the system status using the LEDs” on page 199.

When the code is loaded, additional testing takes place, which ensures that all of the required hardware and code components are installed and functioning correctly.

Understanding events

Informational events provide information on the status of an operation. Information events are recorded in the error event log, and depending on the configuration, can be notified through email, SNMP, and syslog.

Understanding the error codes

Error codes are generated by the event-log analysis and system configuration code.

Error codes help you to identify the cause of a problem, a failing component, and the service actions that might be needed to solve the problem.

Viewing logs and traces

The Storwize V7000 Unified clustered system maintains log files and trace files that can be used to manage your system and diagnose problems.

You can view information about collecting log files or you can view examples of a configuration dump, error log, or featurization log. To do this, click **Reference** in the left pane of the Storwize V7000 Unified Information Center and then expand the **Logs and traces** section.

Understanding the Storwize V7000 Unified battery operation for the control enclosure

Storwize V7000 Unified node canisters cache volume data and hold state information in volatile memory.

If the power fails, the cache and state data is written to a local solid-state drive (SSD) in the canister. The batteries within the control enclosure provide the power to write the cache and state data to a local drive.

Note: Storwize V7000 Unified expansion canisters do not cache volume data or store state information in volatile memory. They, therefore, do not require battery power. If ac power to both power supplies in an expansion enclosure fails, the enclosure powers off. When ac power is restored to at least one of the power supplies, the controller restarts without operator intervention.

There are two power supply units in the control enclosure. Each one contains an integrated battery. Both power supply units and batteries provide power to both control canisters. Each battery has a sufficient charge to power both node canisters for the duration of saving critical data to the local drive. In a fully redundant system with two batteries and two canisters, there is enough charge in the batteries to support saving critical data from both canisters to a local drive twice. In a system with a failed battery, there is enough charge in the remaining battery to support saving critical data from both canisters to a local drive once.

If the ac power to a control enclosure is lost, the canisters do not start saving critical data to a local drive until approximately 10 seconds after the loss of ac power is first detected. If the power is restored within this period, the system continues to operate. This loss in power is called a *brown out*. As soon as the saving of the critical data starts, the system stops handling I/O requests from the host applications, and Metro Mirror and Global Mirror relationships go offline. The system powers off when the saving of the critical data completes.

If both node canisters shut down without writing the cache and state data to the local drive, the system is unable to restart without an extended service action. The system configuration must be restored. If any cache write data is lost, volumes must be restored from a backup. It is, therefore, important not to remove the canisters or the power supply units from the control enclosures unless directed to

do so by the service procedures. Removing either of these components might prevent the node canister from writing its cache and state data to the local drive.

When the ac power is restored to the control enclosure, the system restarts without operator intervention. How quickly it restarts depends on whether there is a history of previous power failures.

When the ac power is restored after a power outage that causes both canisters to save their critical data, the system restarts only when the batteries have sufficient charge to power both canisters for the duration of saving the critical data again. In a fully redundant system with two batteries, this condition means that after one ac power outage and a saving of critical data, the system can restart as soon as the power is restored. If a second ac power outage occurs before the batteries have completed charging, then the system starts in service state and does not permit I/O operations to be restarted until the batteries are half charged. The recharging takes approximately 30 minutes.

In a system with a failed battery, an ac power failure causes both canisters to save critical data and completely discharges the remaining battery. When the ac power is restored, the system starts in service state and does not permit I/O operations to be restarted until the remaining battery is fully charged. The recharging takes approximately 1 hour.

A battery is considered failed for the following conditions:

- When the system can communicate with it and it reports an error.
- When the system is unable to communicate with the battery. Failed communication exists because the power supply, which contains the battery, has been removed or because the power supply has failed in a manner that makes communication with the battery impossible.

There are conditions other than loss of ac power that can cause critical data to be saved and the nodes to go into service state and not permit I/O operations. The node canister saves critical data if they detect there is no longer sufficient battery charge to support a saving of critical data. This situation happens when, for example, both batteries have two-thirds of a charge. The total charge that is available in the enclosure is sufficient to support a saving of critical data once; therefore, both canisters are in active state and I/O operations are permitted. If one battery fails though, the remaining battery has only two-thirds of a charge, and the total charge that is available in the enclosure is now insufficient to perform a saving of the critical data if the ac power fails. Data protection cannot be guaranteed in this case. The nodes save the critical data by using the ac power and enter service state. The nodes do not handle I/O operations until the remaining battery has sufficient charge to support the saving of the critical data. When the battery has sufficient charge, the system automatically restarts.

Important: Although Storwize V7000 Unified is resilient to power failures and brown outs, always install Storwize V7000 Unified in an environment where there is reliable and consistent ac power that meets the Storwize V7000 Unified requirements. Consider uninterruptible power supply units to avoid extended interruptions to data access.

Maintenance discharge cycles

Maintenance discharge cycles extend the lifetime of the batteries and ensure that the system can accurately measure the charge in the batteries. Discharge cycles guarantee that the batteries have sufficient charge to protect the Storwize V7000 Unified system.

Maintenance discharge cycles are scheduled automatically by the system and involve fully discharging a battery and then recharging it again. Maintenance discharges are normally scheduled only when the system has two fully charged batteries. This condition ensures that for the duration of the maintenance cycle, the system still has sufficient charge to complete a save of the critical data if the ac power fails. This condition also ensures that I/O operations continue while the maintenance cycle is performed. It is usual for both batteries to require a maintenance discharge at the same time. In these circumstances, the system automatically schedules the maintenance of one battery. When the maintenance on that battery completes, the maintenance on the other battery starts.

Maintenance discharges are scheduled for the following situations:

- A battery has been powered on for three months without a maintenance discharge.
- A battery has provided protection for saving critical data at least twice.
- A battery has provided protection for at least 10 brown outs, which lasted up to 10 seconds each.

A maintenance discharge takes approximately 10 hours to complete. If the ac power outage occurs during the maintenance cycle, the cycle must be restarted. The cycle is scheduled automatically when the battery is fully charged.

Under the following conditions, a battery is not considered when calculating whether there is sufficient charge to protect the system. This condition persists until a maintenance discharge cycle is completed.

- A battery is performing a maintenance discharge.
- A battery has provided protection for saving critical data at least four times without any intervening maintenance discharge.
- A battery has provided protection for at least 20 brown outs, which lasted up to 10 seconds each.
- A battery must restart a maintenance discharge because the previous maintenance cycle was disrupted by an ac power outage.

If a system suffers repeated ac power failures without a sufficient time interval in between the ac failures to complete battery conditioning, then neither battery is considered when calculating whether there is sufficient charge to protect the system. In these circumstances, the system enters service state and does not permit I/O operations to be restarted until the batteries have charged and one of the batteries has completed a maintenance discharge. This activity takes approximately 10 hours.

If one of the batteries in a system fails and is not replaced, it prevents the other battery from performing a maintenance discharge. Not only does this condition reduce the lifetime of the remaining battery, but it also prevents a maintenance discharge cycle from occurring after the battery has provided protection for at least 2 critical saves or 10 brown outs. Preventing this maintenance cycle from occurring increases the risk that the system accumulates a sufficient number of power outages to cause the remaining battery to be discounted when calculating whether

there is sufficient charge to protect the system. This condition results in the system entering service state while the one remaining battery performs a maintenance discharge. I/O operations are not permitted during this process. This activity takes approximately 10 hours.

Understanding the medium errors and bad blocks

A storage system returns a medium error response to a host when it is unable to successfully read a block. The Storwize V7000 Unified response to a host read follows this behavior.

The volume virtualization that is provided extends the time when a medium error is returned to a host. Because of this difference to non-virtualized systems, the Storwize V7000 Unified uses the term *bad blocks* rather than medium errors.

The Storwize V7000 Unified allocates volumes from the extents that are on the managed disks (MDisks). The MDisk can be a volume on an external storage controller or a RAID array that is created from internal drives. In either case, depending on the RAID level used, there is normally protection against a read error on a single drive. However, it is still possible to get a medium error on a read request if multiple drives have errors or if the drives are rebuilding or are offline due to other issues.

The Storwize V7000 Unified provides migration facilities to move a volume from one underlying set of physical storage to another or to replicate a volume that uses FlashCopy or Metro Mirror or Global Mirror. In all these cases, the migrated volume or the replicated volume returns a medium error to the host when the logical block address on the original volume is read. The system maintains tables of bad blocks to record where the logical block addresses that cannot be read are. These tables are associated with the MDisks that are providing storage for the volumes.

The `dumpdiskbadblocks` command and the `dumpa11mdiskbadblocks` command are available to query the location of bad blocks.

Important: The `dumpdiskbadblocks` only outputs the virtual medium errors that have been created, and not a list of the actual medium errors on MDisks or drives.

It is possible that the tables that are used to record bad block locations can fill up. The table can fill either on an MDisk or on the system as a whole. If a table does fill up, the migration or replication that was creating the bad block fails because it was not possible to create an exact image of the source volume.

The system creates alerts in the event log for the following situations:

- When it detects medium errors and creates a bad block
- When the bad block tables fill up

The following errors are identified:

Table 36. Bad block errors

| Error code | Description |
|------------|---|
| 1840 | The managed disk has bad blocks. On an external controller, this can only be a copied medium error. |

Table 36. Bad block errors (continued)

| Error code | Description |
|------------|--|
| 1226 | The system has failed to create a bad block because the MDisk already has the maximum number of allowed bad blocks. |
| 1225 | The system has failed to create a bad block because the system already has the maximum number of allowed bad blocks. |

The recommended actions for these alerts guide you in correcting the situation.

Clear bad blocks by deallocating the volume disk extent, by deleting the volume or by issuing write I/O to the block. It is good practice to correct bad blocks as soon as they are detected. This action prevents the bad block from being propagated when the volume is replicated or migrated. It is possible, however, for the bad block to be on part of the volume that is not used by the application. For example, it can be in part of a database that has not been initialized. These bad blocks are corrected when the application writes data to these areas. Before the correction happens, the bad block records continue to use up the available bad block space.

Resolving a problem

Described here are some procedures to help resolve fault conditions that might exist on your system and which assume a basic understanding of the Storwize V7000 Unified system concepts.

The following procedures are often used to find and resolve problems:

- Procedures that involve data collection and system configuration
- Procedures that are used for hardware replacement.

Always use the recommended actions on the Events panel of the management GUI as the starting point to diagnose and resolve a problem.

The following topics describe a type of problem that you might experience, that is not resolved by using the management GUI. In those situations, review the symptoms and follow the actions that are provided here.

The “Start here: Use the management GUI recommended actions” topic gives the starting point for any service action. The situations covered in this section are the cases where you cannot start the management GUI or the node canisters in the control enclosure are unable to run the system software.

Note: After you have created your clustered system, remove hardware components only when directed to do so by the fix procedures. Failure to follow the procedures can result in loss of access to data or loss of data. Follow the fix procedures when servicing a control enclosure.

Start here: Use the management GUI recommended actions

The management GUI provides extensive facilities to help you troubleshoot and correct problems on your system.

You can connect to and manage a Storwize V7000 Unified system as soon as you have completed the USB initialization.

When you have logged on, select **Monitoring > Events**. You can work with two separate event logs:

- To work with events for the file modules, select the **File** tab. No fix procedures are available to be run. From the Storwize V7000 Unified Information Center, look up the errors.
- To work with events for the storage system, select the **Block** tab.

For the Storwize V7000 storage system, depending on how you choose to filter alerts, you might see only the alerts that require attention, alerts and messages that are not fixed, or all event types whether they are fixed or unfixed.

Select the recommended alert, or any other alert, and run the fix procedure. The fix procedure steps you through the process of troubleshooting and correcting the problem. The fix procedure displays information that is relevant to the problem and provides various options to correct the problem. Where it is possible, the fix procedure runs the commands that are required to reconfigure the system.

Always use the recommended action for an alert because these actions ensure that all required steps are taken. Use the recommended actions even in cases where the service action seems obvious, such as a drive showing a fault. In this case, the drive must be replaced and reconfiguration must be performed. The fix procedure performs the reconfiguration for you.

The fix procedure also checks that another existing problem does not result in a fix procedure that causes volume data to be lost. For example, if a power supply unit in a node enclosure must be replaced, the fix procedure checks and warns you if the integrated battery in the other power supply unit is not sufficiently charged to protect the system.

If possible, fix the alerts in the order shown to resolve the most serious issues first. Often, other alerts are fixed automatically because they were the result of a more serious issue.

After all the alerts are fixed, go to “Procedure: Checking the status of your system” on page 197.

Problem: Another system may be using the system IP address

Another system may also be connected to your network, using the same IP address that is used for management communications to the Storwize V7000 system. This problem is also known as a duplicate IP address.

The system IP address of the Storwize V7000 is set when the USB initialization of the Storwize V7000 is successfully completed. It is possible for this to happen even if the IP address is already used by another system on your network.

It is also possible that somebody could setup another machine on your network which uses the IP address that your Storwize V7000 system is already using.

The result is that communications can go to and come from the wrong system causing intermittent file module to Storwize V7000 system CLI communication problems.

To check for a duplicate IP address in the local network you can attempt to use the **arping** Linux command on another machine in the same subnet as the control enclosure For example:

```
arping -c 2 -w 3 -I eth0 <V7000 system IP address>
```

If the responses show more than one MAC address (in the square brackets) then there is a duplicate IP address in the local network.

To check for a duplicate IP address in your wider network you can disconnect Ethernet port 1 from each node canister and attempt to ping the IP address from another system in the same subnet.

If you plan to change the IP settings on the storage system but can not ssh to the current system IP to run the **chsystemip** CLI command then refer to “Problem: Unable to change the system IP address because you cannot access the CLI.”

If you plan to change the system IP address and can ssh to the current system IP address, then you can run the **chsystemip** CLI command. Here is an example:

```
>ssh superuser@<system IP address>  
$ chsystemip -clusterip 9.20.136.5 -gw 9.20.136.1 -mask 255.255.255.0 -port 1
```

The default password for superuser is **passwd0rd**.

Update the file module's record of the control enclosure system IP:

To find the file module's current record of the control enclosure system IP address, use the Storwize V7000 Unified management CLI to issue the **lsstoragesystem** command. Here is an example:

```
>ssh admin@<management_IP>  
[kd01ghf.ibm]$ lsstoragesystem  
name          primaryIP      secondaryIP    id  
StorwizeV7000 9.11.137.130 9.11.137.130 00000200A2601508  
EFSSG1000I The command completed successfully.
```

If the primary and secondary IP address shown by the **lsstoragesystem** CLI do not match the system IP addresses shown in the output of the **lssystemip** CLI command, then it is necessary to update the record. The **chstoragesystem** command changes the file module record of the control enclosure system IP. Here is an example:

```
>[kd01ghf.ibm]$ chstoragesystem --ip1 9.71.18.136 --ip2 9.71.18.136  
EFSSG1000I The command completed successfully.
```

Verify that communication from the file module to the control enclosure is now possible by running the **lssystem** command on the Storwize V7000 Unified management CLI:

```
>ssh admin@<management IP address>  
[kd01ghf.ibm]$ lssystemip
```

Problem: Unable to change the system IP address because you cannot access the CLI

This topic helps you if you plan to change the system IP address using the **chsystemip** CLI command but can not ssh to the system IP address to access the CLI. For example, when another machine on your network is using the same IP address.

About this task

If you need to change the IP settings on the storage system but can not ssh on to the current system IP to run the **chsystemip** CLI command then use a nodes canister service IP address to access the CLI. Find the service IP address for each node canister in `satask_results.html` that was returned on the USB flash drive when

the Storwize V7000 was initialized or any time that you insert the USB flash drive into the control enclosure. You should also be able to tell which node canister is currently the main configuration node.

If the control enclosure service IP addresses cannot be reached using ssh, then it can be set using the InitTool and USB flash drive. Refer to “Procedure: Changing the service IP address of a node canister” on page 206.

Changing the system IP of the control enclosure using the service CLI:

Login to the service IP of the main configuration node canister using ssh as superuser. The default password is passw0rd. Issue the chsystemip CLI command to set new IP values. Here is an example:

```
>ssh superuser@<service-ip>
$ chsystemip -clusterip 9.20.136.5 -gw 9.20.136.1 -mask 255.255.255.0 -port 1
```

You may receive the following error:

```
CMMVC5732E The command cannot be initiated because it was not run on
the configuration node.
```

This may indicate that the node you are currently logged in to is not the configuration node for the system. Log out and login using ssh to the other node canister service IP. Then issue the **chsystemip** command again.

If your system includes file modules that have not been initialized yet (for example, the blue identify indicators are blinking) then start the USB initialization process again but this time provide the new Storwize V7000 system IP. This time there is no need to insert the USB flash drive into the control enclosure because it will ignore the mknacluster command in satask.txt; the block cluster is already made but the USB flash drive should be successfully initialized.

If your system includes USB flash drive that have already been successfully initialized, then after the control enclosure system IP address has been changed, it is necessary to ensure that the USB flash drive record of the address matches.

Updating file module's record of the control enclosure system IP:

To find the USB flash drive current record of the control enclosure system IP address, use the Storwize V7000 Unified management CLI to issue the **lsstoragesystem** command. Here is an example:

```
>ssh admin@<management_IP>
[kd01ghf.ibm]$ lsstoragesystem
name          primaryIP    secondaryIP  id
StorwizeV7000 9.11.137.130 9.11.137.130 00000200A2601508
EFSSG1000I The command completed successfully.
```

If the primary and secondary IP address shown by the **lsstoragesystem** CLI do not match the system IP addresses then it is necessary to update the record. The **chstoragesystem** command changes the file module record of the control enclosure system IP. Here is an example:

```
>[kd01ghf.ibm]$ chstoragesystem --ip1 9.71.18.136 --ip2 9.71.18.136
EFSSG1000I The command completed successfully.
```

Verify that communication from the file module to the control enclosure is now possible by running the **lssystemip** command on the Storwize V7000 Unified management CLI:

```
>ssh admin@v7000-unified  
[kd01ghf.ibm]$ lssystemip
```

Problem: Management IP address unknown

This topic helps you if you are not able to run the management GUI because you do not know the IP address. This address is also known as the management IP address.

This topic also helps if the configuration communication between the file system (file modules) and the control enclosure is not working because the wrong IP address is being used.

The management IP address is set when the USB initialization is completed. An address for port 2 can be added later.

Problem: Unable to connect to the management GUI

If you are unable to connect to the management GUI from your web browser and received a Page not found or similar error, this information might help you resolve the issue.

Consider the following possibilities if you are unable to connect to the management GUI:

- You cannot connect if the system is not operational with at least one node online. If you know the service address of a node canister, go to “Procedure: Getting node canister and system information using the service assistant” on page 198; otherwise, go to “Procedure: Getting node canister and system information using a USB flash drive” on page 198 and obtain the state of each of the node canisters from the data that is returned. If there is not a node canister with a state of active, resolve the reason why it is not in active state. If the state of all node canisters is candidate, then there is not a clustered system to connect to. If all nodes are in a service state, go to “Procedure: Fixing node errors” on page 206.
- Ensure that you are using the correct system IP address. If you know the service address of a node canister, go to “Procedure: Getting node canister and system information using the service assistant” on page 198; otherwise, go to “Procedure: Getting node canister and system information using a USB flash drive” on page 198 and obtain the management IP address from the data that is returned.
- Ensure that all node canisters have an Ethernet cable that is connected to port 1 and that the port is working. To understand the port status, go to “Procedure: Finding the status of the Ethernet connections” on page 204.
- Ping the management address to see if the Ethernet network permits the connection. If the ping fails, check the Ethernet network configuration to see if there is a routing or a firewall issue. Ensure that the Ethernet network configuration is compatible with the gateway and subnet or prefix settings. Ensure that you have not used the Ethernet address of another device as the management address. If necessary, modify your network settings to establish a connection.
- If the system IP address settings are incorrect for your environment, take these steps:
 1. Determine the service address of the configuration node canister. You can determine this if you can access the service assistant on any node canister, alternatively use the summary data returned, when a USB flash drive is plugged into a node canister.

2. You can temporarily run the management GUI on the service address of the configuration node. Point your browser to *service address/gui*. For example, if the service address of the configuration node is 11.22.33.44, point your browser to 11.22.33.44/gui.
3. Use the options in the **settings > network** panel to change the management IP settings.
4. As an alternative to using the management GUI, you can use the **chsystemip** CLI command to correct the system IP address settings by using ssh to the service IP of the configuration node.

Problem: Unable to log on to the management GUI

This topic assists you when you can see the management GUI login screen but cannot log on.

Log on using your user name and password. Follow the suggested actions when you encounter a specific situation:

- If you are not logging on as superuser, contact your system administrator who can verify your user name and reset your account password.
- If the user name that you are using is authenticated through a remote authentication server, verify that the server is available. If the authentication server is unavailable, you can log on as user name superuser. This user is always authenticated locally.
- If you do not know the password for superuser, go to “Procedure: Resetting superuser password” on page 197.

Problem: Cannot initialize or create a system

This topic helps if your attempt to create a system has failed.

Note: This clustered storage system is different from the file system cluster on the file modules.

The failure is reported regardless of the method that you used to create a clustered storage system:

- USB flash drive
- management console
- Service assistant
- Service command line

The create clustered-system function protects the system from loss of volume data. If you create a clustered system on a control enclosure that was previously used, you lose all of the volumes that you previously had. To determine if there is an existing system, use data that is returned by “Procedure: Getting node canister and system information using the service assistant” on page 198 or “Procedure: Getting node canister and system information using a USB flash drive” on page 198.

- The node canister that you are attempting to create a clustered system on is in candidate state. The node canister is in candidate state if it is a new canister.
- The partner node canister in the control enclosure is not in active state.
- The latest system ID of the control enclosure is 0.

If the create function failed because there is an existing system, fix the existing clustered system; do not re-create a new clustered system. If you want to create a clustered system and do not want to use any data from the volumes used in the

previous clustered system, go to “Procedure: Deleting a system completely” on page 205, and then run the create function again.

You might not be able to create a cluster if the node canister (the one on which you are attempting to create the clustered system) is in service state. Check whether the node canister is in service state by using the data returned by “Procedure: Getting node canister and system information using the service assistant” on page 198 or “Procedure: Getting node canister and system information using a USB flash drive” on page 198. If the node is in service state, fix the reported node errors. For more information, go to “Procedure: Fixing node errors” on page 206. After the node error is corrected, attempt to create a clustered storage system again.

Problem: Node canister service IP address unknown

This topic describes the methods that you can use to determine the service address of a node canister.

A default service address is initially assigned to each node canister, as shown in Table 37 on page 193. Try using these addresses if the node has not been reconfigured, and the addresses are valid on your network.

If you are able to access the management GUI, the service IP addresses of the node canisters are shown by selecting a node and port at **Settings > Network > Service IP Addresses**.

If you are unable to access the management GUI but you know the management IP address of the system, you can use the address to log into the service assistant that is running on the configuration node.

1. Point your browser at the /service directory of the management IP address of the system. If your management IP address is 11.22.33.44, point your web browser to 11.22.33.44/service.
2. Log into the service assistant.
3. The service assistant home page lists the node canister that can communicate with the node.
4. If the service address of the node canister that you are looking for is listed in the Change Node window, make the node the current node. Its service address is listed under the Access tab of the node details.

If you know the service IP address of any node canister in the system, you can log into the service assistant of that node. Follow the previous instructions for using the service assistant, but at step 1, point your browser at the /service directory of the service IP address you know. If you know a service IP address is 11.22.33.56, point your web browser to 11.22.33.56/service.

Some types of errors can prevent nodes from communicating with each other; in that event, it might be necessary to point your browser directly at the service assistant of the node that requires administering, rather than change the current node in the service assistant.

If you are unable to find the service address of the node using the management GUI or service assistant, you can also use a USB flash drive to find it. For more information, see “Procedure: Getting node canister and system information using a USB flash drive” on page 198.

Table 37. Default service IP addresses

| Canister and port | IPv4 address | IPv4 subnet mask |
|----------------------------------|----------------|------------------|
| Canister 1 (left) port 1 (left) | 192.168.70.121 | 255.255.255.0 |
| Canister 2 (right) port 1 (left) | 192.168.70.122 | 255.255.255.0 |

Problem: Cannot connect to the service assistant

This topic provides assistance if you are unable to display the service assistant on your browser.

You might encounter a number of situations when you cannot connect to the service assistant.

- Check that you have entered the “/service” path after the service IP address. Point your web browser to `<control enclosure management IP address>/service` for the node that you want to work on. For example, if you set a service address of 11.22.33.44 for a node canister, point your browser to 11.22.33.44/service.
- Check that you are using the correct service address for the node canister. To find the IPv4 and IPv6 addresses that are configured on the node, go to “Problem: Node canister service IP address unknown” on page 192. Try accessing the service assistant through these addresses. Verify that the IP address, subnet, and gateway are specified correctly for IPv4 addresses. Verify that the IP address, prefix, and gateway are specified for the IPv6 addresses. If any of the values are incorrect, see “Procedure: Changing the service IP address of a node canister” on page 206.
- You cannot connect to the service assistant if the node canister is not able to start the code. To verify that the LEDs indicate that the code is active, see “Procedure: Understanding the system status using the LEDs” on page 199.
- The service assistant is configured on Ethernet port 1 of a node canister. Verify that an Ethernet cable is connected to this port and to an active port on your Ethernet network. See “Procedure: Finding the status of the Ethernet connections” on page 204 for details.
- Ping the management address to see if the Ethernet network permits the connection. If the ping fails, check the Ethernet network configuration to see if there is a routing or a firewall issue. Check that the Ethernet network configuration is compatible with the gateway and subnet or prefix settings. Check that you have not used an address that is used by another device on your Ethernet network. If necessary, change the network configuration or see “Procedure: Changing the service IP address of a node canister” on page 206 to change the service IP address of a node.
- A default service address is initially assigned to each node canister. The service IP address 192.168.70.121 subnet mask 255.255.255.0 is preconfigured on Ethernet port 1 of the upper canister, canister 1. The service IP address 192.168.70.122 subnet mask 255.255.255.0 is preconfigured on Ethernet port 1 of the lower canister, canister 2.

You might not be able to access these addresses because of the following conditions:

- These addresses are the same as the addresses that are used by other devices on the network.
- These addresses cannot be accessed on your network.
- There are other reasons why they are not suitable for use on your network.

If the previous conditions apply, see “Procedure: Changing the service IP address of a node canister” on page 206 to change the service IP address to one that works in your environment.

If you are unable to change the service address, for example, because you cannot use a USB flash drive in the environment, see “Procedure: Accessing a canister using a directly attached Ethernet cable” on page 207.

Problem: Management GUI or service assistant does not display correctly

This topic provides assistance if the Management GUI or the service assistant does not display correctly.

You must use a supported web browser. For a list of supported browsers, see Planning > Planning for software Web browser requirements to access the management GUI in the Information Center.

Problem: A node canister has a location node error

The node error listed on the service assistant home page or in the event log can indicate a location error.

A location error means that the node canister or the enclosure midplane has been moved or changed. This is normally due to a service action not being completed or not being implemented correctly.

A number of different conditions are reported as location errors. Each condition is indicated by different node error. To find out how to resolve the node error, go to “Procedure: Fixing node errors” on page 206.

Be aware that after a node canister has been used in a system, the node canister must not be moved to a different location, either within the same enclosure or in a different enclosure because this might compromise its access to storage, or a host application's access to volumes. Do not move the canister from its original location unless directed to do so by a service action.

Problem: SAS cabling not valid

This topic provides information to be aware of if you receive errors that indicate the SAS cabling is not valid.

Check the following items:

- No more than five expansion enclosures can be chained to port 1 (below the control enclosure). The connecting sequence from port 1 of the node canister is called chain 1.
- No more than four expansion enclosures can be chained to port 2 (above the control enclosure). The connecting sequence from port 2 of the node canister is called chain 2.
- Do not connect a SAS cable between a port on an upper canister and a port on a lower canister.
- In any enclosure, the same ports must be used on both canisters.
- No SAS cable can be connected between ports in the same enclosure.
- For any enclosure, the cables that are connected to SAS port 1 on each canister must attach to the same enclosure. Similarly, for any enclosure, the cables that

are connected to SAS port 2 on each canister must attach to the same enclosure. Cable attachments for SAS port 1 and cable attachments for SAS port 2 do not go to the same enclosure.

- For cables connected between expansion enclosures, one end is connected to port 1 while the other end is connected to port 2.
- For cables that are connected between a control enclosure and expansion enclosures, port 1 must be used on the expansion enclosures.
- The last enclosure in a chain must not have cables in port 2 of canister 1 and port 2 of canister 2.
- Ensure that each SAS cable is fully inserted.

Problem: New expansion enclosure not detected

This topic helps you resolve why a newly installed expansion enclosure was not detected by the system.

When installing a new expansion enclosure, follow the management GUI Add Enclosure wizard, which is available from the **Manage Devices Actions** menu.

If the expansion enclosure is not detected, perform the following verifications:

- Verify the status of the LEDs at the back of the expansion enclosure. At least one power supply unit must be on with no faults shown. At least one canister must be active, with no fault LED on, and all the serial-attached SCSI (SAS) port 1 LEDs must be on. For details about the LED status, see “Procedure: Understanding the system status using the LEDs” on page 199.
- Verify that the SAS cabling to the expansion enclosure is correctly installed. To review the requirements, see “Problem: SAS cabling not valid” on page 194.

Problem: Mirrored volume copies no longer identical

The management GUI provides options to either check copies that are identical or to check that the copies are identical and to process any differences that are found.

To confirm that the two copies of a mirrored volume are still identical, choose the volume view that works best for you. Select one of the volume copies in the volume that you want to check. From the **Actions** menu, select the **Validate Volume Copies** option.

You have the following choices:

- Validate that the volume copies are identical.
- Validate that the volume copies are identical, mark, and repair any differences that are found.

If you want to resolve any differences, you have the following options:

- Consider that one volume is correct and make the other volume copy match the other copy if any differences are found. The primary volume copy is the copy that is considered correct.
- Do not assume that either volume copy is correct. If a difference is found, the sector is marked. A media error is returned if the volume is read by a host application.

Problem: Command file not processed from USB flash drive

This information assists you in determining why the command file is not being processed, when using a USB flash drive.

You might encounter this problem during initial setup or when running commands if you are using your own USB flash drive rather than the USB flash drive that was packaged with your order.

If you encounter this situation, verify the following items:

- That an `satask_result.html` file is in the root directory on the USB flash drive. If the file does not exist, then the following problems are possible:
 - The USB flash drive is not formatted with the correct file system type. Use any USB flash drive that is formatted with FAT32 file system on its first partition; for example, NTFS is not a supported type. Reformat the key or use a different key.
 - The USB port is not working. Try the key in the other USB port.
 - The node is not operational. Check the status using the LEDs. See “Procedure: Understanding the system status using the LEDs” on page 199.
- If there is a `satask_result.html` file, check the first entry in the file. If there is no entry that matches the time the USB flash drive was used, it is possible that the USB port is not working or the node is not operational. Check the node status using the LEDs. See “Procedure: Understanding the system status using the LEDs” on page 199.
- If there is a status output for the time the USB flash drive was used, then the `satask.txt` file was not found. Check that the file was named correctly. The `satask.txt` file is automatically deleted after it has been processed.

Procedure: FCoE host-link

About this task

If you are having problems attaching to the FCoE hosts, your problem might be related to the network, the Storwize V7000 Unified system, or the host.

Procedure

1. If you are seeing error code 705 on the node, this means Fibre Channel I/O port is inactive. Note that FCoE uses Fibre Channel as a protocol and an Ethernet as an interconnect. If you are dealing with an FCoE enabled port that means either the Fibre Channel Forwarder (FCF) is not seen or the FCoE feature is not configured on the switch:
 - a. Check that the FCoE feature is enabled on the FCF.
 - b. Check the remote port (switch port) properties on the FCF.
2. If you connecting the host through a Converged Enhanced Ethernet (CEE) switch, for network problems, you can attempt any of the following actions:
 - a. Test your connectivity between the host and CEE switch.
 - b. Ask the Ethernet network administrator to check the firewall and router settings.
3. Please run `svcinfo lsfabric` and check that the host is seen as a remote port in the output. If not, then do the following tasks in order:
 - a. Verify that Storwize V7000 Unified and host get an `fcid` on FCF. If not, check the VLAN configuration.
 - b. Verify that Storwize V7000 Unified and host port are part of a zone and that zone is currently in force.
 - c. Verify the volumes are mapped to the host and that they are online. See `lshostvdiskmap` and `lsvdisk` in the CLI configuration guide for more information.

4. If you still have FCoE problems, you can attempt the following action:
 - a. Verify that the host adapter is in good state. You can unload and load the device driver and see the operating system utilities to verify that the device driver is installed, loaded, and operating correctly.

Procedure: Resetting superuser password

You can reset the superuser password to the default password of `passwd` by using a USB flash drive command action.

About this task

You can use this procedure to reset the superuser password if you have forgotten the password. This command runs differently depending on whether you run it on a node canister that is active in a clustered system.

Note: If a node canister is not in active state, the superuser password is still required to log on to the service assistant.

It is possible to configure your system so that resetting the superuser password with the USB flash drive command action is not permitted. If your system is configured this way, there is no work-around. Contact the person who knows the password.

To use a USB flash drive to reset the superuser password, see “USB flash drive and Initialization tool interface” on page 170.

See also “Problem: Unable to log on to the management GUI” on page 191.

Results

If the node canister is active in a clustered system, the password for superuser is changed on the clustered system. If the node canister is not in active state, the superuser password for the node canister is changed. If the node canister joins a clustered system later, the superuser password is reset to that of the clustered system.

Procedure: Identifying which enclosure or canister to service

Use this procedure to identify which enclosure or canister must be serviced.

About this task

Procedure

Use the following options to identify an enclosure. An enclosure is identified by its ID and serial number.

Procedure: Checking the status of your system

Use this procedure to verify the status of objects in your system using the management GUI. If the status of the object is not online, view the alerts and run the recommended fix procedures.

About this task

Volumes normally show offline because another object is offline. A volume is offline if one of the MDisks that makes up the storage pool that it is in is offline. You do not see an alert that relates to the volume; instead, the alert relates to the MDisk. Performing the fix procedures for the MDisk enables the volume to go online.

Procedure

Use the following management GUI functions to find a more detailed status:

- **Monitoring > System Details**
- **Monitoring > Manage Device**
- **Pools > MDisks by Pools**
- **Volumes > Volumes**
- **Monitoring > Events**, and then use the filtering options to display alerts, messages, or event types.

Procedure: Getting node canister and system information using the service assistant

This procedure explains how to view information about the node canisters and system using the service assistant.

About this task

To obtain the information:

1. Log on to the service assistant, as described in “Accessing the service assistant” on page 168
2. View the information about the node canister to which you connected or the other node canister in the enclosure. To change which node's information is shown, select the node in the **Change Node** table of the Home page.

The Home page shows a table of node errors that exist on the node canister and a table of node details for the current node. The node errors are shown in priority order.

The node details are divided into several sections. Each section has a tab. Examine the data that is reported in each tab for the information that you want.

- The Node tab shows general information about the node canister that includes the node state and whether it is a configuration node.
- The Hardware tab shows information about the hardware.
- The Access tab shows the management IP addresses and the service addresses for this node.
- The Location tab identifies the enclosure in which the node canister is located.
- The Ports tab shows information about the I/O ports.

Procedure: Getting node canister and system information using a USB flash drive

This procedure explains how to view information about the node canister and system using a USB flash drive.

About this task

Use any USB flash drive with a FAT32 file system on its first partition.

1. Ensure that the USB flash drive does not contain a file named `satask.txt` in the root directory.

If `satask.txt` does exist in the directory, the node attempts to run the command that is specified in the file. The information that is returned is appended to the `satask_result.html` file. Delete this file if you no longer want the previous output.

Procedure

1. Insert the USB flash drive in one of the USB ports of the node canister from which you want to collect data.
2. The node canister fault LED flashes while information is collected and written to the USB flash drive.
3. Wait until the LED stops flashing before removing the USB flash drive. Because the LED is a fault indicator, it might remain permanently on or off.
4. View the results in file `satask_result.html` in a web browser. The file contains the details and results of the command that was run and the status and the configuration information from the node canister.

Procedure: Understanding the system status using the LEDs

This procedure helps you determine the system status using the LED indicators on the system.

About this task

The LEDs provide a general idea of the system status. You can obtain more detail from the management GUI and the service assistant. Examine the LEDs when you are not able to access the management GUI or the service assistant, or when the system is not showing any information about a device.

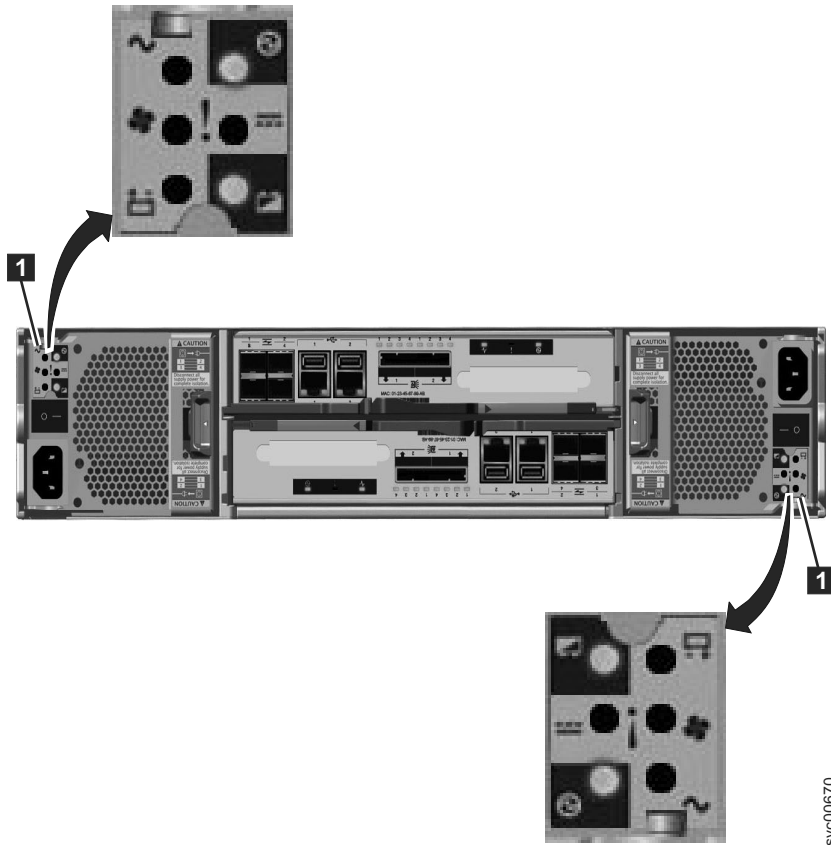
The procedure shows the status for the enclosure chassis, power supply units and batteries, and canisters. It does not show the status for the drives.

The first step is to determine the state of the control enclosure, which includes its power supply units, batteries, and node canisters. Your control enclosure is operational if you can manage the system using the management GUI. You might also want to view the status of the individual power supply units, batteries, or node canisters.

Find the control enclosure for the system that you are troubleshooting. There is one control enclosure in a system. If you are unsure which one is the control enclosure, go to “Procedure: Identifying which enclosure or canister to service” on page 197.

Procedure

1. Use the state of the ac power failure, power supply OK, fan failure, and dc power failure LEDs on each power supply unit in the enclosure to determine if there is power to the system, or if there are power problems. Figure 35 on page 200 shows the LEDs on the power supply unit for the 2076-112 or 2076-124. The LEDs on the power supply units for the 2076-312 and 2076-324 are similar, but they are not shown here.



svc00670

Figure 35. LEDs on the power supply units of the control enclosure

Table 38. Power-supply unit LEDs









| Power supply OK  | ac failure  | Fan failure  | dc failure  | Status | Action |
|--|---|--|---|--|--|
| On | On | On | On | Communication failure between the power supply unit and the enclosure chassis | Replace the power supply unit. If failure is still present, replace the enclosure chassis. |
| Off | Off | Off | Off | No ac power to the enclosure. | Turn on power. |
| Off | Off | Off | On | The ac power is on but power supply unit is not seated correctly in the enclosure. | Seat the power supply unit correctly in the enclosure. |

Table 38. Power-supply unit LEDs (continued)

| Power supply status  | ac failure  | Fan failure  | dc failure  | Status | Action |
|--|---|--|---|--|--|
| Off | On | Off | On | No ac power to this power supply | <ol style="list-style-type: none"> 1. Check that the switch on the power supply unit is on. 2. Check that the ac power is on. 3. Reseat and replace the power cable. |
| On | Off | Off | Off | Power supply is on and operational. | No actions |
| Off | Off | On | Off | Fan failure | Replace the power supply unit. |
| Off | On | On | On | Communication failure and power supply problem | Replace the power supply unit. If replacing the power supply unit does not fix the problem, replace the enclosure chassis. |
| Flashing | X | X | X | No canister is operational. | Both canisters are either off or not seated correctly. Turn off the switch on both power supply units and then turn on both switches. If this action does not resolve the problem, remove both canisters slightly and then push the canisters back in. |
| Off | Flashing | Flashing | Flashing | Firmware is downloading. | No actions. Do not remove ac power. Note: In this case, if there is a battery in a power supply unit, its LEDs also flash. |

2. At least one power supply in the enclosure must indicate Power supply OK or Power supply firmware downloading for the node canisters to operate. For this situation, review the three canister status LEDs on each of the node canisters. Start with the power LED.

Table 39. Power LEDs


| Power LED status  | Description |
|---|--|
| Off | There is no power to the canister. Try reseating the canister. Go to “Procedure: Reseating a node canister” on page 208. If the state persists, follow the hardware replacement procedures for the parts in the following order: node canister, enclosure chassis. |

Table 39. Power LEDs (continued)


| Power LED status  | Description |
|--|---|
| Slow flashing (1 Hz) | Power is available, but the canister is in standby mode. Try to start the node canister by reseating it. Go to “Procedure: Reseating a node canister” on page 208. |
| Fast flashing (2 Hz) | The canister is running its power-on self-test (POST). Wait for the test to complete. If the canister remains in this state for more than 10 minutes, try reseating the canister. Go to “Procedure: Reseating a node canister” on page 208. If the state persists, follow the hardware replacement procedure for the node canister. |

Figure 36 shows the LEDs on the node canister.

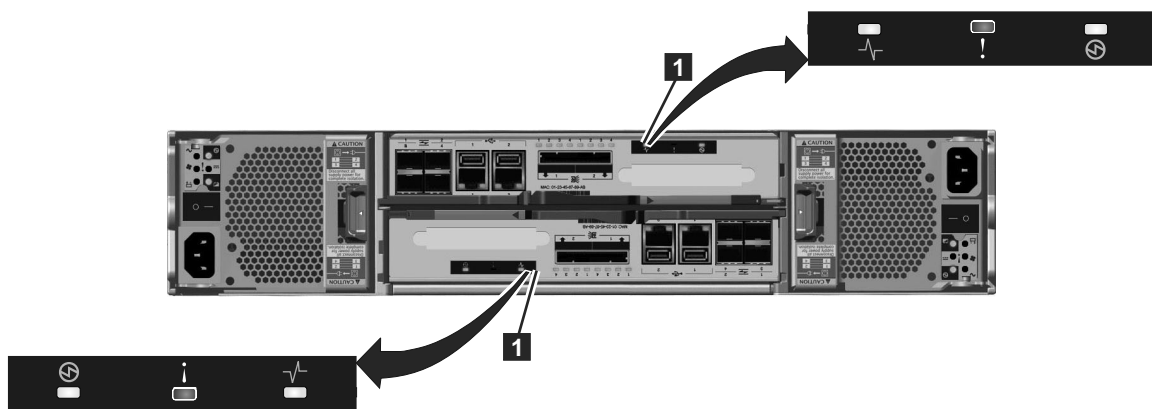


Figure 36. LEDs on the node canisters

- If the power LED is on, consider the states of the clustered-system status and fault LEDs.

Table 40. System status and fault LEDs







| System status LED  | Fault LED  | Status  | Action |
|---|---|--|--|
| Off | Off | Code is not active. | <ul style="list-style-type: none"> Follow procedures for reviewing power LEDs. If the power LEDs show green, reseal the node canister. See “Procedure: Reseating a node canister” on page 208. If the LED status does not change, see “Replacing a node canister” on page 210. |
| Off | On | Code is not active. The BIOS or the service processor has detected a hardware fault. | Follow the hardware replacement procedures for the node canister. |
| On | Off | Code is active. Node state is active. | No action. The node canister is part of a clustered system and can be managed by the management GUI. |

Table 40. System status and fault LEDs (continued)

| System status LED  | Fault LED  | Status  | Action |
|--|---|---|---|
| On | On | Code is active and is in starting state. However, it does not have enough resources to form the clustered system. | The node canister cannot become active in a clustered system. There are no detected problems on the node canister itself. However, it cannot connect to enough resources to safely form a clustered system. Follow the procedure to fix the node errors. Go to "Procedure: Fixing node errors" on page 206. |
| Flashing | Off | Code is active. Node state is candidate. | Create a clustered system on the node canister, or add the node canister to the clustered system. If the other node canister in the enclosure is in active state, it automatically adds this node canister into the clustered system. A node canister in this state can be managed using the service assistant. |
| Flashing | On | Code is active. Node state is service. | The node canister cannot become active in a clustered system. Several problems can exist: hardware problem, a problem with the environment or its location, or problems with the code or data on the canister. Follow the procedure to fix the node errors. Go to "Procedure: Fixing node errors" on page 206. |
| Any | Flashing | The node canister is being identified so that you can locate it. | The fix procedures in the management GUI might have identified the component because it requires servicing. Continue to follow the fix procedures. The service assistant has a function to identify node canisters. If the identification LED is on in error, use the service assistant node actions to turn off the LED. |

Results

To review the status of the control enclosure batteries, see Table 41.

Table 41. Control enclosure battery LEDs





| Battery Good  | Battery Fault  | Description | Action |
|---|--|--|--------|
| On | Off | Battery is good and fully charged. | None |
| Flashing | off | Battery is good but not fully charged. The battery is either charging or a maintenance discharge is being performed. | None |

Table 41. Control enclosure battery LEDs (continued)

| Battery Good  | Battery Fault  | Description | Action |
|---|--|--|--|
| Off | On | Nonrecoverable battery fault. | Replace the battery. If replacing the battery does not fix the issue, replace the power supply unit. |
| Off | Flashing | Recoverable battery fault. | None |
| Flashing | Flashing | The battery cannot be used because the firmware for the power supply unit is being downloaded. | None |

Procedure: Finding the status of the Ethernet connections

This procedure explains how to find the status of the Ethernet connections when you cannot connect.

About this task

Ethernet port 1 must be connected to an active port on your Ethernet network. Determine the state of the Ethernet LEDs by using one of the following methods:

- If the node software is active on the node, use the USB flash drive to obtain the most comprehensive information for the node status. Go to “Procedure: Getting node canister and system information using a USB flash drive” on page 198. The status, speed, and MAC address are returned for each port. Information is returned that identifies whether the node is the configuration node and whether any node errors were reported.
- Examine the LEDs of the Ethernet ports. For the status of the LEDs, go to Ethernet ports and indicators.

Procedure

If your link is not connected, complete the following actions to check the port status each time until it is corrected or connected.

1. Verify that each end of the cable is securely connected.
2. Verify that the port on the Ethernet switch or hub is configured correctly.
3. Connect the cable to a different port on your Ethernet network.
4. If the status is obtained using the USB flash drive, review all the node errors that are reported.
5. Replace the Ethernet cable.

Procedure: Removing system data from a node canister

This procedure guides you through the process to remove system information from a node canister. The information that is removed includes configuration data, cache data, and location data.

About this task

Attention: Do not remove the system data from a node unless instructed to do so by a service procedure. Do not use this procedure to remove the system data from the only online node canister in a system. If the system data is removed or lost from all node canisters in the system, the system is effectively deleted. Attempting a system recovery procedure to restore a deleted system is not guaranteed to recover all of your volumes.

Procedure

1. Log into the service assistant of the node canister.
2. Use the service assistant node action to hold the node in service state.
3. Use the **Manage System** option to remove the system data from the node.

Results

The node canister restarts in service state.

What to do next

When you want the node canister to be active again, use the service assistant to leave service state. The node canister moves to candidate state, and can be added to the system. If the partner node canister is already active, the candidate node is added automatically.

Procedure: Deleting a system completely

This procedure guides you through the process of completely removing all system information. When the procedure is finished, the system performs like a new installation.

About this task

Attention: This procedure makes all the volume data that you have on your system inaccessible. You cannot recover the data. This procedure affects all volumes that are managed by your system.

Do not continue unless you are certain that you want to remove all the volume data and configuration data from your system. This procedure is not used as part of any recovery action.

There are two stages to this procedure. First, the node canisters are reset. Second, the enclosure data is reset.

Procedure

1. Start the service assistant on one of the node canisters.
2. Use the service assistant node action to hold the node in service state.
3. Use the **Manage System** option to remove the system data from the node.
4. Repeat steps 1 through 3 on the second node canister in the enclosure.
5. On one node, open the service assistant **Configure Enclosure** and select the **Reset System ID** option. This action causes the system to reset.

Procedure: Fixing node errors

To fix node errors that are detected by node canisters in your system, use this procedure.

About this task

Node errors are reported in the service assistant when a node detects erroneous conditions in a node canister.

Procedure

1. Carry out “Procedure: Getting node canister and system information using the service assistant” on page 198 to understand the state of each node.
2. If possible, log into the management GUI and use the monitoring page to run the recommended fix procedure.
 - a. Follow the fix procedure instructions to completion.
 - b. Repeat this step for each subsequent recommended fix procedure.
3. If it is not possible to access the management GUI, or no recommended actions are listed, refer to Reference > Messages and codes > Event IDs Error event IDs and error codes from the Information Center and follow the identified user response for each reported node error.

Procedure: Changing the service IP address of a node canister

This procedure identifies many methods that you can use to change the service IP address of a node canister.

About this task

When you change an IPv4 address, you change the IP address, the subnet, mask, and gateway. When you change an IPv6 address, you change the IP address, prefix, and gateway.

Which method to use depends on the status of the system and the other node canisters in the system. Follow the methods in the order shown until you are successful in setting the IP address to the required value.

You can set an IPv4 address, an IPv6 address, or both, as the service address of a node. Enter the required address correctly. If you set the address to 0.0.0.0 or 0000:0000:0000:0000:0000:0000:0000:0000, you disable the access to the port on that protocol.

Procedure

Change the service IP address.

- Use the control enclosure management GUI when the system is operating and the system is able to connect to the node with the service IP address that you want to change.
 1. Select **Settings > Network** from the navigation.
 2. Select **Service IP Addresses**.
 3. Complete the panel. Be sure to select the correct node to configure.

- Use the service assistant when you can connect to the service assistant on either the node canister that you want to configure or on a node canister that can connect to the node canister that you want to configure:
 1. Make the node canister that you want to configure the current node.
 2. Select **Change Service IP** from the menu.
 3. Complete the panel.
- Use one of the following procedures if you cannot connect to the node canister from another node:
 - Use the initialization tool to write the correct command file to the USB flash drive. Go to “Using the initialization tool” on page 171.
 - Use a text editor to create the command file on the USB flash drive. Go to “Using a USB flash drive” on page 170.

Procedure: Accessing a canister using a directly attached Ethernet cable

If you need to use a direct Ethernet connection to attach a personal computer to a node canister to run the service assistant or to use the service CLI, use this procedure.

About this task

Perform this procedure if you are not authorized to use a USB flash drive in your data center and when the service address of your nodes cannot be accessed over your Ethernet network. This situation might occur for a new installation where the default service IP addresses cannot be accessed on your network.

The default service addresses are listed in “Problem: Cannot connect to the service assistant” on page 193.

Note: Do not attempt to use a directly attached Ethernet cable to a canister that is active in a clustered system. You might disrupt access from host applications or the management GUI. If the node is active, go to **Settings > Network** in the management GUI to set the service IP address to one that is accessible on the network.

Procedure

Complete the following steps to access a canister using a directly attached Ethernet cable.

1. Connect one end of an Ethernet cable to Ethernet port 1 of a node canister in the control enclosure.

Note: A cross-over Ethernet cable is not required.
2. Connect the other end of the Ethernet cable directly to the Ethernet port on a personal computer that has a web browser installed.
3. Get the service IP address of the node canister attached at step 1. If the service IP address is unknown, refer to “Problem: Node canister service IP address unknown” on page 192.
4. Use the operating system tools on the computer to set the IP address and subnet mask of the Ethernet port that is used in step 2. Set them to the same subnet of the node canister service IP address.
5. Point the web browser to the service IP address for the node canister.

6. Log on with the superuser password. The default password is `passwd`.
7. Set the service address of the canister to one that can be accessed on the network as soon as possible.
8. Wait for the action to complete.
9. Disconnect your personal computer.
10. Reconnect the node canister to the Ethernet network.

Procedure: Reseating a node canister

Use this procedure to reseat a canister that is in service state or because a service action has directed you.

About this task

Verify that you are reseating the correct node canister and that you use the correct canister handle for the node that you are reseating. Handles for the node canisters are located next to each other. The handle on the right operates the upper canister. The handle on the left operates the lower canister.

Procedure

1. Verify the clustered-system status LED on the node canister. If it is permanently on, the node is active. If the node is active, no reseating is required.
2. Verify that you have selected the correct node canister and verify why you are reseating it. Go to “Procedure: Identifying which enclosure or canister to service” on page 197.
3. Grasp the handle between the thumb and forefinger.
4. Squeeze them together to release the handle.
5. Pull out the handle to its full extension.
6. Grasp the canister and pull it out 2 or 3 inches.
7. Push the canister back into the slot until the handle starts to move.
8. Finish inserting the canister by closing the handle until the locking catch clicks into place.
9. Verify that the cables were not displaced.
10. Verify that the LEDs are on.

Results

Procedure: Powering off your system

Use this procedure to power off your Storwize V7000 Unified system when it must be serviced or to permit other maintenance actions in your data center. To turn off the Storwize V7000 Unified system, see “Turning off the system” in the Storwize V7000 Unified information center.

About this task

Procedure: Collecting information for support

IBM support might ask you to collect trace files and dump files from your system to help them resolve a problem. Typically, you perform this task from the Storwize V7000 Unified management GUI. You can also collect information from the Storwize V7000 control enclosure itself.

About this task

The control enclosure management GUI and the service assistant have features to assist you in collecting the required information. The management GUI collects information from all the components in the system. The service assistant collects information from a single node canister. When the information that is collected is packaged together in a single file, the file is called a *snap*.

Special tools that are only available to the support teams are required to interpret the contents of the support package. The files are not designed for customer use.

Procedure

Always follow the instructions that are given by the support team to determine whether to collect the package by using the management GUI or the service assistant. Instruction is also given for which package content option is required.

- If you are collecting the package by using the management GUI, select **Settings > Support > Download Logs**. Click **Download Support Package**. Follow the instructions to download either the full logs or the block-storage logs.
- If you are collecting the package by using the service assistant, ensure that the node that you want to collect logs from is the current node. Select the **Collect Logs** option from the navigation. You can collect a support package or copy an individual file from the node canister. Follow the instructions to collect the information.

Procedure: Rescuing node canister software from another node (node rescue)

Use this procedure to perform a node rescue.

About this task

A failure has indicated that the node software is damaged and must be reinstalled.

Procedure

1. Ensure that the node you want to reinstall the code on is the current node. Go to “Accessing the service assistant” on page 168.
2. Select **Reinstall Machine Code** from the navigation.
3. Select **Rescue from another node**.

Results

Replacing parts

You can remove and replace customer-replaceable units (CRUs) in control enclosures or expansion enclosures.

Attention: If your system is powered on and performing I/O operations, go to the management GUI and follow the fix procedures. Performing the replacement actions without the assistance of the fix procedures can result in loss of data or loss of access to data.

Even though many of these components are hot-swappable, they are intended to be used only when your system is not up and running and performing I/O operations. If your system is powered on and performing I/O operations, go to the

management GUI and follow the fix procedures. Performing the replacement actions without the assistance of the fix procedures can result in loss of data or loss of access to data.

Each replaceable unit has its own removal procedure. Sometimes you can find that a step within a procedure might refer you to a different remove and replace procedure. You might want to complete the new procedure before you continue with the first procedure that you started.

Remove or replace parts only when you are directed to do so.

Preparing to remove and replace parts

Before you remove and replace parts, you must be aware of all safety issues.

Before you begin

First, read the safety precautions in the *IBM Systems Safety Notices*. These guidelines help you safely work with the Storwize V7000 Unified.

Replacing a node canister

This topic describes how to replace a node canister.

About this task

Attention: If your system is powered on and performing I/O operations, go to the management GUI and follow the fix procedures. Performing the replacement actions without the assistance of the fix procedures can result in loss of data or loss of access to data.

Be careful when you are replacing the hardware components that are located in the back of the system that you do not inadvertently disturb or remove any cables that you are not instructed to remove.

Attention: Do not replace one type of node canister with another type. For example, do not replace a model 2076-112 node canister with a model 2076-312 node canister.

Be aware of the following canister LED states:

- If both the power LED and system status LED are on, do not remove a node canister unless directed to do so by a service procedure.
- If the system status is off, it is acceptable to remove a node canister. However, do not remove a node canister unless directed to do so by a service procedure.
- If the power LED is flashing or off, it is safe to remove a node canister. However, do not remove a node canister unless directed to do so by a service procedure.

Attention: Even if a node canister is powered off, it is still possible to lose data. Do not remove a node canister unless directed to do so by a service procedure.

To replace the node canister, perform the following steps:

Procedure

1. Read the safety information to which “Preparing to remove and replace parts” refers.

2. Confirm that you know which canister to replace. Go to “Procedure: Identifying which enclosure or canister to service” on page 197.
3. Record which data cables are plugged into the specific ports of the node canister. The cables must be inserted back into the same ports after the replacement is complete; otherwise, the system cannot function properly.
4. Disconnect the data cables for each canister.
5. Grasp the handle between the thumb and forefinger.

Note: Ensure that you are opening the correct handle. The handle locations for the node canisters and expansion canisters are slightly different.

Handles for the node canisters are located in close proximity to each other. The handle with the finger grip on the right removes the upper canister (**1**). The handle with the finger grip on the left removes the lower canister (**2**).

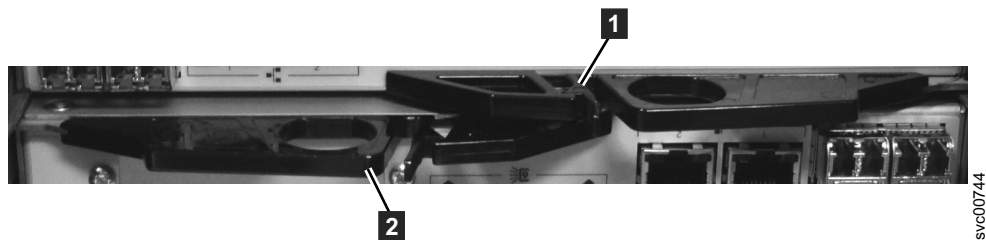


Figure 37. Rear of node canisters that shows the handles.

6. Squeeze them together to release the handle.

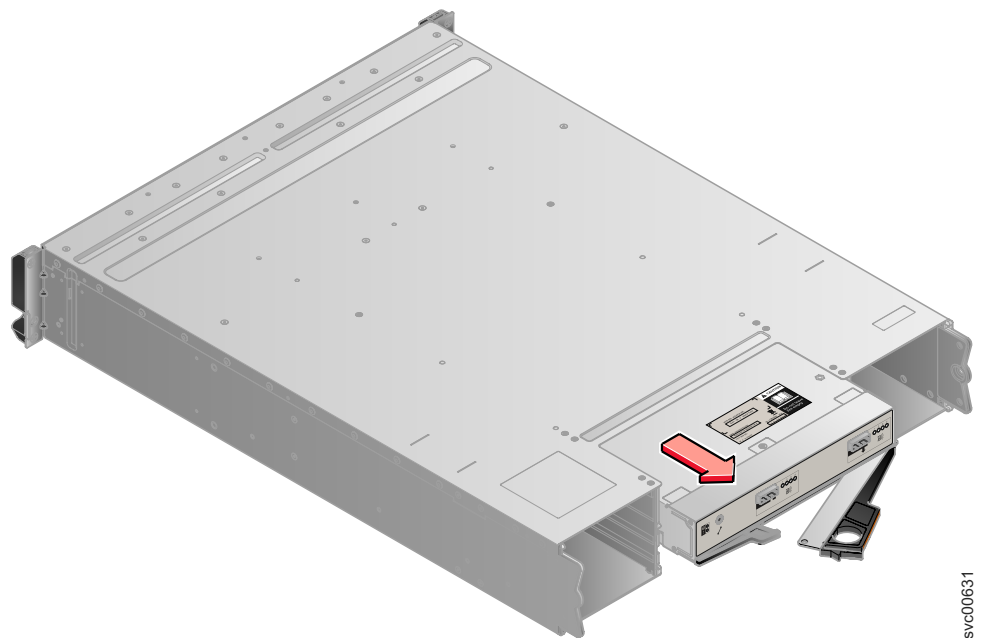


Figure 38. Removing the canister from the enclosure

7. Pull out the handle to its full extension.
8. Grasp canister and pull it out.
9. Insert the new canister into the slot with the handle pointing towards the center of the slot. Insert the unit in the same orientation as the one that you removed.

10. Push the canister back into the slot until the handle starts to move.
11. Finish inserting the canister by closing the handle until the locking catch clicks into place. Make sure that the canister is firmly and correctly seated, otherwise this can lead to problems.
If the enclosure is powered on, the canister starts automatically.
12. Reattach the data cables.

Replacing an expansion canister

This topic describes how to replace an expansion canister.

About this task

Attention: If your system is powered on and performing I/O operations, go to the management GUI and follow the fix procedures. Performing the replacement actions without the assistance of the fix procedures can result in loss of data or loss of access to data.

Even though many of these components are hot-swappable, they are intended to be used only when your system is not up and running and performing I/O operations. If your system is powered on and performing I/O operations, go to the management GUI and follow the fix procedures. Performing the replacement actions without the assistance of the fix procedures can result in loss of data or loss of access to data.

Be careful when you are replacing the hardware components that are located in the back of the system that you do not inadvertently disturb or remove any cables that you are not instructed to remove.

Be aware of the following canister LED states:

- If the power LED is on, do not remove an expansion canister unless directed to do so by a service procedure.
- If the power LED is flashing or off, it is safe to remove an expansion canister. However, do not remove an expansion canister unless directed to do so by a service procedure.

Attention: Even if an expansion canister is powered off, it is still possible to lose data. Do not remove an expansion canister unless directed to do so by a service procedure.

To replace an expansion canister, perform the following steps:

Procedure

1. Read the safety information to which “Preparing to remove and replace parts” on page 210 refers.
2. Record which SAS cables are plugged into the specific ports of the expansion canister. The cables must be inserted back into the same ports after the replacement is complete; otherwise, the system cannot function properly.
3. Disconnect the SAS cables for each canister.
4. Grasp the handle between the thumb and forefinger.

Note: Ensure that you are opening the correct handle. The handle locations for the node canisters and expansion canisters are slightly different.

Handles for the upper and lower expansion canisters overlap each other. The handle with the finger grip on the left removes the upper canister (**1**). The handle with the finger grip on the right removes the lower canister (**2**).

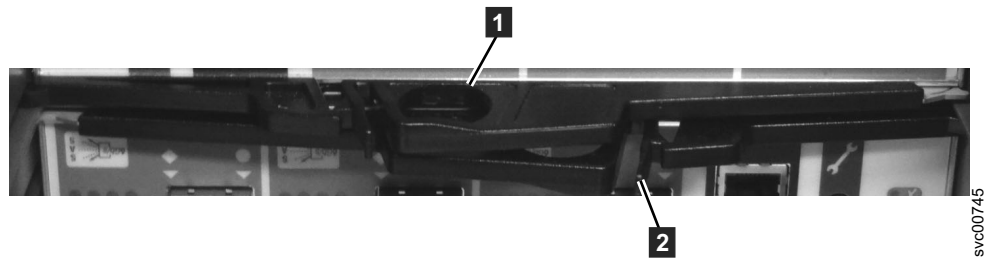


Figure 39. Rear of expansion canisters that shows the handles.

5. Squeeze them together to release the handle.

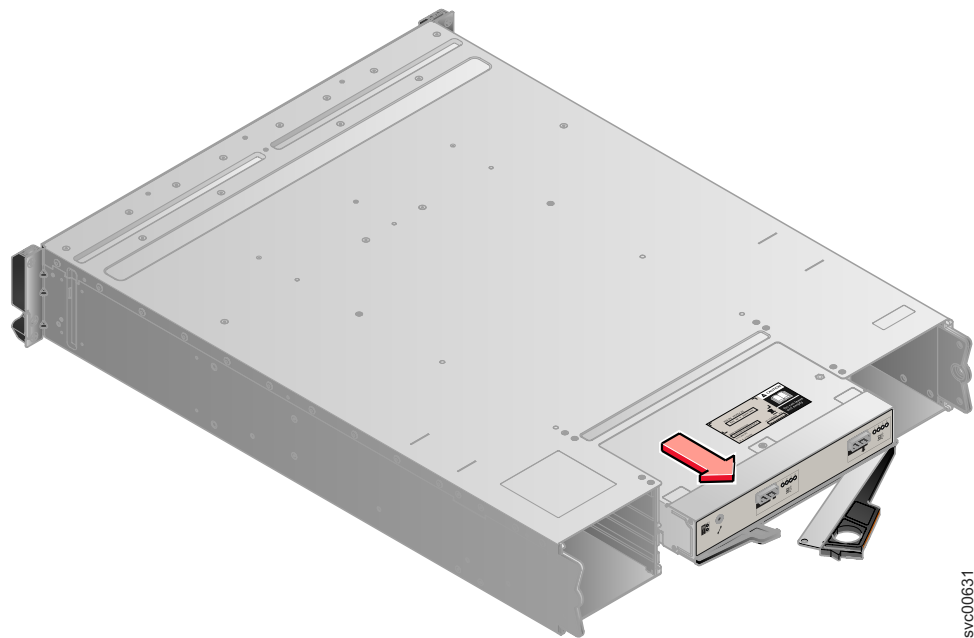


Figure 40. Removing the canister from the enclosure

6. Pull out the handle to its full extension.
7. Grasp canister and pull it out.
8. Insert the new canister into the slot with the handle pointing towards the center of the slot. Insert the unit in the same orientation as the one that you removed.
9. Push the canister back into the slot until the handle starts to move.
10. Finish inserting the canister by closing the handle until the locking catch clicks into place. Make sure that the canister is firmly and correctly seated, otherwise this can lead to problems.
11. Reattach the SAS cables.

Replacing an SFP transceiver

When a failure occurs on a single link, the SFP transceiver might need to be replaced.

Before you begin

Even though many of these components are hot-swappable, they are intended to be used only when your system is not up and running and performing I/O operations. If your system is powered on and performing I/O operations, go to the management GUI and follow the fix procedures. Performing the replacement actions without the assistance of the fix procedures can result in loss of data or loss of access to data.

Be careful when you are replacing the hardware components that are located in the back of the system that you do not inadvertently disturb or remove any cables that you are not instructed to remove.

CAUTION:

Some laser products contain an embedded Class 3A or Class 3B laser diode. Note the following information: laser radiation when open. Do not stare into the beam, do not view directly with optical instruments, and avoid direct exposure to the beam. (C030)

About this task

Perform the following steps to remove and then replace an SFP transceiver:

Procedure

1. Carefully determine the failing physical port connection.

Important: The Fibre Channel links in the enclosures are supported with both longwave SFP transceivers and shortwave SFP transceivers. A longwave SFP transceiver has some blue components that are visible even when the SFP transceiver is plugged in. You must replace an SFP transceiver with the same type of SFP transceiver that you are replacing. If the SFP transceiver to replace is a longwave SFP transceiver, for example, you must replace with another longwave SFP transceiver. Removing the wrong SFP transceiver might result in loss of data access.

2. Remove the optical cable by pressing the release tab and pulling the cable out. Be careful to exert pressure only on the connector and do not pull on the optical cables.
3. Remove the SFP transceiver. There are a number of different handling or locking mechanisms that are used on the SFP transceivers. Some SFP transceivers might have a plastic tag. If so, pull the tag to remove the SFP transceiver.

Important: Always check that the SFP transceiver that you replace matches the SFP transceiver that you remove.

4. Push the new SFP transceiver into the aperture and ensure that it is securely pushed home. The SFP transceiver usually locks into place without having to swing the release handle until it locks flush with the SFP transceiver. Figure 41 on page 215 illustrates an SFP transceiver and its release handle.



svc00418

Figure 41. SFP transceiver

5. Reconnect the optical cable.
6. Confirm that the error is now fixed. Either mark the error as fixed or restart the node depending on the failure indication that you originally noted.

Replacing a power supply unit for a control enclosure

You can replace either of the two 764 watt hot-swap redundant power supplies in the control enclosure. These redundant power supplies operate in parallel, one continuing to power the canister if the other fails.

Before you begin

DANGER

When working on or around the system, observe the following precautions:

Electrical voltage and current from power, telephone, and communication cables are hazardous. To avoid a shock hazard:

- If IBM supplied a power cord(s), connect power to this unit only with the IBM provided power cord. Do not use the IBM provided power cord for any other product.
- Do not open or service any power supply assembly.
- Do not connect or disconnect any cables or perform installation, maintenance, or reconfiguration of this product during an electrical storm.
- The product might be equipped with multiple power cords. To remove all hazardous voltages, disconnect all power cords.
- Connect all power cords to a properly wired and grounded electrical outlet. Ensure that the outlet supplies proper voltage and phase rotation according to the system rating plate.
- Connect any equipment that will be attached to this product to properly wired outlets.
- When possible, use one hand only to connect or disconnect signal cables.
- Never turn on any equipment when there is evidence of fire, water, or structural damage.
- Disconnect the attached power cords, telecommunications systems, networks, and modems before you open the device covers, unless instructed otherwise in the installation and configuration procedures.
- Connect and disconnect cables as described in the following procedures when installing, moving, or opening covers on this product or attached devices.

To disconnect:

1. Turn off everything (unless instructed otherwise).
2. Remove the power cords from the outlets.
3. Remove the signal cables from the connectors.
4. Remove all cables from the devices.

To connect:

1. Turn off everything (unless instructed otherwise).
 2. Attach all cables to the devices.
 3. Attach the signal cables to the connectors.
 4. Attach the power cords to the outlets.
 5. Turn on the devices.
- Sharp edges, corners and joints may be present in and around the system. Use care when handling equipment to avoid cuts, scrapes and pinching. (D005)

Attention: If your system is powered on and performing I/O operations, go to the management GUI and follow the fix procedures. Performing the replacement actions without the assistance of the fix procedures can result in loss of data or loss of access to data.

Attention: A powered-on enclosure must not have a power supply removed for more than five minutes because the cooling does not function correctly with an empty slot. Ensure that you have read and understood all these instructions and have the replacement available, and unpacked, before you remove the existing power supply.

Even though many of these components are hot-swappable, they are intended to be used only when your system is not up and running and performing I/O operations. If your system is powered on and performing I/O operations, go to the management GUI and follow the fix procedures. Performing the replacement actions without the assistance of the fix procedures can result in loss of data or loss of access to data.

Be careful when you are replacing the hardware components that are located in the back of the system that you do not inadvertently disturb or remove any cables that you are not instructed to remove.

Attention: In some instances, it might not be advisable to remove a power supply unit when a system is performing I/O. For example, the charge in the backup battery might not be sufficient enough within the partner power-supply unit to continue operations without causing a loss of access to the data. Wait until the partner battery is 100% charged before replacing the power supply unit.

Ensure that you are aware of the procedures for handling static-sensitive devices before you replace the power supply.

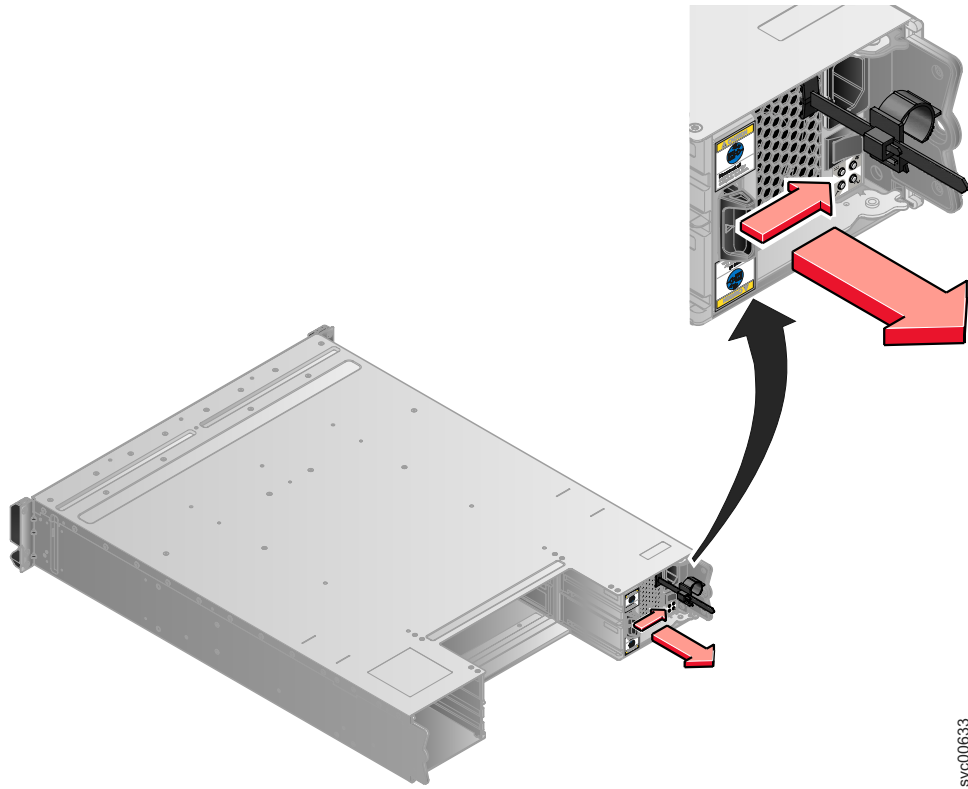
About this task

A replacement power supply unit is not shipped with a battery; therefore, transfer the battery from the existing power supply unit to the replacement unit. To transfer a battery, go to “Replacing a battery in a power supply unit” on page 223.

To replace the power supply, perform the following steps:

Procedure

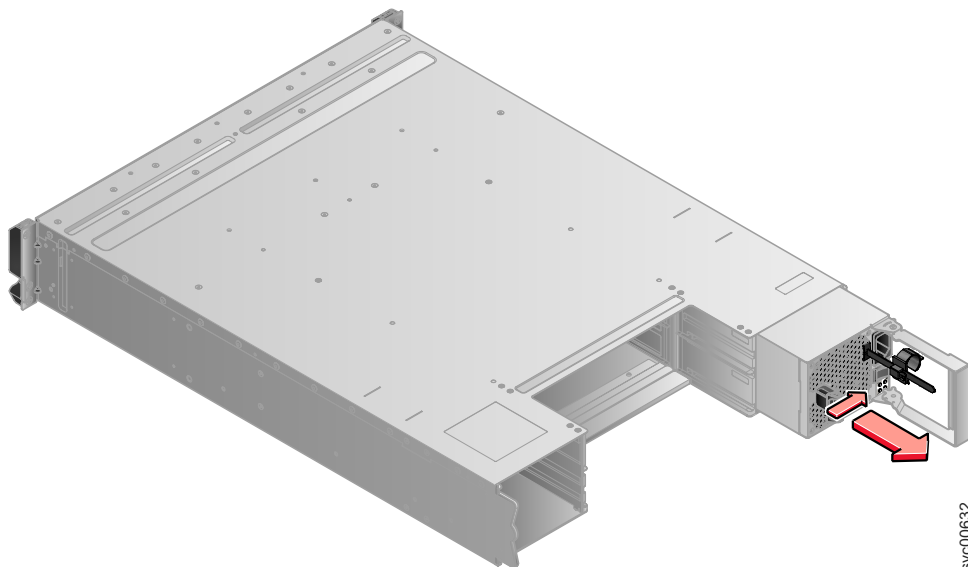
1. Read the safety information to which “Preparing to remove and replace parts” on page 210 refers.
2. Examine the Identify LED that is lit on the front of the enclosure to identify the correct enclosure.
3. Turn off the power to the power supply units using the switches at the back of the units.
4. Disconnect the cable retention bracket and the power cord from the power supply that you are replacing.
5. Remove the power supply unit. Record the orientation of the power supply unit. Power supply unit 1 is top side up, and power supply unit 2 is inverted.
 - a. Depress the black locking catch from the side with the colored sticker as shown in Figure 42 on page 218.



svc00633

Figure 42. Directions for lifting the handle on the power supply unit

- b. Grip the handle to pull the power supply out of the enclosure as shown in Figure 43.



svc00632

Figure 43. Using the handle to remove a power supply unit

6. Insert the replacement power supply unit into the enclosure with the handle pointing towards the center of the enclosure. Insert the unit in the same orientation as the one that you removed.

7. Push the power supply unit back into the enclosure until the handle starts to move.
8. Finish inserting the power supply unit into the enclosure by closing the handle until the locking catch clicks into place.
9. Reattach the power cable and cable retention bracket.
10. Turn on the power switch to the power supply unit.

What to do next

If required, return the power supply. Follow all packaging instructions, and use any packaging materials for shipping that are supplied to you.

Replacing a power supply unit for an expansion enclosure

You can replace either of the two 580 watt hot-swap redundant power supplies in the expansion enclosure. These redundant power supplies operate in parallel, one continuing to power the canister if the other fails.

Before you begin

DANGER

When working on or around the system, observe the following precautions:

Electrical voltage and current from power, telephone, and communication cables are hazardous. To avoid a shock hazard:

- If IBM supplied a power cord(s), connect power to this unit only with the IBM provided power cord. Do not use the IBM provided power cord for any other product.
- Do not open or service any power supply assembly.
- Do not connect or disconnect any cables or perform installation, maintenance, or reconfiguration of this product during an electrical storm.
- The product might be equipped with multiple power cords. To remove all hazardous voltages, disconnect all power cords.
- Connect all power cords to a properly wired and grounded electrical outlet. Ensure that the outlet supplies proper voltage and phase rotation according to the system rating plate.
- Connect any equipment that will be attached to this product to properly wired outlets.
- When possible, use one hand only to connect or disconnect signal cables.
- Never turn on any equipment when there is evidence of fire, water, or structural damage.
- Disconnect the attached power cords, telecommunications systems, networks, and modems before you open the device covers, unless instructed otherwise in the installation and configuration procedures.
- Connect and disconnect cables as described in the following procedures when installing, moving, or opening covers on this product or attached devices.

To disconnect:

1. Turn off everything (unless instructed otherwise).
2. Remove the power cords from the outlets.
3. Remove the signal cables from the connectors.
4. Remove all cables from the devices.

To connect:

1. Turn off everything (unless instructed otherwise).
 2. Attach all cables to the devices.
 3. Attach the signal cables to the connectors.
 4. Attach the power cords to the outlets.
 5. Turn on the devices.
- Sharp edges, corners and joints may be present in and around the system. Use care when handling equipment to avoid cuts, scrapes and pinching. (D005)

Attention: If your system is powered on and performing I/O operations, go to the management GUI and follow the fix procedures. Performing the replacement actions without the assistance of the fix procedures can result in loss of data or loss of access to data.

Attention: A powered-on enclosure must not have a power supply removed for more than five minutes because the cooling does not function correctly with an empty slot. Ensure that you have read and understood all these instructions and have the replacement available, and unpacked, before you remove the existing power supply.

Even though many of these components are hot-swappable, they are intended to be used only when your system is not up and running and performing I/O operations. If your system is powered on and performing I/O operations, go to the management GUI and follow the fix procedures. Performing the replacement actions without the assistance of the fix procedures can result in loss of data or loss of access to data.

Be careful when you are replacing the hardware components that are located in the back of the system that you do not inadvertently disturb or remove any cables that you are not instructed to remove.

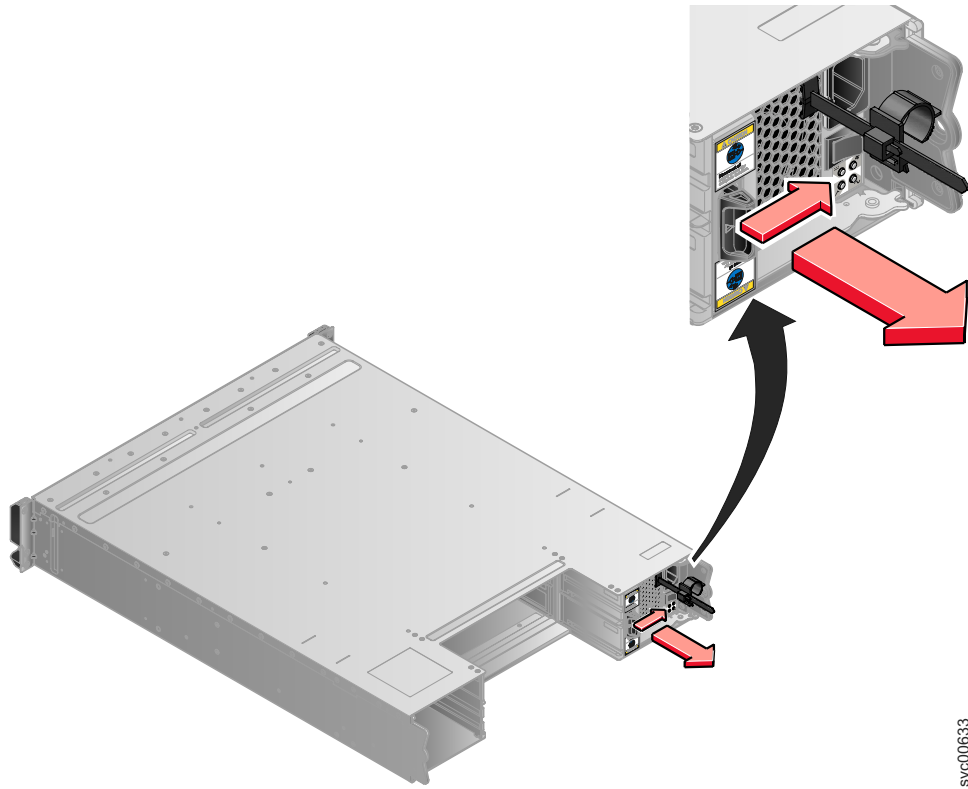
Ensure that you are aware of the procedures for handling static-sensitive devices before you replace the power supply.

About this task

To replace the power supply unit in an expansion enclosure, perform the following steps:

Procedure

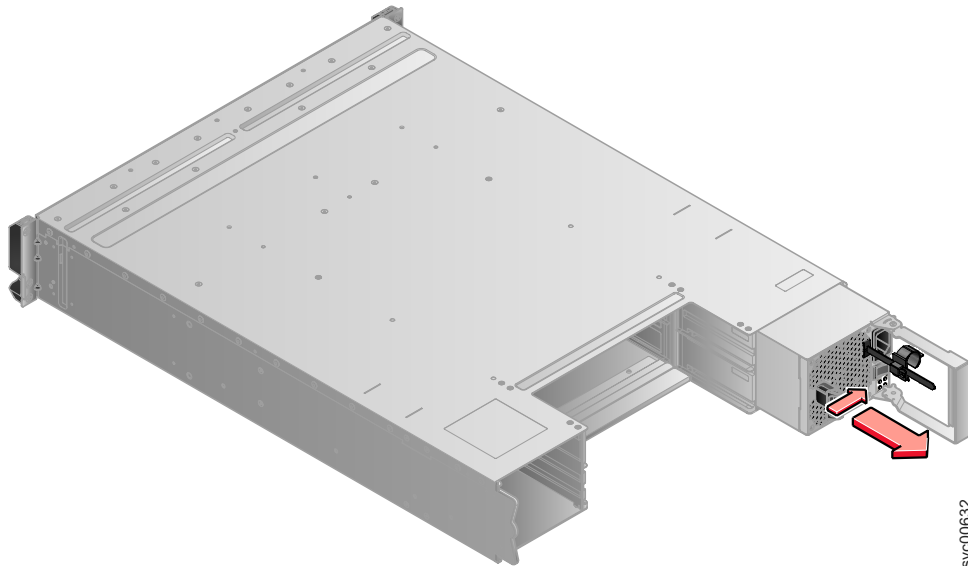
1. Read the safety information to which “Preparing to remove and replace parts” on page 210 refers.
2. Examine the Identify LED that is lit on the front of the enclosure to identify the correct enclosure.
3. Turn off the power to the power supply unit using the switch at the back of the unit.
4. Disconnect the cable retention bracket and the power cord from the power supply that you are replacing.
5. Remove the power supply unit. Record the orientation of the power supply unit. Power supply unit 1 is top side up, and power supply unit 2 is inverted.
 - a. Depress the black locking catch from the side with the colored sticker as shown in Figure 44 on page 222.



svc00633

Figure 44. Directions for lifting the handle on the power supply unit

- b. Grip the handle to pull the power supply out of the enclosure as shown in Figure 45.



svc00632

Figure 45. Using the handle to remove a power supply unit

6. Insert the replacement power supply unit into the enclosure with the handle pointing towards the center of the enclosure. Insert the unit in the same orientation as the one that you removed.

7. Push the power supply unit back into the enclosure until the handle starts to move.
8. Finish inserting the power supply unit in the enclosure by closing the handle until the locking catch clicks into place.
9. Reattach the power cable and cable retention bracket.
10. Turn on the power switch to the power supply unit.

What to do next

If required, return the power supply. Follow all packaging instructions, and use any packaging materials for shipping that are supplied to you.

Replacing a battery in a power supply unit

This topic describes how to replace the battery in the control enclosure power-supply unit.

Before you begin

DANGER

When working on or around the system, observe the following precautions:

Electrical voltage and current from power, telephone, and communication cables are hazardous. To avoid a shock hazard:

- If IBM supplied a power cord(s), connect power to this unit only with the IBM provided power cord. Do not use the IBM provided power cord for any other product.
- Do not open or service any power supply assembly.
- Do not connect or disconnect any cables or perform installation, maintenance, or reconfiguration of this product during an electrical storm.
- The product might be equipped with multiple power cords. To remove all hazardous voltages, disconnect all power cords.
- Connect all power cords to a properly wired and grounded electrical outlet. Ensure that the outlet supplies proper voltage and phase rotation according to the system rating plate.
- Connect any equipment that will be attached to this product to properly wired outlets.
- When possible, use one hand only to connect or disconnect signal cables.
- Never turn on any equipment when there is evidence of fire, water, or structural damage.
- Disconnect the attached power cords, telecommunications systems, networks, and modems before you open the device covers, unless instructed otherwise in the installation and configuration procedures.
- Connect and disconnect cables as described in the following procedures when installing, moving, or opening covers on this product or attached devices.

To disconnect:

1. Turn off everything (unless instructed otherwise).
2. Remove the power cords from the outlets.
3. Remove the signal cables from the connectors.
4. Remove all cables from the devices.

To connect:

1. Turn off everything (unless instructed otherwise).
 2. Attach all cables to the devices.
 3. Attach the signal cables to the connectors.
 4. Attach the power cords to the outlets.
 5. Turn on the devices.
- Sharp edges, corners and joints may be present in and around the system. Use care when handling equipment to avoid cuts, scrapes and pinching. (D005)

CAUTION:

The battery is a lithium ion battery. To avoid possible explosion, do not burn. (C007)

Attention: If your system is powered on and performing I/O operations, go to the management GUI and follow the fix procedures. Performing the replacement actions without the assistance of the fix procedures can result in loss of data or loss of access to data.

Even though many of these components are hot-swappable, they are intended to be used only when your system is not up and running and performing I/O operations. If your system is powered on and performing I/O operations, go to the management GUI and follow the fix procedures. Performing the replacement actions without the assistance of the fix procedures can result in loss of data or loss of access to data.

Be careful when you are replacing the hardware components that are located in the back of the system that you do not inadvertently disturb or remove any cables that you are not instructed to remove.

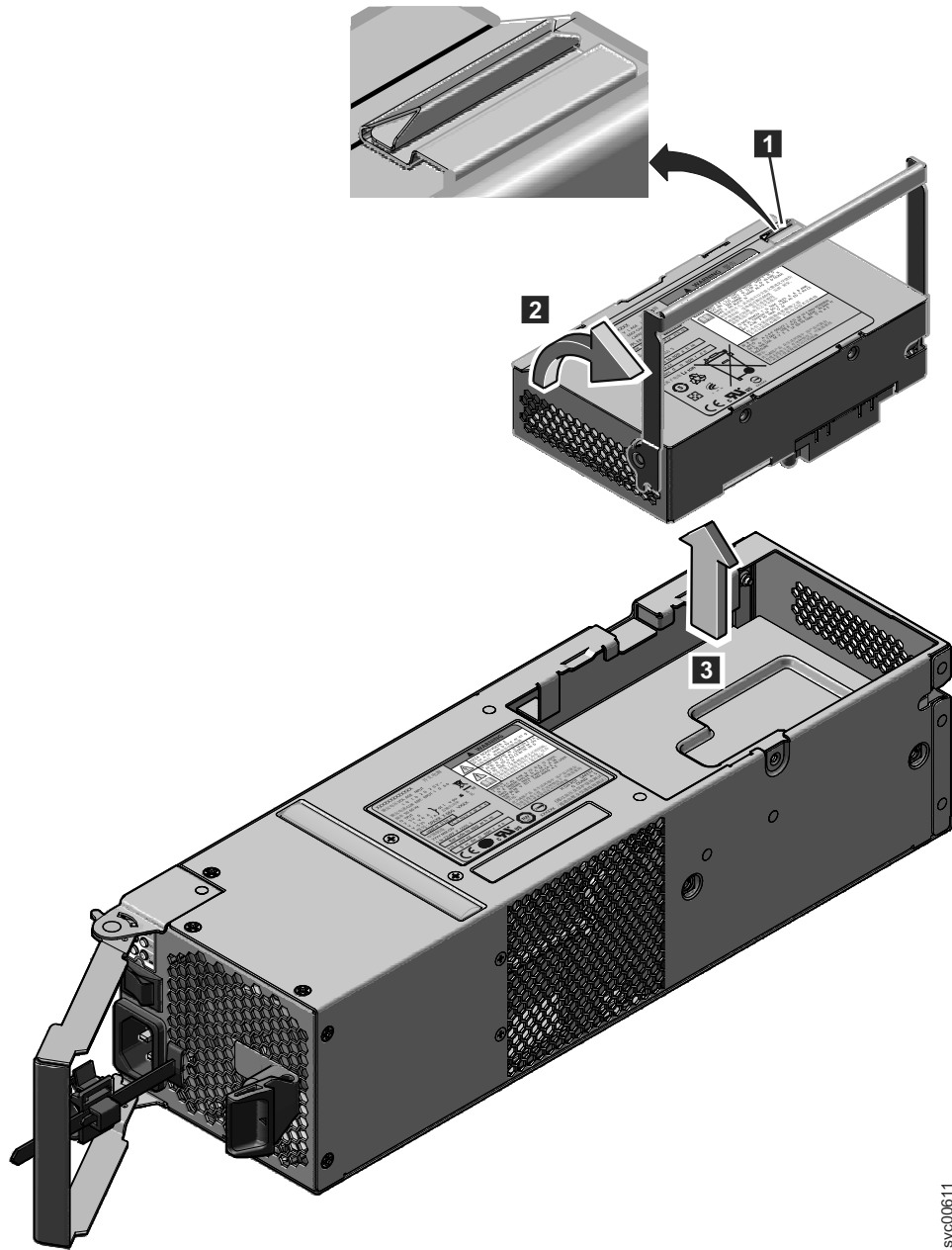
About this task

Each power supply unit in a control enclosure contains an integrated battery that is used during temporary short-term power outages. You must replace the battery with the exact same model.

To replace the battery in the power supply unit of the control enclosure, perform the following steps:

Procedure

1. Read the safety information to which “Preparing to remove and replace parts” on page 210 refers.
2. Follow the removing steps of the replacing a power-supply unit procedure. Go to “Replacing a power supply unit for a control enclosure” on page 215.
3. Remove the battery, as shown in Figure 46 on page 226.



svc00611

Figure 46. Removing the battery from the control enclosure power-supply unit

- a. Press the catch to release the handle **1**.
- b. Lift the handle on the battery **2**.
- c. Lift the battery out of the power supply unit **3**.
4. Install the replacement battery.

Attention: The replacement battery has protective end caps that must be removed prior to use.

 - a. Remove the battery from the packaging.
 - b. Remove the end caps.
 - c. Attach the end caps to both ends of the battery that you removed and place the battery in the original packaging.

- d. Place the replacement battery in the opening on top of the power supply in its proper orientation.
 - e. Press the battery to seat the connector.
 - f. Place the handle in its downward location
5. Push the power supply unit back into the enclosure until the handle starts to move.
 6. Finish inserting the power supply unit into the enclosure by closing the handle until the locking catch clicks into place.
 7. Reattach the power cable and cable retention bracket.
 8. Turn on the power switch to the power supply unit.

What to do next

If required, return the battery. Follow all packaging instructions, and use any packaging materials for shipping that are supplied to you.

Releasing the cable retention bracket

This topic provides instructions for releasing the cable retention bracket when removing the power cords from the power supply unit.

About this task

Be careful when you are replacing the hardware components that are located in the back of the system that you do not inadvertently disturb or remove any cables that you are not instructed to remove.

Each cable retention bracket comes attached to the back of the power supply unit by the power cord plug-in.

To release a cable retention bracket, perform these steps:

Procedure

1. Unlock the cable retention bracket that is around the end of the power cord.
2. Pull the lever next to the black plastic loop slightly towards the center of the canister.
3. Continue to pull the lever towards you as you slide the cable retention bracket away from the end of the cable.

Replacing a 3.5" drive assembly or blank carrier

This topic describes how to replace a 3.5" drive assembly or blank carrier.

About this task

Attention: If your drive is configured for use, go to the management GUI and follow the fix procedures. Performing the replacement actions without the assistance of the fix procedures results in loss of data or loss of access to data.

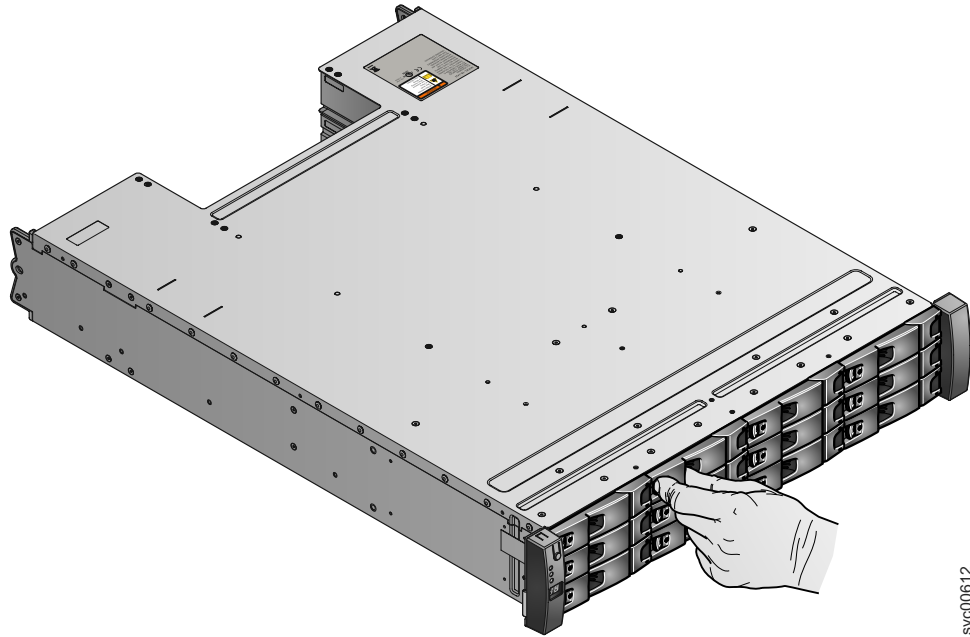
Attention: Do not leave a drive slot empty. Do not remove a drive or drive assembly before you have a replacement available.

The drives can be distinguished from the blank carriers by the color-coded striping on the drive. The drives are marked with an orange striping. The blank carriers are marked with a blue striping.

To replace the drive assembly or blank carrier, perform the following steps:

Procedure

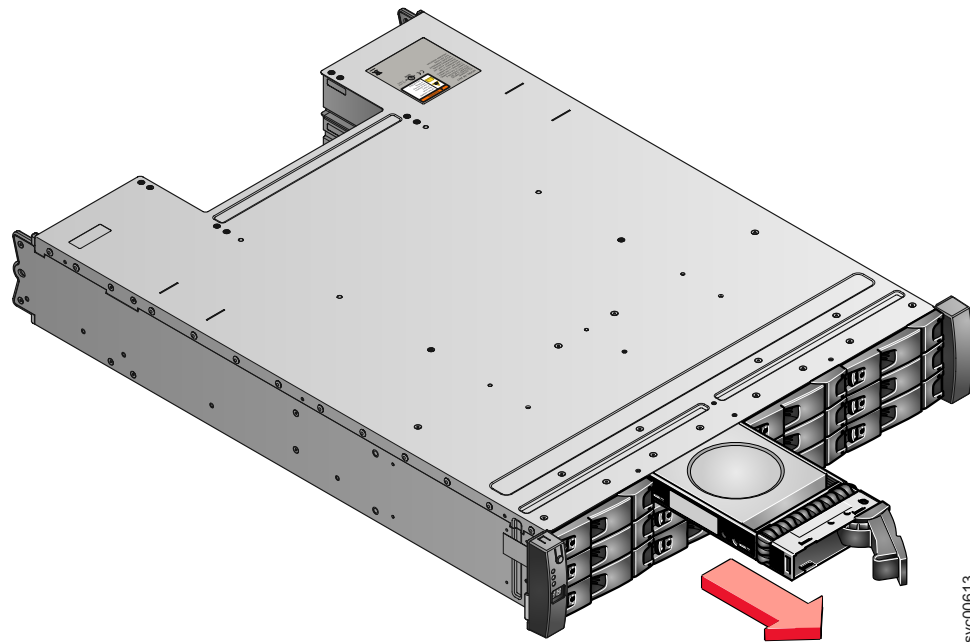
1. Read the safety information to which “Preparing to remove and replace parts” on page 210 refers.
2. Unlock the assembly by squeezing together the tabs on the side.



svc00612

Figure 47. Unlocking the 3.5" drive

3. Open the handle to the full extension.



svc00613

Figure 48. Removing the 3.5" drive

4. Pull out the drive.
5. Push the new drive back into the slot until the handle starts to move.
6. Finish inserting the drive by closing the handle until the locking catch clicks into place.

Replacing a 2.5" drive assembly or blank carrier

This topic describes how to remove a 2.5" drive assembly or blank carrier.

About this task

Attention: If your drive is configured for use, go to the management GUI and follow the fix procedures. Performing the replacement actions without the assistance of the fix procedures results in loss of data or loss of access to data.

Attention: Do not leave a drive slot empty. Do not remove a drive or drive assembly before you have a replacement available.

To replace the drive assembly or blank carrier, perform the following steps:

Procedure

1. Read the safety information to which "Preparing to remove and replace parts" on page 210 refers.
2. Unlock the module by squeezing together the tabs at the top.

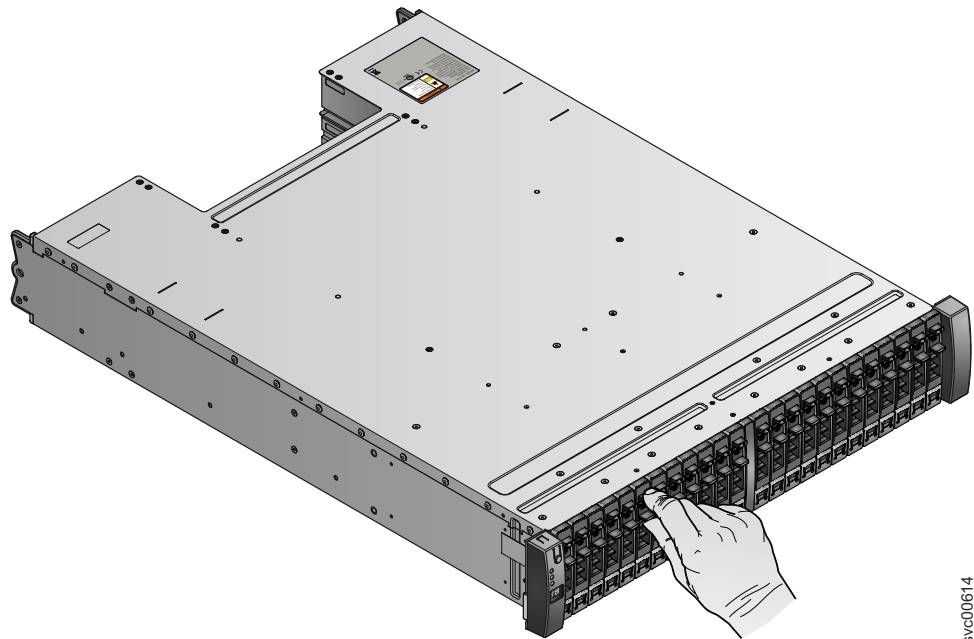
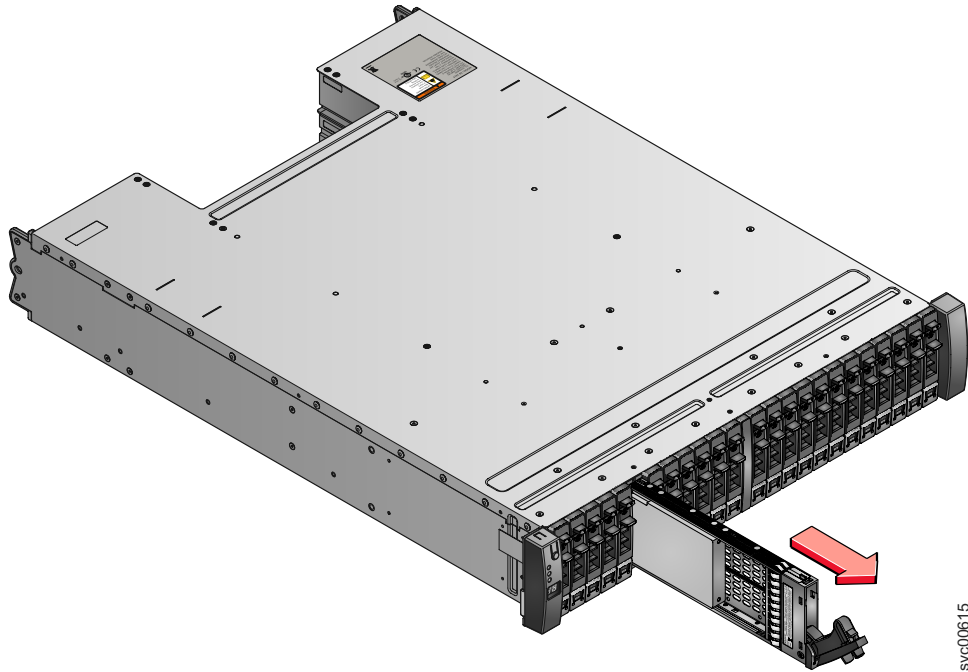


Figure 49. Unlocking the 2.5" drive

3. Open the handle to the full extension.



svc00615

Figure 50. Removing the 2.5" drive

4. Pull out the drive.
5. Push the new drive back into the slot until the handle starts to move.
6. Finish inserting the drive by closing the handle until the locking catch clicks into place.

Replacing enclosure end caps

To replace enclosure end caps, use this procedure.

About this task

Attention: The left end cap is printed with information that helps identify the enclosure.

- machine type and model
- enclosure serial number
- its machine part number

The information on the end cap should always match the information printed on the rear of the enclosure, and it should also match the information that is stored on the enclosure midplane.

Procedure

To remove and replace either the left or right end cap, complete the following steps.

1. If the enclosure is on a table or other flat surface, elevate the enclosure front slightly or carefully extend the front over the table edge.
2. Grasp the end cap by the blue touch point and pull it until the bottom edge of the end cap is clear of the bottom tab on the chassis flange.
3. Lift the end cap off the chassis flange.

4. Fit the slot on the top of the new end cap over the tab on the top of the chassis flange.
5. Rotate the end cap down until it snaps into place. Make sure that the inside surface of the end cap is flush with the chassis.

Replacing a SAS cable

This topic describes how to replace a SAS cable.

About this task

Be careful when you are replacing the hardware components that are located in the back of the system that you do not inadvertently disturb or remove any cables that you are not instructed to remove.

To replace a SAS cable, perform the following steps:

Procedure

1. Record which SAS cable is plugged into the specific port of the expansion canister. The cable must be inserted back into the same port after the replacement is complete; otherwise, the system cannot function properly.

Note: If you are replacing a single cable, this step is not necessary.

2. Pull the tab with the arrow away from the connector.



Figure 51. SAS cable

3. Plug the replacement cable into the specific port.
4. Ensure that the SAS cable is fully inserted. A click is heard when the cable is successfully inserted.

Replacing a control enclosure chassis

This topic describes how to replace a control enclosure chassis.

Before you begin

Note: Ensure that you know the type of enclosure chassis that you are replacing. The procedures for replacing a control enclosure chassis are different from those procedures for replacing an expansion enclosure chassis. For information about replacing an expansion enclosure chassis, see “Replacing an expansion enclosure chassis” on page 237.

DANGER

When working on or around the system, observe the following precautions:

Electrical voltage and current from power, telephone, and communication cables are hazardous. To avoid a shock hazard:

- If IBM supplied a power cord(s), connect power to this unit only with the IBM provided power cord. Do not use the IBM provided power cord for any other product.
- Do not open or service any power supply assembly.
- Do not connect or disconnect any cables or perform installation, maintenance, or reconfiguration of this product during an electrical storm.
- The product might be equipped with multiple power cords. To remove all hazardous voltages, disconnect all power cords.
- Connect all power cords to a properly wired and grounded electrical outlet. Ensure that the outlet supplies proper voltage and phase rotation according to the system rating plate.
- Connect any equipment that will be attached to this product to properly wired outlets.
- When possible, use one hand only to connect or disconnect signal cables.
- Never turn on any equipment when there is evidence of fire, water, or structural damage.
- Disconnect the attached power cords, telecommunications systems, networks, and modems before you open the device covers, unless instructed otherwise in the installation and configuration procedures.
- Connect and disconnect cables as described in the following procedures when installing, moving, or opening covers on this product or attached devices.

To disconnect:

1. Turn off everything (unless instructed otherwise).
2. Remove the power cords from the outlets.
3. Remove the signal cables from the connectors.
4. Remove all cables from the devices.

To connect:

1. Turn off everything (unless instructed otherwise).
 2. Attach all cables to the devices.
 3. Attach the signal cables to the connectors.
 4. Attach the power cords to the outlets.
 5. Turn on the devices.
- Sharp edges, corners and joints may be present in and around the system. Use care when handling equipment to avoid cuts, scrapes and pinching. (D005)

Attention: Perform this procedure only if instructed to do so by a service action or the IBM support center. If you have a single control enclosure, this procedure requires that you shut down your system to replace the control enclosure. If you have more than one control enclosure, you can keep part of the system running, but you lose access to the volumes that are on the affected I/O group and any volumes that are in other I/O groups that depend on the drives that are in the affected I/O group. If the system is still performing I/O requests in all the I/O groups, schedule the replacement during a maintenance period or other time when the I/O can be stopped.

Be careful when you are replacing the hardware components that are located in the back of the system that you do not inadvertently disturb or remove any cables that you are not instructed to remove.

Ensure that you are aware of the procedures for handling static-sensitive devices before you remove the enclosure.

About this task

To replace a control enclosure chassis, perform the following steps:

Procedure

1. If you are able to access either of the node canisters with the service assistant, record the machine type and model of the enclosure, the serial number of the enclosure, and the two WWNNs for the enclosure.
 - From the service assistant home page, open the location data for the node. Record the machine type and model (MTM), the serial number, WWNN 1 and WWNN 2 from the enclosure column.
 - If you are replacing the enclosure because neither node canister can start, retrieve this information after you have completed the replacement.
 - a. Start the service assistant on one of the canisters.
 - b. Go to the node location data on the home page.
 - c. Record the machine type and model, the serial number, WWNN 1 and WWNN 2 from the node copy column.

The machine type and model and the serial number are also shown on the labels at the front and back of the enclosure.

2. If the enclosure is still active, shut down the block host I/O and the Metro Mirror and Global Mirror activity to all the volumes that depend on the affected enclosure.

This statement applies to all volumes in the I/O group that are managed by this enclosure plus any volumes in other I/O groups that depend on the drives in the affected I/O group.

3. If your system contains a single I/O group and if the clustered system is still online, shut the system down by following the procedure in "Turning off the system".
4. If your system contains more than one I/O group, you might not need to power down the file modules if the enclosure is not connected to the file modules and if the drives that are managed by this enclosure are not used in any file volumes. Use the following procedure to see if any file volumes are affected:
 - a. Use the output from the **lsenclosure** CLI command to determine the `enclosure_id` for the control enclosure that is to be replaced.

- b. Use the following CLI command to find the volumes that depend on this enclosure:

```
lsdependentvdisks -enclosure <enclosure_id>
```

Dependent volume names that start with IFS are file volumes that are used by the file modules to provide file systems. Turn off these file modules. See the procedure "Turning off the system".

5. If the I/O group is still online, shut down the I/O group by using the control enclosure CLI.

- a. Identify the two node canisters in the I/O group that are provided by the control enclosure to be replaced.

- b. To shut down each node, issue the following CLI command once for each of the two node canisters:

```
stopssystem -force -node <node ID>
```

- c. Wait for the shutdown to complete.

6. Verify that it is safe to remove the power from the enclosure.

For each of the canisters, verify the status of the system status LED. If the LED is lit on either of the canisters, do not continue because the system is still online. Determine why the node canisters did not shut down in step 3 on page 234 or step 4 on page 234.

Note: If you continue while the system is still active, you risk losing the clustered system configuration and volume cache data that is stored in the canister.

7. Turn off the power to the enclosure using the switches on the power supply units.
8. Record which data cables are plugged into the specific ports. The cables must be inserted back into the same ports after the replacement is complete; otherwise, the system cannot function properly.
9. Disconnect the cable retention brackets and the power cords from the power supply units.
10. Disconnect the data cables for each canister.
11. Remove the power supply units from the enclosure.
12. Remove the canisters from the enclosure. Record the location of each canister. They must be inserted back into the same location in the new enclosure.
13. Remove all the drives and blank drive assemblies from the enclosure. Record the location for each drive. They must be inserted back into the same location in the new enclosure.
14. Remove both enclosure end caps from the enclosure. Keep the left end cap because it is used again.
15. Remove the clamping screws that attached the enclosure to the rack cabinet.
16. Remove the enclosure chassis from the front of the rack cabinet and take the chassis to a work area.
17. Install the new enclosure chassis in the rack cabinet.
18. Remove the end caps from the new enclosure and install the clamping screws that attach the enclosure to the rack cabinet.
19. Replace the end caps. Use the new right end cap and use the left end cap that you removed in step 14.
Using the left end cap that you removed preserves the model and serial number identification.

20. Reinstall the drives in the new enclosure. The drives must be inserted back into the same location from which they were removed on the old enclosure.
21. Reinstall the canisters in the enclosure. The canisters must be inserted back into the same location from which they were removed on the old enclosure.
22. Install the power supply units.
23. Reattach the data cables to each canister using the information that you recorded previously.

Note: The cables must be inserted back into the same ports from which they were removed on the old enclosure; otherwise, the system cannot function properly.

24. Attach the power cords and the cable retention brackets to the power supply units.
25. Write the old enclosure machine type and model (MTM) and serial number on the repair identification (RID) tag that is supplied. Attach the tag to the left flange at the back of the enclosure.
26. Turn on the power to the enclosure using the switches on the power supply units.

The node canisters boot up. The fault LEDs are on because the new enclosure has not been set with the identity of the old enclosure. The node canisters report that they are in the wrong location.

- a. Connect to the service assistant on one of the node canisters to configure the machine type and model, serial number, and WWNNs that are stored in the enclosure. If you have replaced a node canister, connect to the canister that has not been replaced.

You can connect using the previous service address. However, it is not always possible to maintain this address. If you cannot connect through the original service address, attempt to connect using the default service address. If you still cannot access the system, see “Problem: Cannot connect to the service assistant” on page 193.

- b. Use the **Configure enclosure** panel.
- c. Select the options to **Update WWNN 1**, **Update WWNN 2**, **Update the machine type and model**, and **Update the serial number**. Do not update the system ID. Use the node copy data for each of the values. Check that these values match the values that you recorded in step 1 on page 234.

If you were not able to record the values, use the node copy values only if none of them have all zeroes as their value. If any of the node copy values are all zeroes, connect the service assistant to the other node canister and configure the enclosure there. If you still do not have a full set of values, contact IBM support.

After you modify the configuration, the node attempts to restart.

Note: There are situations where the canisters restart and report critical node error 508. If the node canisters fail to become active after they restart when the enclosure is updated, check their status by using the service assistant. If both node canisters show critical node error 508, use the service assistant to restart the nodes. For any other node error, see “Procedure: Fixing node errors” on page 206. To restart a node from the service assistant, perform the following steps:

- 1) Log on to the service assistant.
- 2) From the home page, select the node that you want to restart from the **Changed Node List**.

3) Select **Actions > Restart**.

d. The system starts and can handle I/O requests from the host systems.

Note: The configuration changes that are described in the following steps must be performed to ensure that the system is operating correctly. If you do not perform these steps, the system is unable to report certain errors.

- e. Power up the file modules. See "Turning on the system".
27. Start the management GUI and select **Monitoring > System Details**. You see an additional enclosure in the system list because the system has detected the replacement control enclosure. The original control enclosure is still listed in its configuration. The original enclosure is listed with its original enclosure ID. It is offline and managed. The new enclosure has a new enclosure ID. It is online and unmanaged.
28. Select the original enclosure in the tree view.
Verify that it is offline and managed and that the serial number is correct.
29. From the **Actions** menu, select **Remove enclosure** and confirm the action. The physical hardware has already been removed. You can ignore the messages about removing the hardware. Verify that the original enclosure is no longer listed in the tree view.
30. Add the new enclosure to the system.
 - a. Select the enclosure from the tree view.
 - b. From the **Actions** menu, select **Add Control and Expansion Enclosures**.
 - c. Because you have already added the hardware, select **Next** on the first panel that asks you to install the hardware. The next panel shows the unmanaged new enclosure.
 - d. Follow the steps in the wizard. The wizard changes the control enclosure to Managed.
 - e. Select the enclosure and add it to the system.
31. Select the new enclosure in the tree view and verify that it is now online and managed.
32. Change the enclosure ID of the replaced enclosure to that of the original enclosure. From the **Enclosure ID** field, select the ID value of the original enclosure.
33. Check the status of all volumes and physical storage to ensure everything is online.
34. Restart the host application and any FlashCopy activities, Global Mirror activities, or Metro Mirror activities that were stopped.

Results

Replacing an expansion enclosure chassis

This topic describes how to replace an expansion enclosure chassis.

Before you begin

DANGER

When working on or around the system, observe the following precautions:

Electrical voltage and current from power, telephone, and communication cables are hazardous. To avoid a shock hazard:

- If IBM supplied a power cord(s), connect power to this unit only with the IBM provided power cord. Do not use the IBM provided power cord for any other product.
- Do not open or service any power supply assembly.
- Do not connect or disconnect any cables or perform installation, maintenance, or reconfiguration of this product during an electrical storm.
- The product might be equipped with multiple power cords. To remove all hazardous voltages, disconnect all power cords.
- Connect all power cords to a properly wired and grounded electrical outlet. Ensure that the outlet supplies proper voltage and phase rotation according to the system rating plate.
- Connect any equipment that will be attached to this product to properly wired outlets.
- When possible, use one hand only to connect or disconnect signal cables.
- Never turn on any equipment when there is evidence of fire, water, or structural damage.
- Disconnect the attached power cords, telecommunications systems, networks, and modems before you open the device covers, unless instructed otherwise in the installation and configuration procedures.
- Connect and disconnect cables as described in the following procedures when installing, moving, or opening covers on this product or attached devices.

To disconnect:

1. Turn off everything (unless instructed otherwise).
2. Remove the power cords from the outlets.
3. Remove the signal cables from the connectors.
4. Remove all cables from the devices.

To connect:

1. Turn off everything (unless instructed otherwise).
 2. Attach all cables to the devices.
 3. Attach the signal cables to the connectors.
 4. Attach the power cords to the outlets.
 5. Turn on the devices.
- Sharp edges, corners and joints may be present in and around the system. Use care when handling equipment to avoid cuts, scrapes and pinching. (D005)

Attention: If your system is powered on and performing I/O operations, go the management GUI and follow the fix procedures. Performing the replacement actions without the assistance of the fix procedures can result in loss of data or access to data.

Even though many of these procedures are hot-swappable, these procedures are intended to be used only when your system is not up and running and performing I/O operations. Unless your system is offline, go to the management GUI and follow the fix procedures.

Be careful when you are replacing the hardware components that are located in the back of the system that you do not inadvertently disturb or remove any cables that you are not instructed to remove.

Ensure that you are aware of the procedures for handling static-sensitive devices before you remove the enclosure.

About this task

Note: If your system is online, replacing an expansion enclosure can cause one or more of your volumes to go offline or your quorum disks to be inaccessible. Before you proceed with these procedures, verify which volumes might go offline. From the management GUI, go to **Home > Manage Devices**. Select the enclosure that you want to replace. Then select **Show Dependent Volumes** in the **Actions** menu.

To replace an expansion enclosure chassis, perform the following steps:

Procedure

1. Shut down the I/O activity to the enclosure, which includes host access to GPFS file systems, FlashCopy, Metro Mirror and Global Mirror access.
2. Turn off the power to the enclosure by using the switches on the power supply units.
3. Record which data cables are plugged into the specific ports. The cables must be inserted back into the same ports after the replacement is complete; otherwise, the system cannot function properly.
4. Disconnect the cable retention brackets and the power cords from the power supply units.
5. Disconnect the data cables for each canister.
6. Remove the power supply units from the enclosure.
7. Remove the canisters from the enclosure.
8. Remove all the drives and blank drive assemblies from the enclosure. Record the location for each drive. They must be inserted back into the same location in the new enclosure.
9. Remove both enclosure end caps from the enclosure. Keep the left end cap because it is used again.
10. Remove the clamping screws that attached the enclosure to the rack cabinet.
11. Remove the enclosure chassis from the front of the rack cabinet and take the chassis to a work area.
12. Install the new enclosure chassis in the rack cabinet.
13. Remove the end caps from the new enclosure and install the clamping screws that attach the enclosure to the rack cabinet.

14. Replace the end caps. Use the new right end cap and use the left end cap that you removed in step 9 on page 239.
Using the left end cap that you removed preserves the model and serial number identification.
15. Reinstall the drives in the new enclosure. The drives must be inserted back into the same location from which they were removed on the old enclosure.
16. Reinstall the canisters in the enclosure.
17. Install the power supply units.
18. Reattach the data cables to each canister by using the information that you recorded previously.

Note: The cables must be inserted back into the same ports from which they were removed on the old enclosure; otherwise, the system cannot function properly.

19. Attach the power cords and the cable retention brackets to the power supply units.
20. Write the old enclosure machine type and model (MTM) and serial number on the repair identification (RID) tag that is supplied. Attach the tag to the left flange at the back of the enclosure.
21. Turn on the power to the enclosure by using the switches on the power supply units.

Results

The system records an error that indicates that an enclosure FRU replacement was detected. Go to the management GUI to use the fix procedure to change the machine type and model and serial number in the expansion enclosure.

Replacing the support rails

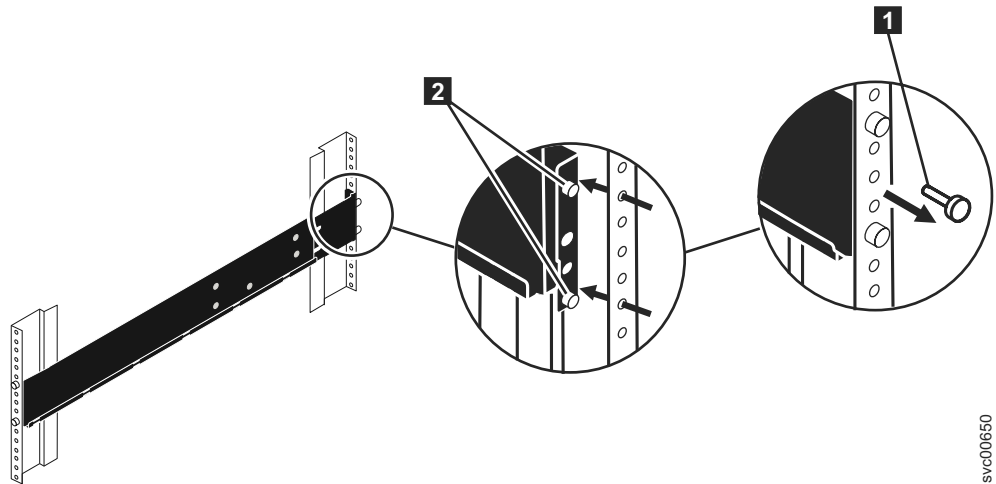
This topic describes how to replace the support rails.

About this task

Perform the following steps to replace the support rails:

Procedure

1. Remove the enclosure.
2. Record the location of the rail assembly in the rack cabinet.
3. Working from the back of the rack cabinet, remove the clamping screw **1** from the rail assembly on both sides of the rack cabinet.



svc00650

Figure 52. Removing a rail assembly from a rack cabinet

4. Working from the front of the rack cabinet, remove the clamping screw from the rail assembly on both sides of the rack cabinet.
 5. From one side of the rack cabinet, grip the rail and slide the rail pieces together to shorten the rail.
 6. Disengage the rail location pins **2**.
 7. From the other side the rack cabinet, grip the rail and slide the rail pieces together to shorten the rail.
 8. Disengage the rail location pins **2**.
 9. Starting from the location of the previous rail assembly, align the bottom of the rail with the bottom of the two rack units. Insert the rail location pins through the holes in the rack cabinet.
 10. Insert a clamping screw into the upper mounting hole between the rail location pins.
 11. Tighten the screw to secure the rail to the rack.
 12. Working from the rear of the rack cabinet, extend the rail that you secured to the front to align the bottom of the rail with the bottom of the two rack units.
- Note:** Ensure that the rail is level between the front and the back.
13. Insert the rail location pins through the holes in the rack cabinet.
 14. Insert a clamping screw into the upper mounting hole between the rail location pins.
 15. Tighten the screw to secure the rail to the rack from the back side.
 16. Repeat the steps to secure the opposite rail to the rack cabinet.

General storage system procedures

This section provides general information about hardware and Fibre Channel link issues.

SAN problem determination

About this task

SAN failures might cause Storwize V7000 Unified volumes to be inaccessible to host systems. Failures can be caused by SAN configuration changes or by hardware failures in SAN components.

The following list identifies some of the hardware that might cause failures:

- Power, fan, or cooling switch
- Application-specific integrated circuits
- Installed small form-factor pluggable (SFP) transceiver
- Fiber-optic cables

Perform the following steps if you were sent here from the error codes:

Procedure

1. Verify that the power is turned on to all switches and storage controllers that the Storwize V7000 Unified system uses, and that they are not reporting any hardware failures. If problems are found, resolve those problems before proceeding further.
2. Verify that the Fibre Channel cables that connect the systems to the switches are securely connected.
3. If you have a SAN management tool, use that tool to view the SAN topology and isolate the failing component.

iSCSI performance analysis and tuning

This procedure provides a solution for iSCSI host performance problems while connected to Storwize V7000 Unified system, and its connectivity to the network switch.

About this task

Some of the attributes and host parameters that might affect iSCSI performance:

- Transmission Control Protocol (TCP) Delayed ACK
- Ethernet jumbo frame
- Network bottleneck or over subscription
- iSCSI session login balance

Procedure

1. Disable the TCP delayed acknowledgment feature.

To disable this feature, please refer to OS/platform documentation.

- VMWare: http://kb.vmware.com/selfservice/microsites/search.do?language=en_US&cmd=displayKC&externalId=1002598(TCP)
- Windows: <http://support.microsoft.com/kb/823764>

The primary signature of this issue: read performance is significantly lower than write performance. Transmission Control Protocol (TCP) delayed acknowledgment is a technique used by some implementations of the TCP in an effort to improve network performance. However, in this scenario where the number of outstanding I/O is 1, the technique can significantly reduce I/O performance.

In essence, several ACK responses may be combined together into a single response, reducing protocol overhead. As described in RFC 1122, a host may delay sending an ACK response by up to 500 ms. Additionally, with a stream of full-sized incoming segments, ACK responses must be sent for every second segment.

Important: The host must be rebooted for these settings to take effect. A few platforms (for example, standard Linux distributions) do not provide a way to disable this feature. However, the issue has been resolved with the version 7.1 release, and no host configuration changes are required to manage **TcpDelayedAck** behavior.

2. Enable jumbo frame for iSCSI.

Jumbo frames are Ethernet frames with a size exceeding 1500 bytes. The maximum transmission unit (MTU) parameter is used to measure the size of jumbo frames.

The Storwize V7000 Unified supports 9000 bytes MTU. Refer to the CLI command **CFGPORTIP** to enable jumbo frame. This command is disruptive as the link flips and the I/O operation through that port will pause.

The network must support jumbo frames end-to-end for this to be effective; verify this by sending a ping packet to be delivered without fragmentation. For example:

- Windows:

```
#ping ?t <iscsi target ip> source <iscsi initiator ip> -f -l <new mtu size - 28>
```

- Linux:

```
#ping <iscsi target ip> source <iscsi initiator ip> -s <new mtu size - 28> -M do
```

- ESXi:

```
#ping <iscsi target ip> source <iscsi initiator ip> -s <new mtu size - 28> -d
```

3. Verify the switch's port statistic where initiator/target ports are connected to make sure packet drops are not high.

Review network architecture to avoid any bottlenecks and oversubscription. The network need to be balanced to avoid any packet drop; packet drop significantly reduces storage performance. Involve networking support to fix any such issues.

4. Optimize and utilize all iSCSI ports.

To optimize Storwize V7000 Unified resource utilization all iSCSI ports must be utilized.

- If two ports of a node are used for iSCSI, lay out the network such that hosts are logged in to the required port.
- Each port is assigned to one CPU, and by balancing the login, one can maximize CPU utilization and achieve better performance.
- Avoid situations where 50 hosts are logged in to port 1 and only 5 host are logged in to port 2.
- Use proper subnetting to achieve a balance between the number of sessions and redundancy.

Fibre Channel link failures

When a failure occurs on a single Fibre Channel link, the small form-factor pluggable (SFP) transceiver might need to be replaced.

Before you begin

The following items can indicate that a single Fibre Channel link has failed:

- The Fibre Channel status LEDs at the rear of the node canister
- An error that indicates a single port has failed

Attempt each of these actions, in the following order, until the failure is fixed:

1. Ensure that the Fibre Channel cable is securely connected at each end.
2. Replace the Fibre Channel cable.
3. Replace the SFP transceiver for the failing port on the Storwize V7000 Unified Storwize V7000 Unified node.

Note: Storwize V7000 Unified nodes are supported with both longwave SFP transceivers and shortwave SFP transceivers. You must replace an SFP transceiver with the same type of SFP transceiver. If the SFP transceiver to replace is a longwave SFP transceiver, for example, you must provide a suitable replacement. Removing the wrong SFP transceiver could result in loss of data access.

- 4.
5. Contact IBM Support for assistance in replacing the node canister.

Ethernet iSCSI host-link problems

If you are having problems attaching to the Ethernet hosts, your problem might be related to the network, the Storwize V7000 Unified system, or the host.

Before you begin

For network problems, you can attempt any of the following actions:

- Test your connectivity between the host and Storwize V7000 Unified ports.
- Try to ping the Storwize V7000 Unified system from the host.
- Ask the Ethernet network administrator to check the firewall and router settings.
- Check that the subnet mask and gateway are correct for the Storwize V7000 Unified host configuration.

Using the management GUI for Storwize V7000 Unified problems, you can attempt any of the following actions:

- View the configured node port IP addresses.
- View the list of volumes that are mapped to a host to ensure that the volume host mappings are correct.
- Verify that the volume is online.

For host problems, you can attempt any of the following actions:

- Verify that the host iSCSI qualified name (IQN) is correctly configured.
- Use operating system utilities (such as Windows device manager) to verify that the device driver is installed, loaded, and operating correctly.

Recover system procedure

The recover system procedure recovers the entire system if the block cluster state has been lost from all nodes. The recover system procedure recovers the entire storage system if the data has been lost from all control enclosure node canisters. The procedure re-creates the storage system by using saved configuration data. The recovery might not be able to restore all volume data. This procedure is also known as Tier 3 (T3) recovery.

Before you perform the storage system recovery you should shutdown the file modules:

- From a workstation with access to the management subnet, log on to the management CLI as an administrator. For example, admin default password is admin.
- `ssh admin@<management IP>`
- Use the `lsnode` CLI command to get the node name of the file module with the passive management node role.
- `initnode -n <passive node name> -s`
- Wait 10 seconds.
- `initnode -s`

After you have performed the following storage system recovery procedure then refer to Turning on the system, located in the Information Center, to power the file modules back on.

Contact IBM Remote Technical support if the health indicator in the management GUI does not turn back to green within 30 minutes. They can assist you with recovering the file modules so that access to the file systems can be restored.

After you perform the storage system recovery procedure, contact IBM support. They can assist you with recovering the file modules so that access to the file systems can be restored.

Attention: Perform service actions only when directed by the fix procedures. If used inappropriately, service actions can cause loss of access to data or even data loss. Before attempting to recover a storage system, investigate the cause of the failure and attempt to resolve those issues by using other fix procedures. Read and understand all of the instructions before performing any action.

Attention: Do not attempt the recovery procedure unless the following conditions are met:

- All hardware errors are fixed.
- All node canisters have candidate status.
- All node canisters must be at the same level of code that the storage system had before the system failure. If any node canisters were modified or replaced, use the service assistant to verify the levels of code, and where necessary, to upgrade or downgrade the level of code.

The system recovery procedure is one of several tasks that must be performed. The following list is an overview of the tasks and the order in which they must be performed:

1. Preparing for system recovery

- a. Review the information regarding when to run the recover system procedure
 - b. Fix your hardware errors
 - c. Remove the system information for node canisters with error code 550 or error code 578 by using the service assistant.
2. Performing the system recovery. After you prepared the system for recovery and met all the pre-conditions, run the system recovery.

Note: Run the procedure on one system in a fabric at a time. Do not perform the procedure on different node canisters in the same system. This restriction also applies to remote systems.

3. Performing actions to get your environment operational
 - Recovering from offline VDisks (volumes) by using the CLI
 - Checking your system, for example, to ensure that all mapped volumes can access the host.

When to run the recover system procedure

Attempt a recover procedure only after a complete and thorough investigation of the cause of the system failure. Attempt to resolve those issues by using other service procedures.

Attention: If you experience failures at any time while running the recover system procedure, call the IBM Support Center. Do not attempt to do further recovery actions, because these actions might prevent IBM Support from restoring the system to an operational status.

Certain conditions must be met before you run the recovery procedure. Use the following items to help you determine when to run the recovery procedure:

1. Check that no node in the cluster is active and that the management IP is not accessible from any other node. If this is the case, there is no need to recover the cluster.
2. Resolve all hardware errors in nodes so that only nodes 578 or 550 are present. If this is not the case, go to “Fix hardware errors.”
3. Ensure all backend-storage that is administered by cluster is present before you run the recover system procedure.
4. If any nodes have been replaced, ensure that the WWNN of the replacement node matches that of the replaced node, and that no prior system data remains on this node. (See “Procedure: Removing system data from a node canister” on page 204.)

Fix hardware errors

Before running a system recovery procedure, it is important to identify and fix the root cause of the hardware issues.

Identifying and fixing the root cause can help recover a system, if these are the faults that are causing the system to fail. The following are common issues which can be easily resolved:

- The node has been powered off or the power cords were unplugged.
- Check the node status of every node canister that is part of this system. Resolve all hardware errors except node error 578 or node error 550.
 - All nodes must be reporting either a node error 578 or a node error 550. These error codes indicate that the system has lost its configuration data. If

any nodes report anything other than these error codes, do not perform a recovery. You can encounter situations where non-configuration nodes report other node errors, such as a 550 node error. The 550 error can also indicate that a node is not able to join a system.

- If any nodes show a node error 550, record the error data that is associated with the 550 error from the service assistant.
 - In addition to the node error 550, the report can show data that is separated by spaces in one of the following forms:
 - Node identifiers in the format: *<enclosure_serial>-<canister slot ID>*(7 characters, hyphen, 1 number), for example, 01234A6-2
 - Quorum drive identifiers in the format: *<enclosure_serial>:<drive slot ID>[<drive 11S serial number>]* (7 characters, colon, 1 or 2 numbers, open square bracket, 22 characters, close square bracket), for example, 01234A9:21[11S1234567890123456789]
 - Quorum MDisk identifier in the format: *WWPN/LUN* (16 hexadecimal digits followed by a forward slash and a decimal number), for example, 1234567890123456/12
 - If the error data contains a node identifier, ensure that the node that is referred to by the ID is showing node error 578. If the node is showing a node error 550, ensure that the two nodes can communicate with each other. Verify the SAN connectivity, and if the 550 error is still present, restart one of the two nodes from the service assistant by clicking **Restart Node**.
 - If the error data contains a quorum drive identifier, locate the enclosure with the reported serial number. Verify that the enclosure is powered on and that the drive in the reported slot is powered on and functioning. If the node canister that is reporting the fault is in the I/O group of the listed enclosure, ensure that it has SAS connectivity to the listed enclosure. If the node canister that is reporting the fault is in a different I/O group from the listed enclosure, ensure that the listed enclosure has SAS connectivity to both node canisters in the control enclosure in its I/O group. After verification, restart the node by clicking **Restart Node** from the service assistant.
 - If the error data contains a quorum MDisk identifier, verify the SAN connectivity between this node and that WWPN. Check the storage controller to ensure that the LUN referred to is online. After verification, if the 550 error is still present, restart the node from the service assistant by clicking **Restart Node**.
 - If there is no error data, the error is because there are insufficient connections between nodes over the Fibre Channel network. Each node must have at least two independent Fibre Channel logical connections, or logins, to every node that is not in the same enclosure. An independent connection is one where both physical ports are different. In this case, there is a connection between the nodes, but there is not a redundant connection. If there is no error data, wait 3 minutes for the SAN to initialize. Next, verify:
 - There are at least two Fibre Channel ports that are operational and connected on every node.
 - The SAN zoning allows every port to connect to every port on every other node
 - All redundant SANs (if used) are operational.

After verification, if the 550 error is still present, restart the node from the service assistant by clicking **Restart Node**.

Note: If after resolving all these scenarios, half or greater than half of the nodes are reporting node error 578, it is appropriate to run the recovery procedure. Call the IBM Support Center for further assistance.

- For any nodes that are reporting a node error 550, ensure that all the missing hardware that is identified by these errors is powered on and connected without faults.
- If you have not been able to restart the system, and if any node other than the current node is reporting node error 550 or 578, you must remove system data from those nodes. This action acknowledges the data loss and puts the nodes into the required candidate state.

Removing system information for node canisters with error code 550 or error code 578 using the service assistant

The system recovery procedure works only when all node canisters are in candidate status. If there are any node canisters that display error code 550 or error code 578, you must remove their data.

About this task

Before performing this task, ensure that you have read the introductory information in the overall recover system procedure.

To remove system information from a node canister with an error 550 or 578, follow this procedure using the service assistant:

Procedure

1. Point your browser to the service IP address of one of the nodes, for example, https://node_service_ip_address/service/.

If you do not know the IP address or if it has not been configured, you must assign an IP address using the initialization tool.

2. Log on to the service assistant.
3. Select **Manage System**.
4. Click **Remove System Data**.
5. Confirm that you want to remove the system data when prompted.
6. Remove the system data for the other nodes that display a 550 or a 578 error.
All nodes previously in this system must have a node status of Candidate and have no errors listed against them.
7. Resolve any hardware errors until the error condition for all nodes in the system is **None**.
8. Ensure that all nodes in the system display a status of candidate.

Results

When all nodes display a status of candidate and all error conditions are **None**, you can run the recovery procedure.

Performing system recovery using the service assistant

Start recovery when all node canisters that were members of the system are online and have candidate status. Use the service assistant to verify the status. If any nodes display error code 550 or 578, remove their system data to place them into candidate status. Do not run the recovery procedure on different node canisters in the same system.

About this task

All node canisters must be at the original level of code, prior to the system failure. If any node canisters were modified or replaced, use the service assistant to verify the levels of code, and where necessary, to upgrade or downgrade the level of code.

Attention: This service action has serious implications if not performed properly. If at any time an error is encountered not covered by this procedure, stop and call IBM Support.

Note: The web browser must not block pop-up windows, otherwise progress windows cannot open.

Run the recovery from any node canisters in the system; the node canisters must not have participated in any other system.

Note: Each individual stage of the recovery procedure might take significant time to complete, dependant upon the specific configuration.

Before performing this procedure, read the recover system procedure introductory information; see “Recover system procedure” on page 245.

Procedure

1. Point your browser to the service IP address of one of the node canisters.
If the IP address is unknown or has not been configured, assign an IP address using the initialization tool; see “Procedure: Changing the service IP address of a node canister” on page 206.
2. Log on to the service assistant.
3. Check that all node canisters that were members of the system are online and have candidate status.
If any nodes display error code 550 or 578, remove their system data to place them into candidate status; see “Procedure: Removing system data from a node canister” on page 204.
4. Select **Recover System** from the navigation.
5. Follow the online instructions to complete the recovery procedure.
 - a. Verify the date and time of the last quorum time. The time stamp must be less than 30 minutes before the failure. The time stamp format is *YYYYMMDD hh:mm*, where *YYYY* is the year, *MM* is the month, *DD* is the day, *hh* is the hour, and *mm* is the minute.
Attention: If the time stamp is not less than 30 minutes before the failure, call IBM Support.
 - b. Verify the date and time of the last backup date. The time stamp must be less than 24 hours before the failure. The time stamp format is *YYYYMMDD hh:mm*, where *YYYY* is the year, *MM* is the month, *DD* is the day, *hh* is the hour, and *mm* is the minute.
Attention: If the time stamp is not less than 24 hours before the failure, call IBM Support.
Changes made after the time of this backup date might not be restored.

Results

Any one of the following categories of messages may be displayed:

- T3 successful

The volumes are back online. Use the final checks to get your environment operational again.

- T3 recovery completed with errors

T3 recovery completed with errors: One or more of the volumes are offline because there was fast write data in the cache. To bring the volumes online, see “Recovering from offline VDisks using the CLI” for details.

- T3 failed

Call IBM Support. Do not attempt any further action.

Verify the environment is operational by performing the checks provided in “What to check after running the system recovery” on page 251.

If any errors are logged in the error log after the system recovery procedure completes, use the fix procedures to resolve these errors, especially the errors related to offline arrays.

If the recovery completes with offline volumes, go to “Recovering from offline VDisks using the CLI.”

After performing the storage system recovery procedure, contact IBM support for assistance with recovering the file modules, so access to the file systems can be restored.

Recovering from offline VDisks using the CLI

If a Tier 3 recovery procedure completes with offline VDisks (volumes), then it is likely that the data which was in the write-cache of the node canisters was lost during the failure that caused all of the node canisters to lose the block storage system cluster state. You can use the command-line interface (CLI) to acknowledge that was lost data lost from the write-cache and bring the volume back online so that you can attempt to deal with the data loss.

About this task

If you have performed the recovery procedure, and it has completed successfully but there are offline volumes, you can perform the following steps to bring the volumes back online. Any volumes that are offline and are not thin-provisioned (or compressed) volumes are offline because of the loss of write-cache data during the event that led all node canisters to lose their cluster state. Any data lost from the write-cache cannot be recovered. These volumes might need additional recovery steps after the volume is brought back online.

Note: If you encounter errors in the error log after running the recovery procedure that are related to offline arrays, use the fix procedures to resolve the offline array errors before fixing the offline volume errors.

Example

Perform the following steps to recover an offline volume after the recovery procedure has completed:

1. Delete all IBM FlashCopy function mappings and Metro Mirror or Global Mirror relationships that use the offline volumes.
2. Run the **recovervdisk** or **recovervdiskbysystem** command. (This will only bring the volume back online so that you can attempt to deal with the data loss.)
Contact IBM Remote Technical Support to help you with recovering from file volumes that have been corrupted by data lost from the write-cache. They might ask you to refer to “Recovering a GPFS file system” on page 161 and help you with interpreting the results from the **chkfs** CLI command.
3. Refer to “What to check after running the system recovery” for what to do with volumes that have been corrupted by the loss of data from the write-cache.
4. Recreate all FlashCopy mappings and Metro Mirror or Global Mirror relationships that use the volumes.

What to check after running the system recovery

Several tasks must be performed before you use the system.

The recovery procedure performs a recreation of the old system from the quorum data. However, some things cannot be restored, such as cached data or system data managing in-flight I/O. This latter loss of state affects RAID arrays managing internal storage. The detailed map about where data is out of synchronization has been lost, meaning that all parity information must be restored, and mirrored pairs must be brought back into synchronization. Normally this results in either old or stale data being used, so only writes in flight are affected. However, if the array had lost redundancy (such as syncing, or degraded or critical RAID status) prior to the error requiring system recovery, then the situation is more severe. Under this situation you need to check the internal storage:

- Parity arrays will likely be syncing to restore parity; they do not have redundancy when this operation proceeds.
- Because there is no redundancy in this process, bad blocks may have been created where data is not accessible.
- Parity arrays could be marked as corrupt. This indicates that the extent of lost data is wider than in-flight IO, and in order to bring the array online, the data loss must be acknowledged.
- Raid-6 arrays that were actually degraded prior the system recovery may require a full restore from backup. For this reason, it is important to have at least a capacity match spare available.

Be aware of these differences regarding the recovered configuration:

- FlashCopy mappings are restored as “idle_or_copied” with 0% progress. Both volumes must have been restored to their original I/O groups.
- The management ID is different. Any scripts or associated programs that refer to the system-management ID of the clustered system (system) must be changed.
- Any FlashCopy mappings that were not in the “idle_or_copied” state with 100% progress at the point of disaster have inconsistent data on their target disks. These mappings must be restarted.
- Intersystem remote copy partnerships and relationships are not restored and must be re-created manually.

- Consistency groups are not restored and must be re-created manually.
- Intrasystem remote copy relationships are restored if all dependencies were successfully restored to their original I/O groups.
- The system time zone might not have been restored.
- The GPFS system quorum state held on the control enclosure might not have been restored.

Before using the block volumes that are accessed by the SAN or with iSCSI, perform the following tasks:

- Start the block host systems.
- Manual actions might be necessary on the hosts to trigger them to rescan for devices. You can perform this task by disconnecting and reconnecting the Fibre Channel cables to each host bus adapter (HBA) port.
- Verify that all mapped volumes can be accessed by the hosts.
- Run file system consistency checks on the block hosts.
- Run the application consistency checks.

Before using the file volumes that are used by GPFS on the file modules to provide Network Attached Storage (NAS), perform the following task:

- Contact IBM support for assistance with recovering the GPFS quorum state so that access to files as NAS can be restored.

Backing up and restoring the system configuration

You can back up and restore the configuration data for the system after preliminary tasks are completed.

Configuration data for the system provides information about your block system and the objects that are defined in it. The backup and restore functions of the **svcconfig** command can back up and restore only your configuration data for the Storwize V7000 system. You must regularly back up your file systems and your application data by using the appropriate backup methods.

You can maintain your configuration data for the system by completing the following tasks:

- Backing up the configuration data
- Restoring the configuration data
- Deleting unwanted backup configuration data files

Before you back up your configuration data, the following prerequisites must be met:

- No independent operations that change the configuration for the system can be running while the backup command is running.
- No object name can begin with an underscore character (_).

Note:

- The default object names for controllers, I/O groups, and managed disks (MDisks) do not restore correctly if the ID of the object is different from what is recorded in the current configuration data file.
- All other objects with default names are renamed during the restore process. The new names appear in the format *name_r* where *name* is the name of the object in your system.

Contact the IBM support center to help you prepare the Storwize V7000 Unified system to do the restoring of the system configuration on the control enclosure.

The configuration restore procedure is designed to restore the information about your block storage configuration, such as block volumes, local Metro Mirror information, local Global Mirror information, storage pools, and nodes. All the data that is written to the block volumes is not restored.

To restore the data on the block volumes, you must restore the application data separately from any application that uses the volumes on the clustered system as storage. The file volumes are not restored. You must restore the file module configuration and the file systems separately. Therefore, you must have a backup of this data before you follow the configuration recovery process.

Before you restore your configuration data, the following prerequisites must be met:

- You have the Security Administrator role associated with your user name and password.
- You have a copy of your backup configuration files on a server that is accessible to the system.
- You have a backup copy of your application data that is ready to load on your system after the restore configuration operation is complete.
- You know the current license settings for your system.
- You did not remove any hardware since the last backup of your configuration.
- No zoning changes were made on the Fibre Channel fabric which would prevent communication between the Storwize V7000 Unified and any storage controllers which are present in the configuration.
- For configurations with more than one I/O group, if a new system is created on which the configuration data is to be restored, the I/O groups for the other control enclosures must be added.

Use the following steps to determine how to achieve an ideal T4 recovery:

- Open the appropriate `svc.config.backup.xml` (or `svc.config.cron.xml`) file with a suitable text editor or browser and navigate to the **node section** of the file.
- For each node entry, make a note of the value of following properties; `IO_group_id`, `canister_id`, `enclosure_serial_number`.
- Use the CLI `sainfo lsservicenodes` command and the data to determine which node canisters previously belonged in each I/O group.

Restoring the system configuration should be performed via one of the nodes previously in IO group zero. For example, **property name="IO_group_id" value="0"** . The remaining enclosures should be added, as required, in the appropriate order based on the previous **IO_group_id** of its node canisters.

Note: It is not currently possible to determine which canister within the identified enclosure was previously used for cluster creation. Typically the restoration should be performed via canister 1.

Before you begin, hardware recovery must be complete. The following hardware must be operational: hosts, Storwize V7000 Unified, drives, the Ethernet network, and the SAN fabric.

Backing up the system configuration using the CLI

You can back up your configuration data using the command-line interface (CLI).

Before you begin

Before you back up your configuration data, the following prerequisites must be met:

- No independent operations that change the configuration can be running while the backup command is running.
- No object name can begin with an underscore character (_).

About this task

The backup feature of the **svconfig** CLI command is designed to back up information about your system configuration, such as volumes, local Metro Mirror information, local Global Mirror information, managed disk (MDisk) groups, and nodes. All other data that you wrote to the volumes is *not* backed up. Any application that uses the volumes on the system as storage, must back up its application data using the appropriate backup methods.

You must regularly back up your configuration data and your application data to avoid data loss. Do this after any significant changes in configuration have been made to the system.

Note: The system automatically creates a backup of the configuration data each day at 1 AM. This is known as a **cron** backup and is written to `/dumps/svc.config.cron.xml_serial#` on the configuration node.

A manual backup can be generated at any time using the instructions in this task. If a severe failure occurs, both the configuration of the system and application data might be lost. The backup of the configuration data can be used to restore the system configuration to the exact state it was in before the failure. In some cases, it might be possible to automatically recover the application data. This can be attempted with the Recover System Procedure, also known as a Tier 3 (T3) procedure. To restore the system configuration without attempting to recover the application data, use the Restoring the System Configuration procedure, also known as a Tier 4 (T4) recovery. Both of these procedures require a recent backup of the configuration data.

Note: The configuration applies to the Storwize V7000 only, and not the file modules.

Complete the following steps to back up your configuration data:

Procedure

1. Back up all of the application data that you stored on your volumes using your preferred backup method.
2. Issue the following CLI command to back up your configuration:
`svconfig backup`

The following output is an example of the messages that might be displayed during the backup process:

```
CMMVC6155I SVCCONFIG processing completed successfully
```

The **svconfig backup** CLI command creates three files that provide information about the backup process and the configuration. These files are created in the /dumps directory of the configuration node canister.

The following table describes the three files that are created by the backup process:

| File name | Description |
|---------------------------------|---|
| svc.config.backup.xml_<serial#> | Contains your configuration data. |
| svc.config.backup.sh_<serial#> | Contains the names of the commands that were issued to create the backup of the system. |
| svc.config.backup.log_<serial#> | Contains details about the backup, including any reported errors or warnings. |

3. Check that the **svconfig backup** command completes successfully, and examine the command output for any warnings or errors. The following output is an example of the message that is displayed when the backup process is successful:

```
CMMVC6155I SVCONFIG processing completed successfully.
```

If the process fails, resolve the errors, and run the command again.

4. Keep backup copies of the files above outside the system to protect them against a system hardware failure. Copy the backup files off the system to a secure location using either the management GUI or scp command line. For example:

```
pscp -unsafe superuser@cluster_ip:/dumps/svc.config.backup.*  
/offclusterstorage/
```

The *cluster_ip* is the IP address or DNS name of the system and **offclusterstorage** is the location where you want to store the backup files.

Tip: To maintain controlled access to your configuration data, copy the backup files to a location that is password-protected.

Deleting backup configuration files using the CLI

You can use the command-line interface (CLI) to delete backup configuration files.

About this task

Perform the following steps to delete backup configuration files:

Procedure

1. Issue the following command to log on to the system:

```
plink -i ssh_private_key_file superuser@control_enclosure_management_ip
```

where *ssh_private_key_file* is the name of the SSH private key file for the superuser and *control_enclosure_management_ip* is the IP address or DNS name of the system from which you want to delete the configuration.

2. Issue the following CLI command to erase all of the files that are stored in the /tmp directory:

```
svconfig clear -all
```

Chapter 6. Call home and remote support

This topic provides instructions for setting up call home support which transmits data with IBM support.

About this task

To set up call home support, perform the following steps:

Procedure

1. Go to **Setting > Support** on the GUI.
2. Under the **Call home** tab, the **General** group displays. Click the **Edit** button at the bottom of the page.
3. Configure **Call home** by completing the text fields. Complete these fields:
 - a. Select the **Enable Call Home** check box. This field enables call home to transmit data with IBM support.
 - b. Complete the information for **Company**, **Customer Email**, and **Customer Phone Number** in case that a PMR must be created.
4. Select the **Outbound Connectivity** group. Complete the fields if the system is behind a proxy:
 - a. Check the **A proxy server is required to access internet** field.
 - b. The **Proxy Address** and **Proxy Port** fields appear. Fill in both fields.
 - c. If the proxy requires authentication, check the **Use Authentication** field:
 - d. Complete the information for the **User** and **Password** fields that appear.
5. Now, select the **Advanced** group and do the following:
 - a. Select the number of **Heart Beat Interval (Days)**, which is used to send small package with general information about the system health. The default is seven days.
 - b. **Machine location** contains information about the physical location of the system. Complete this field as appropriate for the location.
 - c. Enter **Special Instructions** that you want IBM Support to know about the system.
6. Save the new configuration by clicking the **OK** button.

Results

Configuring the remote support system

IBM Storwize V7000 Unified uses IBM Tivoli Assist On Site software to establish remote connections to IBM support representatives.

Establishing an AOS connection

Use this information to establish an AOS connection with IBM remote support for diagnosing and reviewing issues and problems on your system.

Before establishing a connection, be sure that you configure the system for AOS by following the tasks in **Installing > Adding file modules to an existing Storwize V7000 system > Post configuration of the Storwize V7000 Unified system** located in the Information Center,

Establishing a lights-out AOS connection

Use this information to establish a lights-out AOS connection with IBM remote support for diagnosing and reviewing issues and problems on your Storwize V7000 Unified system.

About this task

Configure the system for a lights-out connection using the Enable IBM Tivoli Assist On-Site (AOS) task.

After you configure the system, no other tasks are needed. The remote support contact might ask you for machine information, such as machine type and models, serial numbers, and your machine name. This information helps them locate the system within the back-end AOS connection point repository. The repository is an internal list that shows all available systems that are configured for lights-out connectivity.

Establishing a lights-on AOS connection

Use this information to establish a lights-on AOS connection with IBM remote support for diagnosing and reviewing issues and problems on your IBM Storwize V7000 Unified system.

About this task

This procedure requires that a keyboard, video, and mouse is attached to the local IBM Storwize V7000 Unified file module and that a customer representative is physically present at the connection for the duration of the remote support session.

To establish the AOS connection, perform the following steps:

Note: Each step at the beginning identifies whether the **remote IBM support representative** or the **customer** in the customer data center performs the step.

Procedure

1. **Remote IBM support representative:** Start the connection process from your remote location.
 - a. Establish telephone or Sametime® communications to the IBM authorized servicer at the customer site to find out the problem maintenance request (PMR) number if you do not know it already, and the customer name and geography.
 - b. Open the AOS console and click the connect icon (the plug icon).
 - c. Enter your AOS user ID and password.
 - d. Select the HTTP link type of connection.
 - e. Enter the customer name, the case number (use the PMR number), and the geography.
 - f. Talk to the IBM authorized servicer at the customer site to make sure that the servicer is ready to establish the link before you submit the form.
 - g. Submit the form to the AOS server.

2. **Remote IBM support representative:** Wait for the AOS console to display the connection code when the AOS server returns the code.
3. **Remote IBM support representative:** Communicate the connection code to the IBM authorized servicer at the customer site.

Note: The connection code has a default timeout of 5 minutes. If the IBM authorized servicer at the customer site takes longer than 5 minutes to link to the AOS server, you can extend it for 5 minutes (twice). After the link is established, the link stays active until either you or the authorized servicer breaks the connection.

4. **Customer:** From the file module, log in as root and run `cnrs1launchaos`.
5. **Customer:** Enter the connection code that the IBM support representative gave you.

The script launches the Firefox browser and downloads the executable for establishing the AOS session. Confirm the file download. The file is stored in the `/home/root/desktop` directory.

6. **Customer:** When the executable file finishes downloading, close the Firefox download window and close the browser.

The launch script runs the AOS binary executable file that it downloaded.

7. **Customer:** Grant the IBM support representative the appropriate level of access (Active, Monitor, or Chat) according to customer security for conducting the maintenance action. For example, click **Active**.

Active mode gives full remote access.

Monitor mode restricts the IBM support representative to a view of the console, where the representative can offer guidance on what actions you might take to analyze and correct the problem.

Chat mode opens a chat window with no view of the console.

Chapter 7. Recovery procedures

This section covers the recovery procedures for the file modules and control enclosure.

User ID and system access

This section covers the recovery procedures for the topics that support the user ID and system access.

Accessing a file module as root

Some procedures require that you log on to a file module as root.

About this task

You can use the following methods to access a file module as root.

Procedure

Access a file module as root.

- Type the following command in an X terminal, for example, a Windows or a Linux operating system:

```
ssh -p 1602 root@<file module IP>
```
- Use a Windows application like PuTTY to ssh to port 1602 of a file module service IP and log in as root with the root password that you recorded in your access information. See “Record the access information” on page 3.

Recovering from losing the root password

Some recovery procedures require the root password to be entered for the file module.

Before you begin

If you have forgotten the file module root password, you can change it from any file module user ID that has sufficient authority to run the **chrootpwd** command successfully. If you do not have a user ID or if you have lost the password, then use this procedure to recover. You must have physical access to the file module to perform this procedure. Plug a keyboard and video monitor (KVM) directly into the front of one of the file modules. Stall the boot sequence at the Linux Grub boot loader screen.

About this task

To recover a lost root password, perform the following steps:

Procedure

1. Check that the system is in good health by using the management GUI. Fix any hardware errors that do not require the root password.
2. Use the management GUI to identify the file module that is not the active management node and plug the KVM into that file module.

3. Log in to the management CLI as admin.
 - a. Issue the **stopcluster** command so that you can reboot it in single-user mode.


```
stopcluster --node mgmt001st001 --restart
```
4. To boot the Grub boot loader into single-user mode:
 - a. Watch out for the Grub boot screen on the KVM and select the kernel on the screen.
 - b. Press the e key to edit the entry.
 - c. Select the second line, the line that starts with the word kernel.
 - d. Press the e key to edit the kernel entry to append single-user mode.
 - e. Append the letter S or word Single to the end of the kernel line.

The following screen is an example.

```
[ Minimal BASH-like line editing is supported. For the first word, TAB
  lists possible command completions. Anywhere else TAB lists the possible
  completions of a device/filename. ESC at any time exits. ]

grub edit> kernel /boot/vmlinuz-2.6.15-1-686 root=/dev/sda1 ro Single_
```

- f. Press the Enter key.
5. From the root shell, type **passwd**.
The passwd program prompts you for the new root password. This root password changes at the end of the procedure.
6. Reboot the file module to normal mode. Issue the following command:


```
shutdown -fr now
```

 - a. Wait until the KVM goes past the Grub screen this time and log in when you are prompted to log in.
 - b. Log in as root with the new password on the KVM.
7. Go back to the management CLI to resume the file module back in to the GPFS cluster.
 - a. Add the mgmt001st001 file module back to the system. Issue the following command:


```
resumenode mgmt001st001
```
 - b. Wait until the **1snode** command shows that there are 2 online nodes in the cluster.
8. From the KVM where you logged on as root, use the **chrootpwd** command to change the root password on both file modules.

Results

The chrootpwd program prompts you for the new root password.

The chrootpwd program sets the new root password on both file modules in the cluster.

Resetting the NAS ssh key for configuration communications

The configuration communications between the Storwize V7000 file modules and the control enclosure are done by using ssh over the site 1 Gbps Ethernet LAN; whereas the file data traffic is passed over the direct connect Fibre Channel links by using the SCSI protocol.

Before you begin

During the USB initialization of the Storwize V7000 Unified system, one of the node canisters in the control enclosure creates a public/private key pair to use for ssh. The node canister stores the public key and writes the private key to the USB flash drive memory.

One of the file modules then takes the private key from the USB flash drive memory to use for ssh. The file module passes it to the other file module over the direct connect Ethernet link and then deletes the private key from the USB flash drive memory so that it cannot be used on the wrong system.

It might be necessary to reset the NAS ssh key in the following circumstances:

- When communications between the Storwize V7000 file module and the Storwize V7000 control enclosure is not authorized because of a bad key.
- When both Storwize V7000 file modules have lost the original NAS ssh key.
- When the Storwize V7000 control enclosure has lost the NAS ssh key.

About this task

Perform the following steps to reset the NAS ssh key so that the communications between the file modules and the Storwize V7000 control enclosure resume:

Procedure

1. Log on to the Storwize V7000 control enclosure management CLI as superuser:

```
satask chnaskey -privkeyfile NAS.ppk
```

The private key is left in the /dumps directory.
2. Use SCP to copy the private key file to the /tmp directory on the file module which is currently the active management node:

```
scp -P 1602 /dumps/NAS.ppk root@<active file module IP>:/tmp
```

You are prompted for the file module root password.
3. Log on to the Storwize V7000 Unified management CLI as admin:

```
chstoragesystem --sonasprivkey /tmp/NAS.ppk
```

Working with NFS clients that fail to mount NFS shares after a client IP change

Use this information to resolve a refused mount or Stale NFS file handle response to an attempt to mount Network File System (NFS) shares after a client IP change.

About this task

After a client IP change, a **df -h** command can return no results, as shown in the following example:

```
Filesystem          Size  Used Avail Use% Mounted on
machinename: filename: -    -    -    -    /sharename
```

The **ls** command can return the following error:

```
ls: .: Stale NFS file handle
```

The Storwize V7000 Unified system hosting file module might display the following error:

```
mgmt002st001 mountd[3055867]: refused mount  
request from hostname for sharename (/): not exported
```

If one of these errors occurs, complete the following steps.

Procedure

1. Access the file module, using root privileges, that hosts the active management node role.
2. Issue the **onnode all /usr/sbin/exportfs -a** command to flush the NFS cache in each file module.
3. Verify that the NFS mount is successful. If the problem persists, restart the NFS service on the file module that is refusing the mount requests from that client.
4. Verify that the NFS share mount is successful.

Working with file modules that report a stale NFS file handle

To recover from the “Stale NFS file handle” file system state on a file module, you must suspend, reboot, and resume the file module.

About this task

Note: If the “Stale NFS file handle” message was displayed after a client IP change, refer to “Working with NFS clients that fail to mount NFS shares after a client IP change” on page 263.

Because of errors or conditions related to this file module, the file module disconnected itself from the file system that was shared with the other nodes. All of the file descriptors that were opened to the file system through this file module have become "stale", as indicated by command output or a Stale NFS file handle error message, and cannot access their corresponding files. When this occurs, all affected file modules enter an unhealthy state, and a CIM similar to the following is sent to the alert log:

```
GPFS Error - check stale file handle failed with error code 1:  
see stale file handle on /ibm/gpfs0 on file module: mgmt001st001
```

If you receive the error above, complete the following steps:

Procedure

1. Open the CLI in the active management node using root privileges, and issue **/usr/sbin/exportfs -a** to flush the NFS cache in each file module. Verify that the state of each affected file module is healthy and that no new “Stale NFS file handle” CIMs are displayed in the alert log after you resume the file module. If the problem persists, continue with the following steps.
2. Review the event log to identify the affected file system and all of the nodes where the file system displays the state “Stale NFS file handle”.
3. Suspend each affected file module.
4. Reboot each affected file module.
5. Resume each affected file module.

6. Verify that the state of each affected file module is healthy after you resume the file module and that no new “Stale NFS file handle” CIMs appear in the alert log.

Recovering the GPFS

1. From the root, enter `lsnode -r`. This displays GPFS and CTDB status.
2. Check for the GPFS that are in stale mount by running `lsmount` or `mm1smount gpfs1 -L`.
3. Enter `onnode all df`. This displays `df: 'ibm/gpfsX': Stale NFS handle` where X is the gpfs number such as `gpfs0`.

To recover gpfs, follow the procedure below:

1. Enter `lsnode -r`
2. Enter `ssh<node>`
3. Enter `initnode -r - n <node>` to reboot the node.
4. Enter `exit`.

Ping the node or check uptime or wait for the node to come up.

1. `lsnode -r`
2. `resumenode <node>`

Perform the above procedure for all the nodes in the cluster.

File module-related issues

This section covers the recovery procedures related to file module issues.

Restoring System x firmware (BIOS) settings

During critical repair actions such as the replacement of a system planar in an IBM Storwize V7000 Unified file module, you might have to reset the System x firmware.

Before you begin

The firmware and software code package for the Storwize V7000 Unified microcode can automatically configure the default settings for the System x firmware to the required Storwize V7000 Unified settings. However, to enable the automatic configuration, you must reset the System x firmware from its current state to the default configuration.

About this task

Use the following procedure to set the System x firmware to the default state and start the automatic Storwize V7000 Unified configuration.

Procedure

1. Attach the USB and VGA cable from the KVM switch to the video and USB port of the Storwize V7000 Unified file module that is to be reset.
2. Open the KVM unit in the base rack.
3. Turn on the KVM unit if it is off.
4. Press **PrtSc** to display the KVM selector screen.
5. Scroll down to select the USB cable, then press **Enter**.

6. Turn on the affected file module.
7. From the IBM System x Server Firmware screen, press **F1** to set up the firmware.

A few seconds after the IBM System x Server Firmware screen is displayed, F1 and other options are displayed at the bottom of the screen:

 - F1 - Setup
 - F2 - Diagnostics
 - F12 - Select Boot Device
8. From the System Configuration and Boot Management screen, scroll down to click **Load Default Settings**, and then press **Enter**.

The screen goes blank for a few seconds and then returns to the System Configuration and Boot Management screen.
9. Click **Save**.
10. A window displays a prompt to ask to reset the IMM now. Select **Y**.
11. Press **ESC** twice to return to the System Configuration and Boot Management screen.
12. Scroll down to click **Boot Manager**, and then press **Enter**.
13. Scroll down to click **Add Boot Option**, and then press **Enter**.
14. Scroll down to click **Legacy Only**, and then press **Enter**.

The option is not visible until you scroll down. Selecting the option removes it from the list of available options.
15. Press **ESC** twice to return to the System Configuration and Boot Management screen.
16. Scroll down to click **Save Settings**, and then press **Enter**.
17. Press **ESC** or click **Exit Setup**, and then press **Enter**.
18. When prompted, click **Y** to exit the setup menu.

The system now reboots. During the reboot, the Storwize V7000 Unified code automatically modifies the configuration of the System x firmware (BIOS) to change the default settings to the required settings.

Recovering from file systems that are offline after the volumes came back online

The problem that caused the file volumes to go offline long enough to cause the file systems to become unmounted may have caused disks to be marked as failed which will prevent the file system from being automatically mounting after the volume comes back online.

About this task

The file systems will usually be automatically mounted as soon as the file volumes come back online. However, if GPFS experienced IO errors as the volume went offline then it may mark the disks as failed.

If this happens then the automatic mounting of the file system will not work and the disks must be started using the **Start All Disks** action against the file system in the management GUI before they are mounted using the management GUI.

Procedure

To re mount any file system that was not automatically remounted when the file volumes came back online:

1. Go to the **files > file** systems page in the management GUI to see if any file systems are offline.
2. Hover over the Status indicator of any file system which does not have an OK status.
3. If **The <pool name> file system pool contains failing disks** is displayed then select the action to Start All Disks used by this file system.
4. If hovering over the Status indicator of the file system shows that the file system is not mounted on any node, or on one of the nodes, then select the action to mount the file system.

Results

If the health status indicator is still red after completing all recovery procedures then refer to “Health status and recovery” on page 24 to help you return the health status indicator back to green.

Recovering from a multipath event

Use this procedure to recover a node from a **multipathd** failure.

Before you begin

Use this procedure after completing the procedure in Fibre Channel connectivity between file modules and control enclosure.

The Storwize V7000 Unified system can experience problems where the **multipathd** failures occur. If the paths are not automatically restored, a system reboot can recover the paths.

Important: Perform this procedure against the passive management node only.

Procedure

1. Verify that the node that the **multipathd** event occurred against is the passive management node. If the node that experiences the **multipathd** problems is the active node, then perform the management node failover procedure. See “Performing management node role failover on a “good” system” on page 150.
2. Reboot the file module. See “Rebooting a file module” on page 57.

Diagnosing a multipath event

The **multipath -ll** command verifies that all storage devices are either active or not active.

The following output shows that all storage devices are active.

```
[root@yourmachine.mgmt001st001 ~]# multipath -ll
array1_sas_89360007 (360001ff070e9c00000000001989360007) fm-0 IBM,2073-720
[size=3.1T][features=1 queue_if_no_path][hw_handler=0][rw]
  \_ round-robin 0 [prio=50][active]
  \_ 6:0:0:0 sdb 8:16 [active][ready]
  \_ round-robin 0 [prio=10][enabled]
  \_ 8:0:0:0 sdg 8:96 [active][ready]
array1_sas_89380009 (360001ff070e9c00000000001b89380009) fm-1 IBM,2073-720
[size=3.1T][features=1 queue_if_no_path][hw_handler=0][rw]
```

```

\_ round-robin 0 [prio=50][active]
\_ 6:0:0:2 sdd 8:48 [active][ready]
\_ round-robin 0 [prio=10][enabled]
\_ 8:0:0:2 sdi 8:128 [active][ready]

```

The following output shows that the storage devices are not active.

```

[root@kd271f6.mgmt002st001 ~]# multipath -ll
mpathq (360050768029180b060000000000000007) dm-8 IBM,2145
size=2.5G features='1 queue_if_no_path' hwhandler='0' wp=rw
| ~- 5:0:0:7 sdr 65:16 failed ready running
^- 6:0:0:7 sdi 8:128 failed ready running
mpathp (360050768029180b06000000000000005) dm-3 IBM,2145
size=2.5G features='1 queue_if_no_path' hwhandler='0' wp=rw
| ~- 5:0:0:5 sdp 8:240 failed ready running
^- 6:0:0:5 sdg 8:96 failed ready running

```

The output [active][ready] identifies an active device. The output failed ready running identifies a device that is not active.

Recovering from an NFSD service error

Use this procedure to recover from an NFSD service error.

About this task

This recovery procedure starts the NFSD when it is down.

Procedure

1. Log in as root.
2. Issue the **service nfsd start** command.
3. If the problem persists, restart the node.
4. If the restart action does not resolve the issue, contact the next level of support.

Recovering from an SCM error

Use this procedure to recover from a service configuration management (SCM) error.

About this task

Complete the following procedure if output from the **lshhealth -r** CLI command contains a line similar to the following:

```
SCM ERROR SCM system has found some errors
```

Note: This procedure involves analyzing various logs depending on the errors displayed by the initial SCM error log.

Procedure

1. If an error is displayed, run the **lshhealth -i SCM** command to show the details of the component with the error. SCM is a component, that monitors other components. Ensure to note the details shown by the **Message** and **Value** columns.
2. To know the error code, run the **lslog** command or open the graphical user interface (GUI) Eventlog page.

3. Compare the results returned by `lslog` command with `lshealth -i SCM` command. This procedure helps you in mapping the error. If you are not able to link the `lshealth -i SCM` output with the `lslog` output, continue to the next step.
4. Open the CNSCM log located at `/var/log/cnlog/cnscm` for the file module that reported the error.
5. Review the error entries around the listed time stamp and then check the log for issues that seem related that occurred before the listed time stamp. For example, you might find GPFS-related issues appearing earlier and later, too.
6. Review the log entries and try to match the entries with the `lslog` output. If you are not able to match the entries, continue to the next step.
7. Based on the log entries, check the appropriate corresponding log. If the issue appeared to be related to GPFS, for example, you could look for the root cause in `/var/adm/ras/mmfs.log`.
8. If the log entries do not help resolve the error, contact the next level of support.

Recovering from an httpd service error

Use this procedure to recover from an httpd service error when the service is reported as unhealthy or off.

About this task

Procedure

To fix the httpd error, perform the following steps:

1. Attempt to start the http service manually.
 - a. Log in as root.
 - b. Issue the `service http start` command.
2. When you complete the service action, refer to “Health status and recovery” on page 24.

Recovering from an sshd_data service error

Use this procedure to recover from an sshd_data service error.

About this task

This recovery procedure starts the sshd_data when it is down.

Procedure

1. Log in as root.
2. Issue the service `sshd_data start` command.
3. If the problem persists, restart the node.
4. If the restart action does not resolve the issue, contact the next level of support.

Recovering from an sshd_int service error

Use this procedure to recover from an sshd_int service error.

About this task

This recovery procedure starts the sshd_int when it is down.

Procedure

1. Log in as root.
2. Issue the service **sshd_int start** command.
3. If the problem persists, restart the node.
4. If the restart action does not resolve the issue, contact the next level of support.

Recovering from an sshd_mgmt service error

Use this procedure to recover from an sshd_mgmt service error.

About this task

This recovery procedure starts the sshd_mgmt when it is down.

Procedure

1. Log in as root.
2. Issue the service **sshd_mgmt start** command.
3. If the problem persists, restart the node.
4. If the restart action does not resolve the issue, contact the next level of support.

Recovering from an sshd_service service error

Use this procedure to recover from an sshd_service service error.

About this task

This recovery procedure starts the sshd_service when it is down.

Procedure

1. Log in as root.
2. Issue the service **sshd_service start** command.
3. If the problem persists, restart the node.
4. If the restart action does not resolve the issue, contact the next level of support.

Control enclosure-related issues

This section covers the recovery procedures that involve control enclosure issues.

Recovering when file volumes come back online

Use this procedure to recover a file system after all the file volumes are back online after a repair or recovery action.

About this task

Each fix procedure that brings the file volumes back online also suggests that you run this procedure. This procedure checks that the file systems have also come back online.

Perform the following steps to check that the file systems are back online after their file volumes are back online following an outage.

Procedure

1. In the management GUI, check that all volumes are back online.
2. Go to **Monitoring > Events** and click the **Block** tab.
3. Run any **Next recommended action**.
4. When all volumes are back online, go to **Filesystems** in the management GUI.
5. If any file systems are not online, recover them by using the recover a GPFS file system procedure. See “Recovering a GPFS file system” on page 161.
6. If there are file systems that have not come back online, go to **Monitoring > Events** and click the **File** tab to fix any errors.
7. If there are any stale NFS handle errors for the offline file systems, follow the “Working with file modules that report a stale NFS file handle” on page 264.

Recovering when a file volume does not come back online

An offline volume can normally be fixed by performing the fix procedure for the event in the management GUI.

About this task

Procedure

To run the fix procedures, perform the following steps:

1. Log in to the Storwize V7000 Unified management GUI.
2. Go to **Monitoring > Events** and click the **Block** tab.
3. Run any **Next recommended action**.

Results

If the fix procedures do not bring back a file system volume online, contact your service provider for assistance.

Recovering from offline compressed volumes

Recovering from offline compressed volumes. Getting them back online.

When a Storwize V7000 storage pool (MDisk Group) runs out of space:

- Any volume that tries to expand (such as new data being written to a compressed volume) is taken offline.
- Taking a file volume offline takes the Network Shared Disk (NSD) offline because each NSD is made from one file volume.
- Taking meta data (NSD) offline takes the whole file system offline (but putting meta data in a compressed volume is not allowed).
- The file system is unmounted if it is offline for more than 30 seconds.
- This is different from the file system filling up, which causes the file system to enter read only mode.

There are two options to recover from this:

- Increase the storage pool capacity.
- Free the unusable blocks in the compressed volumes.

Table 42. Recovering from offline compressed volumes.

| Scenario | Recovery Procedure | Who does it? |
|--|---|---|
| Storage pool warning (80% full) | Provision more storage to pool | You You (Storwize V7000 fix procedure) |
| Compression ratio wrong (file system still online) | Increase the storage to pool size Or Free the unusable blocks in the compressed volumes. | You (with help from this page) You (with help from IBM Remote Technical support) |
| Storage pool full (file system offline) | Provision more storage to pool | You (Storwize V7000 fix procedure) |
| Storage pool full (file system offline) No available storage | Borrow hot spare disks, bring file system online, free up space, shrink filesystem, return hot spare disks | You (with help fro IBM Remote Technical Support) |

Increasing the Storage pool capacity

To increase storage pool capacity, add more RAID arrays to the storage pool using the management GUI.

Storage can be taken or borrowed from the block allocation to resolve out of space conditions in the file allocation. Point in time block copies are a good candidate for deletion.

Storwize V7000 Unified can virtualize external block storage controllers. If spare capacity is available on other block storage controllers then you can virtualize those and add the mdisks to the volume storage pool.

Free the unusable blocks in the compressed volumes

If you cannot increase the storage pool capacity then contact IBM Remote Technical Support to help you.

Recovering from a 1001 error code

A 1001 error code indicates that the Storwize V7000 control enclosure has automatically performed a recovery. The control enclosure CLI is now restricted to make sure that there are no more block storage configuration changes until IBM Remote Technical Support has checked that it is safe for block storage configuration changes to be allowed again.

About this task

The file volumes presented by the control enclosure for GPFS to use as disks for file systems may have been offline long enough to cause the file systems to be unmounted. The file systems will usually be automatically mounted as soon as the file volumes come back online after the control enclosure recovery. You can immediately remount any remaining unmounted file systems without waiting for IBM support to tell you that it is safe for you to re-enable the control enclosure CLI.

Note: The management GUI can become very slow when the control enclosure CLI is restricted, so the following procedure shows how to use the management CLI to check if the file systems are mounted. However, it is better to use the management GUI if that is working fine.

Procedure

To check if the file systems were automatically mounted following the recovery of the control enclosure:

1. Log on to the management CLI with your administrator credentials. For example:

```
ssh admin@<management_IP address>
```

2. Use the `lsnode -r` CLI command to check the status of CTDB and GPFS on each file module. For example:

```
lsnode -r
```

3. Use the `lsmount` CLI command to check if all of your file systems that should be mounted are mounted. For example:

```
[kd52v6h.ibm]$ lsmount
File system Mount status Last update
gpfs0      not mounted 10/17/12 10:44 AM
gpfs1      not mounted 10/17/12 10:44 AM
gpfs2      not mounted 10/17/12 10:44 AM
EFSSG1000I The command completed successfully.
```

4. If all of the required file systems are mounted on both nodes then there is no need to continue going through this procedure because network users should be able to access files on GPFS. Otherwise use the `lsdisk` CLI command to check if all of the disks are available. For example:

```
[kd52v6h.ibm]$ lsdisk
Name File system Failure group Type Pool Status Availability Timestamp
Block properties
IFS1350385068630 gpfs0 1 metadataOnly system ready up 10/17/12 10:27 AM
IFS1350385068630,io_grp0,,easytier,6005076802AD8022780000000000000
IFS1350385068806 gpfs0 1 metadataOnly system ready up 10/17/12 10:27 AM
IFS1350385068806,io_grp0,,easytier,6005076802AD8022780000000000001
IFS1350385089739 gpfs0 2 metadataOnly system ready up 10/17/12 10:27 AM
IFS1350385089739,io_grp0,,easytier,6005076802AD80227800000000000002
IFS1350385089889 gpfs0 2 metadataOnly system ready up 10/17/12 10:27 AM
IFS1350385089889,io_grp0,,easytier,6005076802AD80227800000000000003
IFS1350385108175 gpfs0 0 dataOnly system ready up 10/17/12 10:27 AM
IFS1350385108175,io_grp0,,easytier,6005076802AD8022780000000000004
```

5. If all disks are up then you can use the `mountfs` CLI command to mount each file system that is not mounted. For example

```
mountfs <file system name>
```

6. Otherwise if none of the disks are up or some of the disks are not up then use the `lsdisk` CLI command to check if all of your file volumes that should be online are online. Note that the names of file volumes are the same as the names of the disks. For example

```
[kd52v6h.ibm]$ lsvdisk
id name IO_group_id IO_group_name status mdisk_grp_id mdisk_grp_name capacity
type
FC_id FC_name RC_id RC_name vdisk_UID fc_map_count copy_count fast_write_state
0 IFS1350385068630 0 io_grp0 online 1 metal 100.00GB striped
6005076802AD80227800000000000000 0 1 not_empty
1 IFS1350385068806 0 io_grp0 online 1 metal 100.00GB striped
6005076802AD802278000000000000001 0 1 not_empty
2 IFS1350385089739 0 io_grp0 online 2 meta2 100.00GB striped
6005076802AD802278000000000000002 0 1 not_empty
3 IFS1350385089889 0 io_grp0 online 2 meta2 100.00GB striped
6005076802AD802278000000000000003 0 1 not_empty
4 IFS1350385108175 0 io_grp0 online 0 mdiskgrp0 341.00GB striped
6005076802AD802278000000000000004 0 1 not_empty
```

7. If any file volumes are offline then refer to Recovering when a file volume does not come back online.

8. If none of the disks are up but all file volumes are online then the multi pathing driver in the file modules may have failed and the best way to recover is to reboot the file modules one after the other using the procedure below.
9. If some of the disks are not up but the volumes are online then restart all disks used by a file system before you continue to mount it.
10. Use the `chdisk` CLI command to restart all disks used by the file system. For example
`chdisk <comma separated list of disk names> --start`
11. Use the `mountfs` CLI command to mount the file system. For example:
`mountfs <file system name>`

What to do next

Rebooting the file modules if none of the disks are up but all file volumes are online:

To reboot the file modules if the multi-pathing driver may have failed following a recovery of the control enclosure:

1. Identify the passive and the active management nodes from the Description column in the output from the CLI command:
`lsnode -r`
 Reboot the file module that is the passive management node using the CLI command:
`stopcluster -node <node name> -reboot`
2. Wait until both nodes show **OK** in the Connection status column of the output from the CLI command:
`lsnode -r`
3. Resume the file module back into the cluster using the CLI command:
`resumefile <node name>`
4. Reboot the file module that is the active management node using the CLI command. The active management node fails over to the file module that you rebooted first.
`stopcluster -node <node name> -reboot`
5. Log back on to the Storwize V7000 Unified CLI. Wait until both nodes show **OK** in the Connection status column of the output from the CLI command:
`lsnode -r`
6. Resume the file module back into the cluster using the CLI command:
`resumefile <node name>`
7. Then wait for GPFS to be active on both file modules in the output of the CLI command:
`lsnode -r`
8. Check that the file systems are mounted by using the `lsmount -r` management CLI command:
`lsmount -r`
9. See Checking the GPFS file system mount on each file module if any file systems are not mounted.

Note that the management GUI can become very slow when the Storwize V7000 CLI is restricted. When you log on to the management GUI, it issues a warning that the Storwize V7000 CLI is restricted. The management GUI runs the fix

procedure to direct you to send logs to IBM. The fix procedure directs you back to this procedure to make the file systems accessible again.

To collect the Storwize V7000 logs, select the **Collect Logs** option from the navigation in the service assistant. Choose the **With statesave** option.

The fix procedure re-enables the control enclosure CLI, provided that IBM support approved of this procedure.

After completing this procedure the health status indicator could still be red because the Fibre Channel links may not have sent an event showing that they have recovered. Refer to Connectivity issues to help you see if this is the case and refer to Health status and recovery to help you return the health status indicator back to green.

Restoring data

This section covers the recovery procedures that relate to restoring data.

Restoring asynchronous data

Recovering a file system with asynchronous replication requires that you configure and start a replication relationship from the target site to the source site.

Before you begin

After the source site (site A) has failed, set the target site (Site B) as the new source site and replicate back to Site A. To restore asynchronous data, perform the following steps:

Procedure

1. Where the previous replication relationship was Site A replicating to Site B, configure the asynchronous replication by reversing the source and target site information. Site B replicates to Site A. See “Configuring asynchronous replication” and transpose the source and target information.
2. Start the replication that was configured in step 1 by using the **startrepl -fullsync** CLI command. See “Starting and stopping asynchronous replication” for more information.
3. If the amount of data that is to be replicated back to Site A is large, multiple replications from Site B to Site A might be required. Multiple replications are required until modifications to Site B can be suspended to perform a final replication to Site A to enable Site A to synch up.

Note: Do not use the **fullsync** option for these incremental replications.

4. After you verify that the data on Site A has been replicated accurately, you can reconfigure Site A as the primary site. Remove any replication tasks from Site B to Site A by using the **rmtask** CLI command.

Restoring Tivoli Storage Manager data

The Storwize V7000 Unified system contains a Tivoli Storage Manager client that works with your Tivoli Storage Manager server system to perform high-speed data backup and recovery operations.

Before you begin

Before restoring a file system, determine whether a backup is running and when backups were completed. To restore the data, perform the following steps:

Procedure

1. Determine whether a backup is running and when backups were completed by running the **lsbackup** CLI command. Specify the file system.

For example, the command to display the gpfs0 file system backup listing shows the output in the following format:
lsbackup gpfs0 Filesystem Date
Message gpfs0 20.01.2010 02:00:00.000 G0300IEFSSG0300I The filesystem
gpfs0 backup started. gpfs0 19.01.2010 06:10:00.123 G0702IEFSSG0702I The
filesystem gpfs0 backup was done successfully. gpfs0 15.01.2010
02:00:00.000 G0300IEFSSG0300I The filesystem gpfs0 backup started.

2. Restore the backup by using the **startrestore** CLI command. Specify a file system name pattern.

You cannot restore two file systems at the same time; therefore, the file pattern cannot match more than one file system name.

Use the **-t** option to specify a date and time in the format "dd.MM.yyyyHH:mm:ss.SSS" to restore files as they existed at that time. If a time is not specified, the most recently backed up versions are restored. For example, to restore the /ibm/gpfs0/temp/* file pattern to its backed up state as of January 19, 2010 at 12:45 PM, enter the following command:

```
# startrestore "/ibm/gpfs0/temp/*" -t "19.01.2010 12:45:00.000"
```

See the **startrestore** CLI command for additional command information, default options, and file pattern examples.

Attention: The **-R** option overwrites files and has the potential to overwrite newer files with older data.

3. Use the **lsbackupfs** CLI command to determine whether a restore is running. The **Message** field displays RESTORE_RUNNING if a restore is running on a file system.

4. Monitor the progress of the restore process by using the **QUERY SESSION** command in the Tivoli Storage Manager administrative CLI client.

Run this command twice and compare the values in the Bytes Sent column of the output. Incremental values indicate that the process is in progress; whereas, identical values indicate that the restore process has stopped.

Note: The following error message can occur while restoring millions of files:
ANS1030E The operating system refused a TSM request for memory
allocation. 2010-07-09 15:51:54-05:00 dsmc return code: 12

What to do next

If the file system is managed by Tivoli Storage Manager for Space Management, break down the restore into smaller file patterns or subdirectories that contain fewer files.

If the file system is not managed by Tivoli Storage Manager for Space Management, try to force a no-query-restore (NQR) by altering the path that is specified for the restore. To do this action, include all files by putting a wildcard ("*") after the file system path:

```
# startrestore "ibm/gpfs0/*"
```


This example attempts a no query restore, which minimizes memory issues with the Tivoli Storage Manager client because the Tivoli Storage Manager server does the optimization of the file list. If you are still unable to restore a larger number of files at the same time, break down the restore into smaller file patterns or subdirectories that contain fewer files.

Upgrade recovery

This section covers the recovery procedures that relate to upgrade.

Error codes and recommendations when running the `applysoftware` command

If any errors are posted after you issue the `applysoftware` command, see Table 43 and take the described course of action. Follow these guidelines:

1. Follow the actions in the order presented.
2. After each recommended fix, restart the upgrade by issuing the `applysoftware` command again. If the action fails, try the next recommended action.
3. If the recommended actions fail to resolve the issue, call the IBM Support Center.

Table 43. Upgrade error codes from using the `applysoftware` command and recommended actions

| Error Code | The <code>applysoftware</code> command explanation | Action |
|------------|---|--|
| EFSSG1000I | The command completed successfully. | None. |
| EFSSG4100 | The command completed successfully. | None. |
| EFSSG4101 | The required parameter was not specified. | Check the command and verify that the parameters are entered correctly. |
| EFSSG4101A | The <code>applysoftware</code> command returned required parameter not specified. | |
| EFSSG4102 | The software package does not exist. | Verify that the file actually exists where specified. Also verify that the command is passing the correct location parameters. |
| EFSSG4102A | The <code>applysoftware</code> command returned software package does not exist | |
| EFSSG4103 | The software package is not valid. | The package might be corrupt. If this problem persists, download a new package and try again. |
| EFSSG4103A | The <code>applysoftware</code> command returned invalid software package return code. | |
| EFSSG4104 | An unexpected return code. | Call your next level of support. |

Table 43. Upgrade error codes from using the **applysoftware** command and recommended actions (continued)

| Error Code | The applysoftware command explanation | Action |
|------------|---|---|
| EFSSG4105 | Unable to mount the USB flash drive. | Run <code>umount /media/usb</code> , then remove the USB flash drive. Reinsert the USB flash drive. If the error persists, remove the USB flash drive and reboot. After the system reboots, reinsert the USB flash drive. |
| EFSSG4105C | The applysoftware command returned unable to mount USB. | |
| EFSSG4106A | The applysoftware command returned that there is insufficient system file system space. | |
| EFSSG4153 | The required parameter was not specified. | Verify that the file actually exists where specified. Also verify that the command is passing the correct location parameters. |
| EFSSG4154 | You must start on primary management node <code>mgmt001st001</code> . | Switch to the other node and try the command again. |
| EFSSG4154A | The applysoftware returned must start on primary management node <code>mgmt001st001</code> . | |
| EFSSG4155 | Unable to mount USB flash drive. | Back up to a USB flash drive. Enter <code># backupmanagementnode --unmount /media/usb</code> . Remove the USB flash drive and insert again. If the error persists, remove the USB flash drive and reboot. When the system is running, insert the USB flash drive again. |
| EFSSG4155I | The applysoftware command returned upgrade is already running. | |
| EFSSG4156 | The specified International Organization for Standardization (ISO) does not exist. | Verify that the file actually exists where specified. Also verify that the command is passing the correct location parameters. |
| EFSSG4156A | The applysoftware command returned the specified ISO does not exist. | |

Table 43. Upgrade error codes from using the **applysoftware** command and recommended actions (continued)

| Error Code | The applysoftware command explanation | Action |
|------------|--|--|
| EFSSG4157 | The specific upgrade International Organization for Standardization (ISO) content is not valid. | The package might be corrupt. If this problem persists, download a new package and try again. |
| EFSSG4157I | The applysoftware command returned the specific upgrade ISO invalid content. | |
| EFSSG4158 | The specific upgrade cannot be installed over the current version. | Check the upgrade documentation and verify that the level you are coming from is compatible with the level you are going to. If the upgrade level is not compatible, download the correct level and try again. If the upgrade level is compatible and the error persists, call the IBM Support Center. |
| EFSSG4158I | The applysoftware command returned the specific upgrade cannot be installed over the current version. | |
| EFSSG4159 | The system is in an unhealthy state and the upgrade cannot start. | See Chapter 3, "Getting started troubleshooting," on page 9. Determine if the system has issues. |
| EFSSG4159I | The applysoftware command returned that the system is in an unhealthy state and upgrade cannot start. | |
| EFSSG4160 | The system has insufficient file system space. | At least 3 GB of space is required. Remove unneeded files from the /var file system. |
| EFSSA0201C | The license agreement has not been accepted. | |

General upgrade error codes and recommended actions

If any errors are posted during the upgrade process, see Table 44 on page 280 and take the described course of action. If the error you see is not listed in this table, call the IBM Support Center. Follow these guidelines:

1. Follow the actions in the order presented.
2. After each recommended fix, restart the upgrade by issuing the **applysoftware** command again. If the action fails, try the next recommended action.
3. If the recommended actions fail to resolve the issue, call the IBM Support Center.

Table 44. Upgrade error codes and recommended actions

| Error Code | Explanation | Action |
|------------|---|--|
| 019A | Yum update failed. | Contact IBM Remote Technical Support. |
| 019B | Unable to remove StartBackupTSM task. | <ol style="list-style-type: none"> 1. Check to see if management service is running on active node. If it is not, use startmgtsrv to start. 2. Contact IBM Remote Technical Support. |
| 019C | Unable to determine active management node. | <ol style="list-style-type: none"> 1. Check to see if management service is running on active node. If it is not use startmgtsrv to start. 2. Contact IBM Remote Technical Support. |
| 019D | Check the system health. | <ol style="list-style-type: none"> 1. Use lnode to determine what this node is showing unhealthy. (CTDB or GPFS). Possibly reboot unhealthy node and wait for node to come back up. Then check health of node with lnode. 2. Contact IBM Remote Technical Support. |
| 019E | Internal error - cluster or node not provided | Contact IBM Remote Technical Support. |
| 019F | CIM restart failed. | Contact IBM Remote Technical Support. |
| 01A0 | Failed to reboot. | <p>Determine the cause of the failed reboot:</p> <ol style="list-style-type: none"> 1. Check console of system if able. See if the system is hung in BIOS or during boot. 2. Check cabling of system. 3. Check light path diagnostic for error indications. . 4. Reboot the system from console and restart upgrade. 5. Contact IBM Remote Technical Support. |
| 01A1 | Internal upgrade error. | Contact IBM Remote Technical Support. |
| 01A3 | Unable to uninstall CNCSM callbacks. | Contact IBM Remote Technical Support. |
| 01A4 | Unable to stop backup jobs. | <ol style="list-style-type: none"> 1. Check the status of the backups by typing lsjobstatus -j backup. 2. Attempt to stop backups by typing stopbackup --all. 3. Contact IBM Remote Technical Support. |

Table 44. Upgrade error codes and recommended actions (continued)

| Error Code | Explanation | Action |
|------------|--|---|
| 01A5 | Backup cron jobs are running. | <ol style="list-style-type: none"> 1. Check the condition of tasks by typing <code>ltask -t cron</code>. 2. Attempt to remove the backup by typing <code>rmtask StartBackupTSM</code>. 3. Contact IBM Remote Technical Support. |
| 01A6 | Unable to install CNCSM callbacks. | Contact IBM Remote Technical Support. |
| 01A7 | Internal vital product data (VPD) error. | Contact IBM Remote Technical Support. |
| 01A8 | Check the health of management service. | <ol style="list-style-type: none"> 1. Attempt to start the management service with <code>startmgtsrv</code> on active management node 2. Contact IBM Remote Technical Support. |
| 01A9 | Unable to stop performance collection daemon. | Contact IBM Remote Technical Support. |
| 01AB | Internal upgrade error in <code>node_setup_system</code> . | Contact IBM Remote Technical Support. |
| 01B1 | Management node replication failed. | <ol style="list-style-type: none"> 1. Follow the replication recovery procedure. See Resolving issues reported by <code>lshealth</code> for resolving the management node replication failure. 2. Contact IBM Remote Technical Support. |
| 01B2 | Unable to start performance collection daemon. | Contact IBM Remote Technical Support. |
| 01B3 | Failed to copy upgrade package to Storwize V7000. | This could be caused by a number of issues. Check Monitoring > Events under both the block tab and the file tab on the management GUI for an event that could have caused this error and follow the recommended action. If there is no obvious event that could have caused this error, refer to "Ethernet connectivity from file modules to the control enclosure" on page 30. |
| 01B4 | Failed to start upgrade on Storwize V7000 with the <code>applysoftware</code> command. | This could be caused by a number of issues. Check Monitoring > Events under both the block tab and the file tab on the management GUI for an event that could have caused this error and follow the recommended action. If there is no obvious event that could have caused this error, refer to "Ethernet connectivity from file modules to the control enclosure" on page 30. |

Table 44. Upgrade error codes and recommended actions (continued)

| Error Code | Explanation | Action |
|------------|---|---|
| 01B5 | Storwize V7000 multipaths are unhealthy. | Check the Fibre Channel connections to the system. Reseat Fibre Channel cables. For more information, see Fibre Channel connectivity between file modules and control enclosure. |
| 01B6 | Storwize V7000 vdisks are unhealthy as indicated by using the lsvdisk command. | See Chapter 5, "Control enclosure," on page 167. |
| 01B7 | Failed to query status of Storwize V7000 upgrade by using the svcinfolsoftwareupgradestatus command. | This could be caused by a number of issues. Check Monitoring > Events under both the block tab and the file tab on the management GUI for an event that could have caused this error and follow the recommended action. If there is no obvious event that could have caused this error, refer to "Ethernet connectivity from file modules to the control enclosure" on page 30. |
| 01B8 | Failed to query status of Storwize V7000 nodes by using the svcinfolsnode command. | See Chapter 5, "Control enclosure," on page 167. |
| 01B9 | Failed to check the Storwize V7000 version. | This could be caused by a number of issues. Check Monitoring > Events under both the block tab and the file tab on the management GUI for an event that could have caused this error and follow the recommended action. If there is no obvious event that could have caused this error, refer to "Ethernet connectivity from file modules to the control enclosure" on page 30. |
| 01BA | Unable to verify the correct software version. | <ol style="list-style-type: none"> 1. Check the health of the storage controllers. 2. Contact IBM Remote Technical Support. |
| 01BC | Check the health of storage controllers. | Contact IBM Remote Technical Support. |
| 01BD | Unable to update software repository. | <ol style="list-style-type: none"> 1. Ensure that the system is not under a heavy load. Restart the upgrade. 2. Contact IBM Remote Technical Support. |
| 01BE | Unable to distribute upgrade callbacks. | <ol style="list-style-type: none"> 1. Check on health of the cluster using lshhealth. 2. Contact IBM Remote Technical Support. |

Table 44. Upgrade error codes and recommended actions (continued)

| Error Code | Explanation | Action |
|------------|---|--|
| 01BF | Upgrade callback failed | <ol style="list-style-type: none"> 1. Contact your customer advocate. Upgrade callbacks are custom steps placed on a system before the start of upgrade. 2. Contact IBM Remote Technical Support. |
| 01C0 | Asynchronous replication is running. Stop asynchronous replication and continue with the upgrade. | <ol style="list-style-type: none"> 1. Stop asynchronous replication by typing <code>stoprepl gpfs0 --kill</code>. Asynchronous replication is considered active if in RUNNING or KILLING state. 2. Contact IBM Remote Technical Support. |
| 01C1 | Asynchronous replication failed to stop. Stop asynchronous replication and continue with the upgrade. | <ol style="list-style-type: none"> 1. Stop asynchronous replication by typing <code>stoprepl gpfs0 --kill</code>. Asynchronous replication is considered active if in RUNNING or KILLING state. 2. Contact IBM Remote Technical Support. |
| 01C2 | Failed while checking for current running asynchronous jobs. | <ol style="list-style-type: none"> 1. Attempt to check status of <code>lsrepl</code>. If this command is working restart upgrade. 2. Contact IBM Remote Technical Support. |
| 01C3 | Could not stop CTDB. | Contact IBM Remote Technical Support. |
| 01C4 | Unable to remove callbacks | Contact IBM Remote Technical Support. |
| 01C5 | Could not reinstall Lib_Utils. | Contact IBM Remote Technical Support. |
| 01C6 | Failed while running <code>sonas_update_yum</code> . | Contact IBM Remote Technical Support. |
| 01C7 | Unable to get list of cluster nodes. | Contact IBM Remote Technical Support. |
| 01C8 | Failed while running <code>cnrssconfig</code> . | Contact IBM Remote Technical Support. |
| 01C9 | Unable to install CIM configuration. | Contact IBM Remote Technical Support. |
| 01CA | Unable to get name of cluster. | Contact IBM Remote Technical Support. |
| 01CB | Unable to install GPFS packages. | Contact IBM Remote Technical Support. |
| 01CC | Could not install platform. Upgrade on target system. | Contact IBM Remote Technical Support. |
| 01CD | Unable to mount GPFS file systems. | <ol style="list-style-type: none"> 1. See "Checking the GPFS file system mount on each file module" on page 155 2. Restart upgrade and see if this was a transient issue. 3. Follow SONAS GPFS troubleshooting documentation. 4. Contact IBM Remote Technical Support. |

Table 44. Upgrade error codes and recommended actions (continued)

| Error Code | Explanation | Action |
|------------|---|--|
| 01CE | Unable to update system security. | <ol style="list-style-type: none"> 1. Restart upgrade and see if this was a transient issue. 2. Contact IBM Remote Technical Support. |
| 01CF | Unable to configure node. | <ol style="list-style-type: none"> 1. Pull both power supply cables from subject node. Wait 10 seconds, then plug back in. After the system restarts, try again. 2. Contact IBM Remote Technical Support. |
| 01D0 | Unable to disable call home. | Contact IBM Remote Technical Support. |
| 01D1 | Unable to enable call home. | Contact IBM Remote Technical Support. |
| 01D2 | Failed to stop GPFS. | <ol style="list-style-type: none"> 1. Follow SONAS GPFS troubleshooting documentation. 2. Contact IBM Remote Technical Support. |
| 01D3 | Could not determine if backups are running. | <ol style="list-style-type: none"> 1. Attempt to stop backups. 2. Type <code>lsjobstatus -j backup;echo \$?</code>. If the return code is 0, start the upgrade again. 3. If the return code is any other number, contact IBM Remote Technical Support. |
| 01D5 | Storwize V7000 stalled_non_redundant. | Refer to Storwize V7000 documentation. |
| 01D6 | Storwize V7000 system stalled. | Refer to Storwize V7000 documentation. |
| 01D8 | CTDB cluster is unhealthy. | <ol style="list-style-type: none"> 1. See "Checking CTDB health" on page 153. 2. Use <code>lshhealth</code> or RAS procedures to determine unhealthy components. 3. Contact IBM Remote Technical Support. |
| 01DA | GPFS system is unhealthy. | <ol style="list-style-type: none"> 1. See "Checking the GPFS file system mount on each file module" on page 155. 2. Use <code>lsmnode -r</code> to confirm GPFS is unhealthy. If node GPFS is healthy restart the upgrade. 3. Contact IBM Remote Technical Support. |
| 01DB | Failed to stop performance center. | Contact IBM Remote Technical Support. |
| 01DC | Failed to configure performance center. | Contact IBM Remote Technical Support. |
| 01DD | Failed to start performance center. | Contact IBM Remote Technical Support. |

Table 44. Upgrade error codes and recommended actions (continued)

| Error Code | Explanation | Action |
|------------|---|---|
| 01DE | Unable to communicate with passive management node. | <ol style="list-style-type: none"> 1. Ensure that the active mgmt node can communicate with the passive management node before restarting the upgrade. 2. Contact IBM Remote Technical Support. |
| 01DF | Upgrade must be resumed from the other management node. | Restart upgrade from other management node. This might require that a failover be issued first. |
| 01E0 | HSM upgrade failed. | Contact IBM Remote Technical Support. |
| 01E1 | mmchconfig Failed | Contact IBM Remote Technical Support. |
| 01E2 | mmauth Failed | Contact IBM Remote Technical Support. |
| 01E3 | mmlsfs Failed | Contact IBM Remote Technical Support. |
| 01E3 | mmchfs Failed | Contact IBM Remote Technical Support. |
| 01E4 | Disable HSM failed | Contact IBM Remote Technical Support. |
| 01E5 | Enable HSM failed | Contact IBM Remote Technical Support. |
| 01E7 | Unable to ping node | Verify that the node is powered on and the InfiniBand network is working correctly. |
| 0513 | Management service could not be stopped | Contact IBM Remote Technical Support. |
| 0514 | Database backup failed | Contact IBM Remote Technical Support. |
| 0515 | Database backup failed | Contact IBM Remote Technical Support. |
| 0516 | Database package install failed | Contact IBM Remote Technical Support. |
| 0517 | Database initialization failed | Contact IBM Remote Technical Support. |
| 0518 | Database service not running | Contact IBM Remote Technical Support. |
| 0520 | Database restore failed | Contact IBM Remote Technical Support. |
| 0521 | Database replication suspend or resume error. | Contact IBM Remote Technical Support. |
| 0522 | Unable to clean the CTDB configuration file. | Contact IBM Remote Technical Support. |

Chapter 8. Troubleshooting compressed file systems

To ensure that the capacity demands are not exceeded, the underlying block storage pools that provide the compression mechanism for file systems need to be monitored and maintained.

When a block storage pool that is used for compressed file systems runs out of capacity, any compressed volume using that pool that expands is taken offline. If a volume used by a file system is offline for more than 30 seconds then the file system is unmounted, and all I/O to the file system fails. This behavior is different from file systems. When a file system runs out of capacity, the file system enters read-only mode.

To ensure that capacity demands are met for a compressed file systems, monitor capacity usage for the block storage pools and volumes that provide the underlying compression mechanism for file systems. For details on setting thresholds and monitoring capacity for both the block storage and compressed file systems, see “Monitoring file system compression” on page 292

However, there can be cases where capacity exceeds the demands of the data being compressed and additional capacity needs to be added to the system. The following table provides an overview of typical recovery scenarios that are related to running out of capacity for compressed file systems.

Table 45. Capacity failure scenarios

| Failure Scenario | Recovery Procedure |
|--|--|
| Storage pool warning indicates the pool is at the specified capacity threshold. The default threshold is 80%. | “Recovery procedure: Increase capacity of the storage pool” |
| Estimated compression savings for file system in not achieved. (File system is still online) | One of these options: 1. “Recovery procedure: Increase capacity of the storage pool” 2. Free the unusable blocks in the compressed volumes. Note: Contact IBM Remote Technical Support or your service representative to complete this recovery procedure. |
| Storage pool is full and the file system pool is offline. | “Recovery procedure: Adding additional capacity for offline compressed file systems” on page 289 |
| Storage pool is full and the file system pool is offline, but no additional storage is available to add to the pool. | Contact IBM Remote Technical Support or your service representative. |

Recovery procedure: Increase capacity of the storage pool

If the allocated capacity of the block storage pool exceeds the specified capacity threshold then its compressed volumes can go offline. The default threshold is 80% of capacity; however, the value can be set lower or higher depending on the environment. If a compressed file volume is offline for 30 seconds, the file system is unmounted. Proper monitoring of storage pool thresholds is essential to ensure

capacity consumption is not exceeding expectations. If the used capacity does exceed the specified threshold, you can recover by adding more storage to the block storage pool.

The most important metric to monitor is the physical capacity that is used in the storage pool. Make sure the physical allocation does not exceed the specified threshold. The default threshold is set at 80%. To reduce the current utilization of the used capacity, more physical capacity needs to be added to the storage pool or data needs to be deleted from the file system. To view the current level of utilization for block storage pools that are used for file system compression, select **Files > File Systems** and ensure that the **Storage pools** filter is selected. The management GUI displays all the file systems and their associated storage pools. Select the file system and expand the file system pool to display the block storage pool that is used for that file system. The Capacity column displays the current used capacity for the file and the underlying block storage pools. To view specific thresholds for individual volumes, select the **NSDs** filter to display the block volumes that are used in the file system. To view specific thresholds for individual volumes, right-click a volume and select **Properties**. In the upper right of the Properties panel, an allocation bar is displayed with the current threshold indicated by a red vertical bar.

Add any available MDisks: If an MDisk has already been created but not assigned to a pool, complete these steps:

1. In the management GUI, select **Pools > MDisk by Pools**.
2. Select **Not in pool** to display all the available MDisks that are not currently allocated to a storage pool.
3. Right-click the MDisks that you want to add to the storage pool and select **Add to Pool**.
4. On the **Add to Pool** dialog, select the pool and click **Add to Pool**.
5. Verify that the MDisk was added to the selected pool by expanding the pool and ensuring that the added MDisk is displayed.

Add any available drives: If MDisks have not been configured from available internal drives, you can provision the available drives into existing storage pools by completing these steps:

1. In the management GUI, select **Pools > Internal Storage**.
2. Select **Configure Storage**.
3. On the **Configure Internal Storage** dialog, select **Select a different configuration** and complete the following steps:
 - a. In the **Drive Class** field, select the drive class that is available based on the installed storage on the system.
 - b. In the **Preset** field, select the RAID configuration for the storage you are configuring.
 - c. Select **Optimize for capacity** to configure all available capacity.
 - d. Verify the configuration and click **Next**.
 - e. Click **Expand an existing pool** and select the storage pool that is used for compression.
4. Click **Finish**.

Allocate storage from available external storage: The system supports adding external storage systems to provide additional capacity and virtualization. If your environment has external storage systems, you can increase capacity to the storage pool by completing these steps:

1. In the management GUI, select **Pools > External Storage**.
2. Select the storage system to view a list of MDisks that are currently detected on the external storage system. If there are no MDisks that are displayed, click **Detect MDisks**. If the Storwize V7000 Unified system attached to external storage systems, you can allocate additional LUNs.
3. Right-click an unmanaged MDisk and select **Add to Pool**.
4. On the **Add to Pool** dialog, select the pool and click **Add to Pool**.
5. Verify that the MDisk was added to the selected pool by expanding the pool and ensuring that the added MDisk is displayed.

Recovery procedure: Adding additional capacity for offline compressed file systems

In this situation, the storage pool has run out of capacity. As a result, the file system is unmounted and has gone offline, which makes all I/O to the file system fail.

To recover from this situation, you can either add available MDisks to the pool, or if free MDisks are not available, you can make spare drives available to build a new array (MDisk) to add to the pool. However, because spare drives are automatically used as backup drives when other drives fail on the system, using a spare drive to recover an offline file system can prevent an automated recovery if another drive fails on the system. After the file system is brought back online and capacity deficiencies have been addressed, return the drive to use as a spare or add another drive to replace it as a spare. If you add a new drive, new drives must be added to the system.

Increasing capacity to the storage pool

If MDisks are available to provide extra capacity to the storage pool that the compressed file system uses, you can add MDisks to the pool or create more MDisk (arrays).

Add any available MDisks: If an MDisk has already been created but not assigned to a pool, complete these steps:

1. In the management GUI, select **Pools > MDisk by Pools**.
2. Select **Not in pool** to display all the available MDisks that are not currently allocated to a storage pool.
3. Right-click the MDisks that you want to add to the storage pool and select **Add to Pool**.
4. On the **Add to Pool** dialog, select the pool and click **Add to Pool**.
5. Verify that the MDisk was added to the selected pool by expanding the pool and ensuring that the added MDisk is displayed.

Add any available drives: If MDisks have not been configured from available internal drives, you can provision the available drives into existing storage pools by completing these steps:

1. In the management GUI, select **Pools > Internal Storage**.

2. Select **Configure Storage**.
3. On the **Configure Internal Storage** dialog, select **Select a different configuration** and complete the following steps:
 - a. In the **Drive Class** field, select the drive class that is available based on the installed storage on the system.
 - b. In the **Preset** field, select the RAID configuration for the storage you are configuring.
 - c. Select **Optimize for capacity** to configure all available capacity.
 - d. Verify the configuration and click **Next**.
 - e. Click **Expand an existing pool** and select the storage pool that is used for compression.
4. Click **Finish**.

Using spare drives to add capacity to the storage pool

If drives are not available, you need to make spare drives available to add capacity to the storage pool, bring the file system back online, ensure capacity for the storage pool does not run out again, and return spare drives to the system.

Note: If you are unfamiliar with managing spare goals and spare disks, contact IBM support for guidance. Increasing capacity in this way is meant only as a short term solution to this problem. Further provisioning to permanently resolve capacity constraints can be conducted with the help of IBM service personnel who might recommend that additional drives be added to your system.

To use spare drives to add capacity to the storage pool and bring file systems back online, complete these steps:

1. **Mark a spare drive as a candidate drive:** When block storage is configured on the system, available drives are categorized based on their drive class and drive type. To provide for drive redundancy, some drives are mark as spares, which provide backup drives in the event of a drive failure. Other drives are marked as candidates, which means they can be used as capacity for block storage pools. To mark a spare drive as a candidate and make it available to the block storage pool, complete these steps:
 - a. In the management GUI, select **Pools > Internal Storage**.
 - b. From the list of drives that display, right-click a drive that is marked as a spare drive and select **Mark as... > Candidate**.

Note: The **Use** column displays how a specific drive is used on the system.

- c. Click **OK**.
2. **Expand the storage pool:** After the spare drive has been marked as a candidate drive, you can expand the capacity of the block storage pool that is used for the offline file system.
 - a. In the management GUI, select **Pools > Internal Storage**.
 - b. Select **Configure Storage**.
 - c. On the **Configure Internal Storage** dialog, select **Select a different configuration** and complete the following steps:
 - 1) In the **Drive Class** field, select the drive class of the candidate drive (former spare) that is available based on the installed storage on the system. Verify the correct number of disks is displayed.
 - 2) In the **Preset** field, select the RAID configuration for the storage you are configuring. If you are adding only one disk, the only RAID option is RAID0 which does not provide any data protection.

- 3) Select **Optimize for capacity** to configure all available capacity.
 - 4) Verify the configuration and click **Next**.
 - 5) Click **Expand an existing pool** and select the storage pool that is used for compression.
3. **Check event logs to ensure all underlying volumes are back online.** Before bringing the file system back online ensure that all the errors for both the block volumes and the file system have been resolved by completing these steps:
 - a. In the management GUI, select **Monitoring > Events** and select **Block**.
 - b. Run the fix procedures in the recommended order for all events that are related to the block volume that is used by the file system.
 - c. Select **File** and fix all errors that are related to the offline file systems.
 4. **Bring file systems back online:** After the capacity has been added to the storage pool, bring the file system back online by completing these steps:
 - a. In the management GUI, select **Files > File Systems**.
 - b. Right-click the compressed file system that is offline and select **Mount**. If the file system does not come back online you may need to restart all of the disks that the file system uses Right-click the compressed file system that went offline and select **Start All Disks**.
 5. **Prevent the file system from running out of capacity again:**

First ensure that you have free capacity at least the size of the real capacity of the temporary drive that you are adding.

To decrease the file system capacity, you can remove the disks (NSD) and the corresponding mapping to block volumes to force migration of the data to other NSDs, thus freeing up space on the file system. To remove an NSD, contact IBM Remote Technical Support.
 6. **Return spare drives to the system:** To ensure that drive redundancy is not compromised, spare drives that were used to bring the offline file systems back online need be replaced either by returning the original drive back to its spare use or by adding a new drive to the system. Ensure that the file system capacity has been decreased accordingly before returning the spare drives to the systems. To return the drive back to its spare use, complete these steps:
 - a. In the management GUI, select **Pools > Internal Storage**.
 - b. From the list of drives that display, ensure that no MDisk are associated with the drive. If the drive is associated with MDisk, select **Pools > MDisks by Pool**. Right-click the MDisk and select **Remove from Pool**.
 - c. In the management GUI, select **Pools > Internal Storage**.
 - d. From the list of drives that display, right-click a drive you marked as a candidate in Step 1 and select **Mark as... > Spare** .
 - e. Click **OK**.

To add additional drives to the system, complete these steps:

 - a. Acquire additional drives from IBM or vendor.
 - b. Install drives into available drive slots on the enclosure. See “Installing a hot-swap hard disk drive” on page 115.
 - c. After the drives are available, select **Pools > Internal Storage**.
 - d. From the list of drives that display, right-click the new drive and select **Mark as... > Spare**.

Monitoring file system compression

You can use the management GUI to monitor file and file system pool capacity metrics in a single view by selecting **Monitoring > Capacity and Files > File Systems > Storage pools**.

You can use two views to monitor the capacity usage on the system. Select **Monitoring Capacity** to display a consolidated view of all information needed to monitor capacity-related information on the system. In addition, you can create alerts on capacity where you are notified when a specified capacity threshold has been reached for file system or storage pool capacity. The Capacity View shows system-wide compression savings and thin provisioning efficiency on storage pool level.

The most important metric to monitor is the physical capacity that is used in the storage pool. Make sure the physical allocation does not exceed the specified threshold. The default threshold is set at 80%. To reduce the current utilization of the used capacity, more physical capacity needs to be added to the storage pool or data needs to be deleted from the file system. To view the current level of utilization for block storage pools that are used for file system compression, select **Files > File Systems** and ensure that the **Storage pools** filter is selected. The management GUI displays all the file systems and their associated storage pools. Select the file system and expand the file system pool to display the block storage pool that is used for that file system. The Capacity column displays the current used capacity for the file and the underlying block storage pools. To view specific thresholds for individual volumes, select the **NSDs** filter to display the block volumes that are used in the file system. To view specific thresholds for individual volumes, right-click a volume and select **Properties**. In the upper right of the Properties panel, an allocation bar is displayed with the current threshold indicated by a red vertical bar.

Whenever a threshold is reached and an alert is issued, the system suggests actions that correspond to the specific scenario. If action is not taken and the storage pool reaches 100% utilization, volumes and their related network shared disks (NSDs) can go offline, which causes the file system to go offline. To see an overview of recovery scenarios, go to Chapter 8, "Troubleshooting compressed file systems," on page 287.

Theoretically, the total virtual capacity for all volumes in a pool can exceed the actual physical capacity that is available to the storage pool. For example, an administrator creates a 10 TB file system from a storage pool that has 10 TB of capacity. In this example, one volume is used and is allocated the full 10 TB of capacity to store this data. On average, the data that is stored in this file system has 60% compression savings. After the file system is full with 10 TB of data that gets 60% compression savings, it has actually used only 4 TB of physical capacity from the pool to store the compressed data. To use the remaining 6 TB of unused capacity, virtual capacity can be added for the volumes in the pool.

However, in reality, you need contingency capacity on the storage pool that remains unallocated and available to minimize impact to capacity utilization when data changes affects compression rates. In most cases, data does not have the same compression rate because it is constantly changing over the course of life cycle. Incompressible data or data that does not compress well can be added to a file system, which impacts compression rates. The system default for the contingency threshold at 80% of the physical capacity which provides 20% contingency capacity for the storage pool, which is adequate for most environment. For example, if an

administrator has a storage pool with 10 TB of physical storage and sets the threshold to 80%, only 8 TB out of the physical 10 TB are available in the pool. However, if the data in the pool receives 60% compression savings, the administrator can store approximately 20 TB of uncompressed user data in 8 TB of physical space. In this way, the maximum amount of virtual capacity exceeds the physical capacity for the compressed storage pool. To calculate the recommended virtual capacity, you can use the following equation:

Recommended maximum virtual capacity (in TB) = $(CT * PC) * (1 / (1 - CR))$

Contingency threshold (CT)

0.8 to represent 80% contingency threshold.

Physical capacity in TB (PC)

10 TB physical capacity that is available in the pool.

Compression savings (CR)

0.6 represents 60% compression savings.

File System Capacity Management

Additionally you must also monitor file capacity utilization to ensure that the file system does not reach 100% utilization and run out of capacity. The capacity utilization of a file system issued physical capacity in the compressed pool. The system uses the same threshold and alerting system and suggests corrective actions when thresholds are reached. If based on the original, uncompressed capacity that the system presents to users and applications of the file system.

To free up capacity in a file system, you can either delete files from the file system or increase the current capacity of the storage pool, which can be used to expand the volumes that are related to the NSDs from the unused physical capacity. If corrective action to reduce utilization is not performed before the file system reaches 100% utilization, the file system goes offline and no longer handles read and write requests.

Appendix. Accessibility features for IBM Storwize V7000 Unified

Accessibility features help users who have a disability, such as restricted mobility or limited vision, to use information technology products successfully.

Accessibility features

These are the major accessibility features in Storwize V7000 Unified:

- You can use screen-reader software and a digital speech synthesizer to hear what is displayed on the screen. PDF documents have been tested using Adobe Reader version 7.0. HTML documents have been tested using JAWS version 9.0.
- This product uses standard Windows navigation keys.
- Interfaces are commonly used by screen readers.
- Keys are discernible by touch, but do not activate just by touching them.
- Industry-standard devices, ports, and connectors.
- You can attach alternative input and output devices.

The Storwize V7000 Unified Information Center and its related publications are accessibility-enabled. The accessibility features of the Information Center are described in Viewing information in the information center in the Information Center.

Keyboard navigation

You can use keys or key combinations to perform operations and initiate menu actions that can also be done through mouse actions. You can navigate the Storwize V7000 Unified Information Center from the keyboard by using the shortcut keys for your browser or screen-reader software. See your browser or screen-reader software Help for a list of shortcut keys that it supports.

IBM and accessibility

See the IBM Human Ability and Accessibility Center for more information about the commitment that IBM has to accessibility.

Notices

This information was developed for products and services offered in the U.S.A.

IBM may not offer the products, services, or features discussed in this document in other countries. Consult your local IBM representative for information on the products and services currently available in your area. Any reference to an IBM product, program, or service is not intended to state or imply that only that IBM product, program, or service may be used. Any functionally equivalent product, program, or service that does not infringe any IBM intellectual property right may be used instead. However, it is the user's responsibility to evaluate and verify the operation of any non-IBM product, program, or service.

IBM may have patents or pending patent applications covering subject matter described in this document. The furnishing of this document does not grant you any license to these patents. You can send license inquiries, in writing, to:

*IBM Director of Licensing
IBM Corporation
North Castle Drive
Armonk, NY 10504-1785
U.S.A.*

For license inquiries regarding double-byte character set (DBCS) information, contact the IBM Intellectual Property Department in your country or send inquiries, in writing, to:

*Intellectual Property Licensing
Legal and Intellectual Property Law
IBM Japan, Ltd.
19-21, Nihonbashi-Hakozakicho, Chuo-ku
Tokyo 103-8510, Japan*

The following paragraph does not apply to the United Kingdom or any other country where such provisions are inconsistent with local law:

INTERNATIONAL BUSINESS MACHINES CORPORATION PROVIDES THIS PUBLICATION "AS IS" WITHOUT WARRANTY OF ANY KIND, EITHER EXPRESS OR IMPLIED, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED WARRANTIES OF NON-INFRINGEMENT, MERCHANTABILITY OR FITNESS FOR A PARTICULAR PURPOSE. Some states do not allow disclaimer of express or implied warranties in certain transactions, therefore, this statement may not apply to you.

This information could include technical inaccuracies or typographical errors. Changes are periodically made to the information herein; these changes will be incorporated in new editions of the publication. IBM may make improvements and/or changes in the product(s) and/or the program(s) described in this publication at any time without notice.

Any references in this information to non-IBM Web sites are provided for convenience only and do not in any manner serve as an endorsement of those Web sites. The materials at those Web sites are not part of the materials for this IBM product and use of those Web sites is at your own risk.

IBM may use or distribute any of the information you supply in any way it believes appropriate without incurring any obligation to you.

Licensees of this program who wish to have information about it for the purpose of enabling: (i) the exchange of information between independently created programs and other programs (including this one) and (ii) the mutual use of the information which has been exchanged, should contact:

*IBM Corporation
Almaden Research
650 Harry Road
Bldg 80, D3-304, Department 277
San Jose, CA 95120-6099
U.S.A.*

Such information may be available, subject to appropriate terms and conditions, including in some cases, payment of a fee.

The licensed program described in this document and all licensed material available for it are provided by IBM under terms of the IBM Customer Agreement, IBM International Program License Agreement or any equivalent agreement between us.

Any performance data contained herein was determined in a controlled environment. Therefore, the results obtained in other operating environments may vary significantly. Some measurements may have been made on development-level systems and there is no guarantee that these measurements will be the same on generally available systems. Furthermore, some measurements may have been estimated through extrapolation. Actual results may vary. Users of this document should verify the applicable data for their specific environment.

Information concerning non-IBM products was obtained from the suppliers of those products, their published announcements or other publicly available sources. IBM has not tested those products and cannot confirm the accuracy of performance, compatibility or any other claims related to non-IBM products. Questions on the capabilities of non-IBM products should be addressed to the suppliers of those products.

All statements regarding IBM's future direction or intent are subject to change or withdrawal without notice, and represent goals and objectives only.

All IBM prices shown are IBM's suggested retail prices, are current and are subject to change without notice. Dealer prices may vary.

This information is for planning purposes only. The information herein is subject to change before the products described become available.

This information contains examples of data and reports used in daily business operations. To illustrate them as completely as possible, the examples include the names of individuals, companies, brands, and products. All of these names are fictitious and any similarity to the names and addresses used by an actual business enterprise is entirely coincidental.

COPYRIGHT LICENSE:

This information contains sample application programs in source language, which illustrate programming techniques on various operating platforms. You may copy, modify, and distribute these sample programs in any form without payment to IBM, for the purposes of developing, using, marketing or distributing application programs conforming to the application programming interface for the operating platform for which the sample programs are written. These examples have not been thoroughly tested under all conditions. IBM, therefore, cannot guarantee or imply reliability, serviceability, or function of these programs. The sample programs are provided "AS IS", without warranty of any kind. IBM shall not be liable for any damages arising out of your use of the sample programs.

If you are viewing this information softcopy, the photographs and color illustrations may not appear.

Trademarks

IBM, the IBM logo, and ibm.com[®] are trademarks or registered trademarks of International Business Machines Corp., registered in many jurisdictions worldwide. Other product and service names might be trademarks of IBM or other companies. A current list of IBM trademarks is available on the web at Copyright and trademark information at www.ibm.com/legal/copytrade.shtml.

Adobe, the Adobe logo, PostScript, and the PostScript logo are either registered trademarks or trademarks of Adobe Systems Incorporated in the United States, and/or other countries.

Intel and Intel Xeon are trademarks or registered trademarks of Intel Corporation or its subsidiaries in the United States and other countries.

Linux and the Linux logo is a registered trademark of Linus Torvalds in the United States, other countries, or both.

Microsoft, Windows, and the Windows logo are trademarks of Microsoft Corporation in the United States, other countries, or both.

Other product and service names might be trademarks of IBM or other companies.

Electronic emission notices

This section contains the electronic emission notices or statements for the United States and other countries.

Federal Communications Commission (FCC) statement

This explains the Federal Communications Commission's (FCC's) statement.

This equipment has been tested and found to comply with the limits for a Class A digital device, pursuant to Part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference when the equipment is operated in a commercial environment. This equipment generates, uses, and can radiate radio frequency energy and, if not installed and used in accordance with the instruction manual, might cause harmful interference to radio communications. Operation of this equipment in a residential area is likely to cause harmful interference, in which case the user will be required to correct the interference at his own expense.

Properly shielded and grounded cables and connectors must be used in order to meet FCC emission limits. IBM is not responsible for any radio or television interference caused by using other than recommended cables and connectors, or by unauthorized changes or modifications to this equipment. Unauthorized changes or modifications could void the user's authority to operate the equipment.

This device complies with Part 15 of the FCC Rules. Operation is subject to the following two conditions: (1) this device might not cause harmful interference, and (2) this device must accept any interference received, including interference that might cause undesired operation.

Industry Canada compliance statement

This Class A digital apparatus complies with Canadian ICES-003.

Cet appareil numérique de la classe A est conform à la norme NMB-003 du Canada.

Australia and New Zealand Class A Statement

Attention: This is a Class A product. In a domestic environment this product might cause radio interference in which case the user might be required to take adequate measures.

European Union Electromagnetic Compatibility Directive

This product is in conformity with the protection requirements of European Union (EU) Council Directive 2004/108/EC on the approximation of the laws of the Member States relating to electromagnetic compatibility. IBM cannot accept responsibility for any failure to satisfy the protection requirements resulting from a non-recommended modification of the product, including the fitting of non-IBM option cards.

Attention: This is an EN 55022 Class A product. In a domestic environment this product might cause radio interference in which case the user might be required to take adequate measures.

Responsible Manufacturer:

International Business Machines Corp.
New Orchard Road
Armonk, New York 10504
914-499-1900

European community contact:

IBM Deutschland GmbH
Technical Regulations, Department M372
IBM-Allee 1, 71139 Ehningen, Germany
Tele: +49 7032 15-2941
Email: lugi@de.ibm.com

Germany Electromagnetic Compatibility Directive

Deutschsprachiger EU Hinweis: Hinweis für Geräte der Klasse A EU-Richtlinie zur Elektromagnetischen Verträglichkeit

Dieses Produkt entspricht den Schutzanforderungen der EU-Richtlinie 2004/108/EG zur Angleichung der Rechtsvorschriften über die elektromagnetische Verträglichkeit in den EU-Mitgliedsstaaten und hält die Grenzwerte der EN 55022 Klasse A ein.

Um dieses sicherzustellen, sind die Geräte wie in den Handbüchern beschrieben zu installieren und zu betreiben. Des Weiteren dürfen auch nur von der IBM empfohlene Kabel angeschlossen werden. IBM übernimmt keine Verantwortung für die Einhaltung der Schutzanforderungen, wenn das Produkt ohne Zustimmung der IBM verändert bzw. wenn Erweiterungskomponenten von Fremdherstellern ohne Empfehlung der IBM gesteckt/eingebaut werden.

EN 55022 Klasse A Geräte müssen mit folgendem Warnhinweis versehen werden:

“Warnung: Dieses ist eine Einrichtung der Klasse A. Diese Einrichtung kann im Wohnbereich Funk-Störungen verursachen; in diesem Fall kann vom Betreiber verlangt werden, angemessene Maßnahmen zu ergreifen und dafür aufzukommen.”

Deutschland: Einhaltung des Gesetzes über die elektromagnetische Verträglichkeit von Geräten

Dieses Produkt entspricht dem “Gesetz über die elektromagnetische Verträglichkeit von Geräten (EMVG).” Dies ist die Umsetzung der EU-Richtlinie 2004/108/EG in der Bundesrepublik Deutschland.

Zulassungsbescheinigung laut dem Deutschen Gesetz über die elektromagnetische Verträglichkeit von Geräten (EMVG) (bzw. der EMC EG Richtlinie 2004/108/EG) für Geräte der Klasse A

Dieses Gerät ist berechtigt, in Übereinstimmung mit dem Deutschen EMVG das EG-Konformitätszeichen - CE - zu führen.

Verantwortlich für die Einhaltung der EMV Vorschriften ist der Hersteller:

International Business Machines Corp.
New Orchard Road
Armonk, New York 10504
Tel: 914-499-1900

Der verantwortliche Ansprechpartner des Herstellers in der EU ist:

IBM Deutschland GmbH
Technical Regulations, Abteilung M372
IBM-Allee 1, 71139 Ehningen, Germany
Tele: +49 7032 15-2941
Email: lugi@de.ibm.com

Generelle Informationen:

Das Gerät erfüllt die Schutzanforderungen nach EN 55024 und EN 55022 Klasse A.

People's Republic of China Class A Statement

中华人民共和国“A类”警告声明

声明

此为A级产品，在生活环境中，该产品可能会造成无线电干扰。在这种情况下，可能需要用户对其干扰采取切实可行的措施。

Taiwan Class A compliance statement

警告使用者：
這是甲類的資訊產品，在居住的環境中使用時，可能會造成射頻干擾，在這種情況下，使用者會被要求採取某些適當的對策。

Taiwan Contact Information

This topic contains the product service contact information for Taiwan.

IBM Taiwan Product Service Contact Information:
IBM Taiwan Corporation
3F, No 7, Song Ren Rd., Taipei Taiwan
Tel: 0800-016-888

台灣IBM 產品服務聯絡方式：
台灣國際商業機器股份有限公司
台北市松仁路7號3樓
電話：0800-016-888

f2c00790

Japan VCCI Council Class A statement

This explains the Japan Voluntary Control Council for Interference (VCCI) statement.

この装置は、クラス A 情報技術装置です。この装置を家庭環境で使用すると電波妨害を引き起こすことがあります。この場合には使用者が適切な対策を講ずるよう要求されることがあります。

VCCI-A

Japan Electronics and Information Technology Industries Association Statement

This explains the Japan Electronics and Information Technology Industries Association (JEITA) statement for less than or equal to 20 A per phase.

高調波ガイドライン適合品

This explains the JEITA statement for greater than 20 A per phase.

高調波ガイドライン準用品

jeita2

Korean Communications Commission Class A Statement

This explains the Korean Communications Commission (KCC) statement.

이 기기는 업무용(A급)으로 전자파적합기기로
서 판매자 또는 사용자는 이 점을 주의하시기
바라며, 가정외의 지역에서 사용하는 것을 목
적으로 합니다.

Russia Electromagnetic Interference Class A Statement

This statement explains the Russia Electromagnetic Interference (EMI) statement.

ВНИМАНИЕ! Настоящее изделие относится к классу А.
В жилых помещениях оно может создавать радиопомехи, для
снижения которых необходимы дополнительные меры



Printed in USA

GA32-1057-10

